Homological stability for configuration spaces of disconnected submanifolds

Martin Palmer // Lausanne, 8<sup>th</sup> July 2013

Slides also on webpage: zatibq.com

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- Computationally useful, if you know (a) the stable range f and (b) the stable homology H<sub>\*</sub>(X<sub>∞</sub>) = H<sub>\*</sub>(telescope(··· → X<sub>n</sub> → X<sub>n+1</sub> → ···)).

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- Usually (b) is done by finding a more 'tractable' space Y and a homology equivalence X<sub>∞</sub> → Y. This requires different techniques to proving homological stability; we will focus on homological stability in this talk.
- There are many examples of this phenomenon from different areas:
  - classical groups
  - mapping class groups
  - automorphism groups of free groups
  - configuration spaces
  - ...

More detailed examples on the next slide...

### A selection of homological stability results (from many more)

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| $X_n^*$  |   | f(n)      |                            | Y   |                |
|--|---|-----------|----------------------------|---|----------------|
| $\Sigma_n$   | symmetric groups                                | n/2       | [Nakaoka]                  | $\Omega_0^\infty S^\infty$                    | [BPQ]          |
| $B_n$  | braid groups                                    | n/2       | [Arnol'd]                  | $\Omega_0^2 S^2 \simeq \Omega^2 S^3$          | [Segal]        |
| $C_n(\mathbb{R}^d)$  | config. spaces on $\mathbb{R}^d$                | n/2       | [Segal]                    | $\Omega_0^d S^d$                              | [Segal]        |
| $C_n(M)$   | (M  conn. and open)                             | n/2       | [McDuff,Segal]             | $\Gamma_0(\dot{T}M)$                          | [McDuff]       |
| $GL_n(R)$  | (R  Dedekind domain)                            | (n-1)/4   | [Charney]                  | $K(GL(R),1)^+ \sim$                           | → K-theory     |
| $Sp_{2n}(R)$   | (R  Dedekind domain)                            | (n-6)/2   | [Charney]                  | K(Sp(R),1)                                    |                |
| $O_n(\mathbb{F})$  | $(\mathbb{F}=\mathbb{R},\mathbb{C},\mathbb{H})$ | n-1       | [Sah]                      | $K(O(\mathbb{F}), 1)$                         |                |
| Many other families of classical groups  |   |           |                            |   |                |
| $\operatorname{Aut}(F_n)$  | $(F_n = \text{free group})$                     | (n-2)/2   | [Hatcher-Vogtmann]         | $\Omega_0^\infty S^\infty$                    | [Galatius]     |
| $\operatorname{Out}(F_n)$  |   | (n-4)/2   | [Hatcher-Vogtmann]         |   |                |
| MCGs of oriented surfaces  |   | $^{2g/3}$ | [Harer, Ivanov, Boldsen]   | $\Omega_0^\infty MTSO(2)$                     | [Madsen-Weiss] |
| MCGs of nonorientable surfaces   |   | (g-3)/3   | [Wahl,Randal-Williams]     | $\Omega_0^\infty MTO(2)$                      | [Wahl]         |
| MCGs of 3-dim handlebodies   |   | (g-2)/2   | $[Hatcher-Wahl]^{\dagger}$ | $\Omega_0^{\infty} \Sigma^{\infty} BSO(3)_+$  | [Hatcher]      |
| $B Diff_{\partial} \text{ of } \sharp_g(S^1 \times S^2) \smallsetminus \mathring{D}^3$   |   |           |                            | $\Omega_0^\infty \Sigma^\infty BSO(4)_+$      | [Hatcher]      |
| $BDiff_\partial$ of $\sharp_g(S^n \times S^n) \smallsetminus \mathring{D}^{2n \ddagger}$ |   | (g-4)/2   | [Galatius-Randal-Williams] | $\Omega_0^\infty MTO(2n)^{\langle n \rangle}$ | [GRW]          |

\*  $X_n \coloneqq K(G_n, 1)$  if the entry is a group  $G_n$ .

Notation: we use K(G, 1) when G is a discrete group, and BG when it is a (non-discrete) topological group.

 $^\dagger$  More generally: MCGs of (compact connected) oriented 3-manifolds.

<sup>‡</sup> For  $n \ge 3$ .

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$$C_n(\mathbb{R}^2) \xrightarrow{} C_{n.S^1}(\mathbb{R}^3)$$

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$$\pi_{1} = \Sigma \operatorname{Aut}(F_{n}) = \operatorname{MCG}\left( \underbrace{\swarrow}_{:} \underbrace{\bigcirc}_{:} \right) / \operatorname{twists}$$

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Choose:

 $\begin{array}{ll} M \mbox{ connected, non-compact, = interior}(\overline{M}) & P \mbox{ and } Q \mbox{ closed (same dim.)} \\ \mbox{An embedding } q \colon Q \hookrightarrow M \mbox{ and an embedding "at infinity" } p \colon P \hookrightarrow \partial \overline{M} \end{array}$ 

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So homological stability is certainly true when  $M = \mathbb{R}^{\infty}$  (at least when  $Q = \emptyset$ ).

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As long as  $\dim(P) \leq \frac{1}{2}(\dim(M) - 3)$ , the map  $C_q(M) \to C_{q+p}(M)$  is an isomorphism on  $H_*(-;\mathbb{Z})$  in the stable range  $* \leq n/2$ .

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As long as  $\dim(P) \leq \frac{1}{2}(\dim(M) - 3)$ , the map  $C_q(M) \to C_{q+p}(M)$  is an isomorphism on  $H_*(-;\mathbb{Z})$  in the stable range  $* \leq n/2$ . Here, n is the number of components  $q_0$  of q which are isotopic to p and unlinked from  $q \smallsetminus q_0$ . Equivalently:

$$n \coloneqq \max\left\{m \in \mathbb{N} \mid q = q' + m.p \text{ for some } q'\right\}$$

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- Improvement (in progress): Remove the codimension condition altogether... This would then include the case  $C_{n.S^1}(\mathbb{R}^3)$ .

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- Then  $H_*(\mathcal{E}_g(M);\mathbb{Z}) \cong H_*(\mathcal{E}_{g+1}(M);\mathbb{Z})$  in the stable range  $* \leqslant (2g-2)/3$ .

## Thanks for listening $\ensuremath{\textcircled{\sc 0}}$

