## Homological stability for partitioned braid groups on surfaces

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## Abstract:

Braid groups were first introduced, implicitly, by Hurewicz, as the fundamental groups of configuration spaces of points in the plane (or, equivalently, the disc):

$$B_n = \pi_1(C_n(D^2)).$$

Using this viewpoint, one may generalise this to define the surface braid groups  $B_n(S) = \pi_1(C_n(S))$ for any surface S. The topic of this talk will be the partitioned braid groups of a surface S, which are most easily defined using a slight modification of this viewpoint. Suppose that n = tm, and we have chosen a basepoint for  $C_n(S)$  in which the n points are partitioned into t teams with m members each. The partitioned braid group

$$B_{m|t}(S) \leqslant B_n(S)$$

is the subgroup of all braids that respect this partition into teams (team members must end up together, although entire teams may swap positions). More formally,  $B_{m|t}(S)$  is the preimage of a certain subgroup  $(\Sigma_m)^t \rtimes \Sigma_t$  of  $\Sigma_n$  under the canonical projection  $B_n(S) \to \Sigma_n$ . It may also be interpreted as the fundamental group of a certain  $\frac{n!}{t!(m!)^t}$ -sheeted covering space of  $C_n(S)$ .

In the 1970s, V. I. Arnol'd, D. McDuff and G. Segal showed that, for any connected surface S with non-empty boundary, the surface braid groups  $B_n(S)$  are *homologically stable*: their homology in any particular degree is independent of the number of strands n once n is large enough. The purpose of this talk is to present the proof of a generalisation of this result: for any fixed m and fixed homological degree i, the homology  $H_i(B_{m|t}(S))$  is independent of the number of teams t once t is large enough.

As with many homological stability results, the main geometric input for the proof is the high-connectivity of certain simplicial complexes. I will first explain how one uses this input for the inductive proof of homological stability, and then sketch the proof of the high-connectivity of these simplicial complexes, using techniques discussed in a previous talk at GeMAT in July 2018 (but I will recall everything that we will need from that talk).

This talk represents joint work with TriThang Tran at the University of Melbourne.

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