

The 3D index and Dehn surgery

joint work with C. Hodgson and H. Rubinstein

Moduli & Friends seminar

Daniele Celoria

Overview

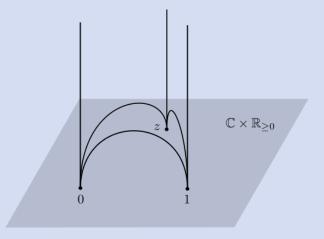
Idea: rigorous proof of a Dehn surgery formula for the 3D index.

- hyperbolic geometry in dimension 3
- the DGG 3D index
- Dehn surgery
- the proof
- applications & open questions

Introduction

In what follows, M = compact, connected, orientable 3-manifold with $\partial M = c$ tori (e.g. link complement).

 \boldsymbol{M} can be described via an ideal triangulation:



Thurston's Gluing equations Edge equations (how tetrahedra fit together)

$$\sum_{i=1}^{n} \log(z_i) = 2\pi i$$

Completeness equations (holonomy)

$$\forall \sigma \subset \partial M \ \sum_i \epsilon_i \log(z_i) = 0$$

Can be read off SnapPy's gluing_equations() command.

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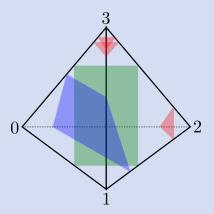
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Pachner moves

Normal surfaces

Surfaces intersecting each tetrahedron in a 'straight' disk.



Can be described as $\mathbb N\text{-solutions}$ of a linear system in $(\mathbb R^{3+4})^n.$

$3\mathsf{D}\xspace$ index

The **3D-index** is an 'invariant' of cusped 3-manifolds introduced by the physicists Dimofte-Gaiotto-Gukov in 2011, which contains much information about the topology/geometry of the manifold.

$$M \rightsquigarrow \mathcal{T}_M + \text{`boundary data'} \ \gamma \rightsquigarrow I_{\mathcal{T}_M}^{\gamma}(q) \in \mathbb{Z}\llbracket q^{\frac{1}{2}} \rrbracket$$

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Encodes and detects many geometric/topological properties of M:

- hyperbolicity
- is a "generating function" over normal surfaces
- coefficients related to the topology of ${\cal M}$
- connections with \hat{A} polynomials

Definition

The tetrahedral index $I_\Delta \colon \mathbb{Z}^2 \to \mathbb{Z}\llbracket q^{\frac{1}{2}} \rrbracket$ is defined by

$$I_{\Delta}(m,e)(q) = \sum_{n=\max\{0,-e\}}^{\infty} (-1)^n \frac{q^{\frac{1}{2}n(n+1)-(n+\frac{1}{2}e)m}}{(q;q)_n(q;q)_{n+e}} \quad \text{for}$$

where
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 is a *q*-Pochhammer symbol.

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A more symmetric version is given by

$$J_{\Delta}(a,b,c) = (-\sqrt{q})^{-b} I_{\Delta}(b-c,a-b) \text{ for } a,b,c \in \mathbb{Z},$$

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Remark

$$I_{\Delta}(m,e) = \frac{q^{-\frac{me}{2}}(q^{e+1};q)_{\infty}}{(q;q)_{\infty}} {}_{1}\phi_{1} \begin{bmatrix} 0\\ q^{e+1};q,q^{1-m} \end{bmatrix}$$

(In this form it is a specialised Hahn-Exton *q*-Bessel function)

q-hypergeometric series

Definition For 0 < q < 1, define

$${}_{r}\phi_{s}\begin{bmatrix}a_{1}&\dots&a_{r}\\b_{1}&\dots&b_{s}\end{bmatrix} = \sum_{n=0}^{\infty}\frac{(a_{1},\dots,a_{r};q)_{n}}{(b_{1},\dots,b_{s},q;q)_{n}}\left((-1)^{n}q^{\binom{n}{2}}\right)^{1+s-r}z^{n}$$

where

$$(a;q)_n = \prod_{i=0}^{n-1} (1 - aq^i) \text{ and } (a_1, \dots, a_m;q)_n = \prod_{i=1}^m (a_i;q)_n.$$

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Example:

$$e_q(z) = \sum_{n \ge 0} \frac{z^n}{(q;q)_n} = {}_1\phi_0 \begin{bmatrix} 0 \\ -; q, z \end{bmatrix} = \frac{1}{(z;q)_\infty} \text{ then } \lim_{q \to 1^-} e_q(z) = e^z$$

