

Reidemeister moves for triple-crossing link diagrams

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Joint work with

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Knots and representation theory

Seminar

Moscow

Plan

- Reidemeister moves for classical (2-)diagrams
- n -diagrams ($n \geq 2$)
- Main Theorem : analogue of Reidemeister moves for 3-diagrams
- sketch proof of completeness of the moves

Classical knot/link diagrams

- immersed 1-manifold in \mathbb{R}^2 (closed)
- embedded except at finitely many double-points, where 2 strands intersect transversely : 
- plus "over-under" information at each double-point : 