Some useful identities

- symmetry $I_{\Delta}(m,e) = I_{\Delta}(-e,-m)$
- 3 term relations

$$q^{\frac{e}{2}}I_{\Delta}(m+1,e) + q^{-\frac{m}{2}}I_{\Delta}(m,e+1) - I_{\Delta}(m,e) = 0$$

$$q^{\frac{e}{2}}I_{\Delta}(m-1,e) + q^{-\frac{m}{2}}I_{\Delta}(m,e-1) - I_{\Delta}(m,e) = 0$$
(1)

• quadratic identity

$$\sum_{e \in \mathbb{Z}} I_{\Delta}(m, e) I_{\Delta}(m, e+c) q^e = \delta_{c,0},$$

• pentagon identity

$$\sum_{e \in \mathbb{Z}} q^e I_{\Delta}(m_1, e + x_1) I_{\Delta}(m_2, e + x_2) I_{\Delta}(m_1 + m_2, e + x_3) = q^{-x_3} I_{\Delta}(m_1 - x_2 + x_3, x_1 - x_3) I_{\Delta}(m_2 - x_1 + x_3, x_2 - x_3).$$

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Definition

$$I_{\mathcal{T}}^{0}(q) = \sum_{\substack{k:\mathcal{E}\to\mathbb{Z},\\k\mid_{\mathcal{E}'}=0}} q^{k(\mathcal{E})} \prod_{j=1}^{n} J_{\Delta}(q_j(k))$$

where $k(\mathcal{E})=\sum_{e\in\mathcal{E}}k(e)$ and \mathcal{E}' is a suitable choice of r edges. (For r=1 any edge is suitable.)

$$I_{\mathcal{T}}^{\gamma}(q) = \sum_{\substack{k:\mathcal{E}\to\mathbb{Z},\\k|_{\mathcal{E}'}=0}} q^{k(\mathcal{E})} \prod_{j=1}^{n} J_{\Delta}(q_j(k) + \gamma_j)$$

where $\gamma_j = (a_j(\gamma), b_j(\gamma), c_j(\gamma)) \in \mathbb{Z}^3$ depends on $\gamma \in H_1(\partial M; \mathbb{Z})$.

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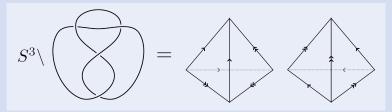
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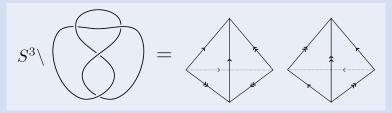
 Physics predicts that I_T should be a topological invariant of M. However, it is not defined for all triangulations T?

Example: complement of 4_1



edge/curve	weight	a_1	b_1	c_1	a_2	b_2	c_2
e_1	k	2	1	0	2	1	0
e_2	0	0	1	2	0	1	2
2μ	x	0	0	1	-1	0	0
2λ	$\frac{1}{2}y$	0	0	0	2	0	-2

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Hence, for $x, y \in \mathbb{Z}$,

$$I_{\mathcal{T}}^{(x,y)}(q) = \sum_{k \in \mathbb{Z}} q^k J_{\Delta}(2k,k,x) J_{\Delta}(2k-x+y,k,-y)$$
$$= \sum_{k \in \mathbb{Z}} I_{\Delta}(k-x,k) I_{\Delta}(k+y,k-x+y).$$

[S. Garoufalidis, C. Hodgson, N. Hoffmann, J.H. Rubinstein, H. Segerman]

I^γ_T(q) is well-defined (for all γ) iff T is 1-efficient (i.e. no embedded normal spheres and tori except peripheral tori.)

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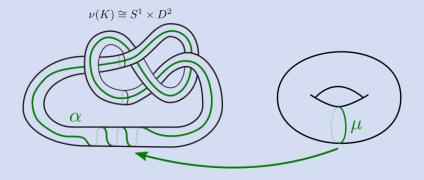
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- $I^{\gamma}_{\mathcal{T}}(q)$ is invariant under 2-3 moves, 0-2 moves *if all triangulations are 1-efficient*.
- If M is hyperbolic we get a topological invariant $I^{\gamma}_{M}(q).$
- Can write $I_T^{\gamma}(q)$ as a sum over singular Q-normal surfaces in T with boundary γ .

Dehn surgery



3D-index and Dehn filling

In 2018, the physicists D. Gang and K. Yonekura proposed a formula giving the 3D-index for Dehn fillings on a cusped 3-manifold M.

The Gang-Yonekura formula gives the 3D-index for $M(\alpha)$ as an infinite linear combination of the 3D-indices $I_M^{\gamma}(q)$ for M over boundary classes γ having intersection number 0 or ± 2 with α .

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If
$$K = \ker(H_1(T;\mathbb{Z}) \to H_1(M;\mathbb{Z}_2))$$
, $|\gamma| = \#$ components of γ :

$$I_{M(\alpha)}(q) = \frac{1}{2} \left(\sum_{\substack{\gamma \in K \\ \gamma \cdot \alpha = 0}} (-1)^{|\gamma|} (q^{\frac{|\gamma|}{2}} + q^{-\frac{|\gamma|}{2}}) I_M^{\gamma}(q) - \sum_{\substack{\gamma \in K \\ \gamma \cdot \alpha = \pm 2}} I_M^{\gamma}(q) \right)$$

Main result

We wanted to show that this formula holds for Dehn fillings on some (but not all!) cusps of a multi-cusped manifold.

Theorem [CHR]

Let M be a compact orientable 3-manifold with boundary consisting of at least 2 tori, and let T be one component of ∂M . Let \mathcal{T}_M be a 1-efficient triangulation with a standard cusp at T.

Given a surgery curve $\alpha \subset T$, let $\mathcal{T}(\alpha)$ be the ideal triangulation of $M(\alpha)$ obtained from \mathcal{T} by replacing the standard cusp by the *layered solid torus* with α bounding a meridian disc. Then the Gang-Yonekura formula holds for the triangulations \mathcal{T} and $\mathcal{T}(\alpha)$ for all α with at most 3 exceptions.

Corollary [CHR]

Let M be a cusped hyperbolic 3-manifold with at least two cusps, and assume that one cusp T has a *generic shape*, i.e. the corresponding Euclidean torus is not rectangular. Then the Gang-Yonekura formula holds for almost all Dehn fillings $M(\alpha)$.

Corollary [CHR]

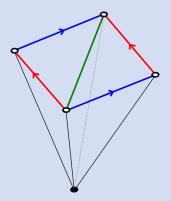
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Proof: By first expanding the cusp at T until it bumps into itself, then expanding the other cusps, we obtain a canonical (Epstein-Penner) ideal triangulation \mathcal{T} with a standard cusp at T. Then work of Guéritaud-Schleimer shows that for almost all α , the corresponding canonical triangulation of $M(\alpha)$ is isomorphic to the triangulation $\mathcal{T}(\alpha)$.

So we obtain $I_M = I_T$ and $I_{M(\alpha)} = I_{T(\alpha)}$.

Explanation of the theorem

A standard cusp has a triangulation by two ideal tetrahedra:

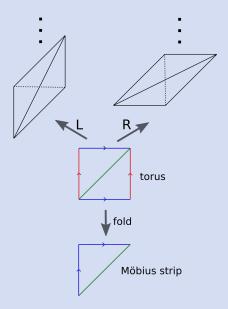


Theorem [Howie-Mathews-Purcell] (paraphrased)

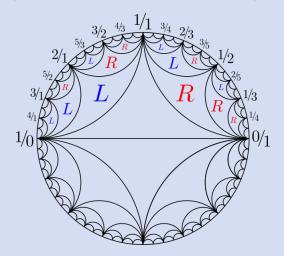
If there's more than one cusp, there exists a triangulation where all but one cusps are standard.

Layered solid tori

- start with two triangles giving a torus,
- add layers of tetrahedra on top to get a triangulation of $T^2 \times [0,1], \label{eq:triangle}$
- "fold up" the bottom torus $T^2 \times 0$ onto a Möbius strip.
- This gives a solid torus (which is a neighbourhood of the Möbius strip).

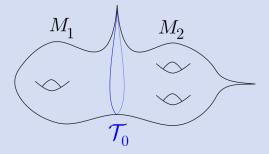


Layered triangulations of the solid torus are parameterised by finite words in the alphabet $\{L, R\}$ giving triangles in the Farey tessellation (related to continued fraction expansion).



Gluing formulas and relative index

Let \mathcal{T} be an ideal triangulation of M and \mathcal{T}_0 be a union of triangles in \mathcal{T} splitting \mathcal{T} into triangulations $\mathcal{T}_1, \mathcal{T}_2$ of submanifolds M_1, M_2 respectively.



Let \mathcal{E} be the set of all edges of \mathcal{T} ,

 \mathcal{E}' a collection of r edges "omitted" in computing the index of \mathcal{T} , \mathcal{E}_i the set of edges in \mathcal{T}_i , and $\mathcal{E}'_i = \mathcal{E}_i \cap \mathcal{E}'$.

Relative index

For any prescribed $\gamma \in K \subset H_1(\partial M; \mathbb{Z})$ and "boundary weights" $b_0: \mathcal{E}_0 \to \mathbb{Z}$ with $b_0|_{\mathcal{E}'_0} = 0$ we define *relative indices* for i = 1, 2 by

$$I_{\mathcal{T}_{i}}^{\gamma}(q;b_{0}) = \sum_{\substack{k:\mathcal{E}_{i} \to \mathbb{Z}, \\ k|_{\mathcal{E}_{i}}=0, \\ k|_{\mathcal{E}_{0}}=b_{0}}} q^{k(\mathcal{E}_{i} \setminus \mathcal{E}_{0})} \prod_{j=1}^{n} J_{\Delta}(q_{j}(k) + \gamma_{j})$$

where $k(\mathcal{E}_i \setminus \mathcal{E}_0) = \sum_{e \in \mathcal{E}_i \setminus \mathcal{E}_0} k(e)$.

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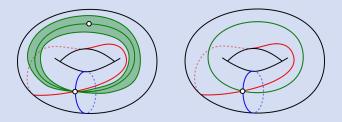
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Gluing formula

$$I_{\mathcal{T}}^{\gamma}(q) = \sum_{\substack{b_0:\mathcal{E}_0 \to \mathbb{Z}, \\ b_0|\mathcal{E}_0'=0}} q^{b_0(\mathcal{E}_0)} I_{\mathcal{T}_1}^{\gamma}(q;b_0) I_{\mathcal{T}_2}^{\gamma}(q;b_0)$$

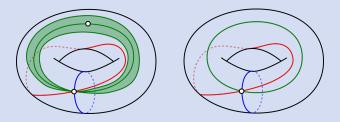
where $b_0(\mathcal{E}_0) = \sum_{e \in \mathcal{E}_0} b_0(e)$.

Local version



By the gluing formula, it suffices to show: relative index of a layered solid torus = Gang-Yonekura formula applied to the relative index of a standard cusp.

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By the gluing formula, it suffices to show:

relative index of a layered solid torus = Gang-Yonekura formula applied to the relative index of a standard cusp.

Proof of this local version:

- Use induction on the number of tetrahedra in the solid torus.
- Inductive step is proved using the pentagon identity.

• The base case (much harder for us!) needs some new algebraic identities.

Base case: LST(1, 1, 2)

Theorem [CHR]

For every $b = (b_1, b_2) \in \mathbb{Z}^2$,

$$\frac{1}{2}\sum_{k\in\mathbb{Z}}(q^k+q^{-k})G_b(k,k) - G_b(k,k+1) - G_b(k,k-1) = q^{-b_1}\delta_{b_1,b_2}$$

where $G_b(e,m) = I_{\Delta}(e - b_1, m + b_2)I_{\Delta}(-e - b_1, -m + b_2).$

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where
$$G_b(e,m) = I_{\Delta}(e - b_1, m + b_2)I_{\Delta}(-e - b_1, -m + b_2).$$

Sketch of Proof: First introduce the "diagonal" generating functions:

$$arphi_r(z,q) = \sum_{e \in \mathbb{Z}} I_\Delta(e-r,e) z^e, ext{ where } r \in \mathbb{Z}.$$

Then the LHS in the theorem is the coefficient of \boldsymbol{z}^0 in

$$z^{-2b_2}\left(\varphi_r(zq^{\frac{1}{2}},q)\varphi_r(zq^{-\frac{1}{2}},q)-\varphi_{r+1}(z,q)\varphi_{r-1}(z,q)\right),$$

where $r = b_1 + b_2$.

A meromorphic approach

To study $\varphi_r(z,q)$, we begin with Garoufalidis-Kashaev's meromorphic 3D index:

Definition

$$\psi^{0}(z,w,q) = c(q) \frac{(z^{-1};q)_{\infty}}{(-qz;q)_{\infty}} \frac{(-qw;q)_{\infty}}{(w^{-1};q)_{\infty}} \frac{(-qzw^{-1};q)_{\infty}}{(wz^{-1};q)_{\infty}}$$

where $c(q) = \frac{(q;q)_{\infty}^2}{(q^2;q^2)_{\infty}}$.

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where $c(q) = \frac{(q;q)_{\infty}^2}{(q^2;q^2)_{\infty}}$.

Theorem [Garoufalidis-Kashaev]

$$\psi^0(z, w, q) = \sum_{e, m \in \mathbb{Z}} (-q)^e I_\Delta(m, e)(q^2) z^e w^m$$

We then extract the "diagonal series" $\varphi_r(z,q)$ as a complex line integral, and use Cauchy's residue theorem to express this as an infinite sum of residues:

$$\varphi_r(z,q) = \sum_{e \in \mathbb{Z}} (-q)^e I_\Delta(e-r,e)(q^2) x^{e-r} = \frac{1}{2\pi i} \int_{|s|=\rho} \psi^0\left(s,\frac{x}{s}\right) \frac{\mathrm{d}s}{s^{r+1}}$$

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Theorem [CHR] $\varphi_{r}(z,q) = \begin{cases} (-zq^{-\frac{1}{2}})^{\frac{r}{2}} {}_{3}\phi_{3} \begin{bmatrix} -z^{-1}\sqrt{q} & -z\sqrt{q} & 0 \\ -q & \sqrt{q} & -\sqrt{q}; q, q^{1-\frac{r}{2}} \end{bmatrix} & r \text{ even} \\ \\ (-z)^{\frac{r-1}{2}} q^{\frac{1-r}{2}} \frac{(1+z)}{1-q} {}_{3}\phi_{3} \begin{bmatrix} -z^{-1}q & -zq & 0 \\ -q & q^{\frac{3}{2}} & -q^{\frac{3}{2}}; q, q^{\frac{3-r}{2}} \end{bmatrix} & r \text{ odd.} \end{cases}$ After further manipulations we can apply a *q*-analogue of the *Pythagoras theorem* proved by F. Štampach to obtain:

Proposition [CHR] For $r \in \mathbb{Z}$ and $z, q \in \mathbb{C}, |q| < 1$ $\varphi_r(zq^{\frac{1}{2}}, q)\varphi_r(zq^{-\frac{1}{2}}, q) - \varphi_{r+1}(z, q)\varphi_{r-1}(z, q) \equiv z^r q^{-\frac{1}{2}r}$ After further manipulations we can apply a *q*-analogue of the *Pythagoras theorem* proved by F. Štampach to obtain:

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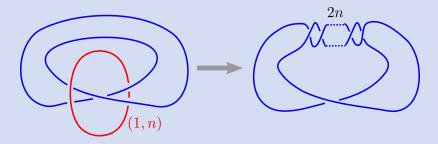
Corollary If $r \in \mathbb{Z}$ is even, then:

$$\sum_{e \in \mathbb{Z}} (-\sqrt{q})^e I_{\Delta}(e-r,e) = 1$$

If $r \in \mathbb{Z}$ is odd, then:

$$\sum_{e \in \mathbb{Z}} (-q)^e I_{\Delta}(e-r,e) = 1$$

Example: 3D-index for alternating torus knots



Using some of our identities for the tetrahedral index and applying the Gang-Yonekura formula we can show

$$I_{T(2n-1,2)}^{(x,y)}(q) = \begin{cases} 1 & \text{ if } (x,y) \text{ is a multiple of } (-2(2n-1),1) \\ 0 & \text{ otherwise} \end{cases}$$

Asymptotic stability formula

Let α, β be homology classes of dual simple closed curves on $T \subset \partial M$ with $\alpha \notin K, \beta \in K$, (e.g. $\alpha = \mu, \beta = \lambda$).

Theorem [CHR] Let $\alpha_n = \alpha + n\beta$ for $n \in \mathbb{Z}$. Then: $\lim_{n \to \infty} I_{M(\alpha_n)}(q) \to I_M^0(q) - I_M^{2\beta}(q).$

Crucially, the result depends on the 'direction' we choose, unlike in Thurston's hyperbolic filling theorem!

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Surgeries on the Whitehead link $\frac{1}{n} 1 - 4q + q^2 + 16q^3 + 22q^4 + q^5 - 72q^6 - 158q^7 + \dots$ $n 1 - q - q^2 + 4q^3 + 6q^4 + 5q^5 - 11q^6 - 32q^7 + \dots$

Closed manifolds?

The index is not defined for closed manifolds. Using Gang-Yonekura's formula, we can try to force a definition!

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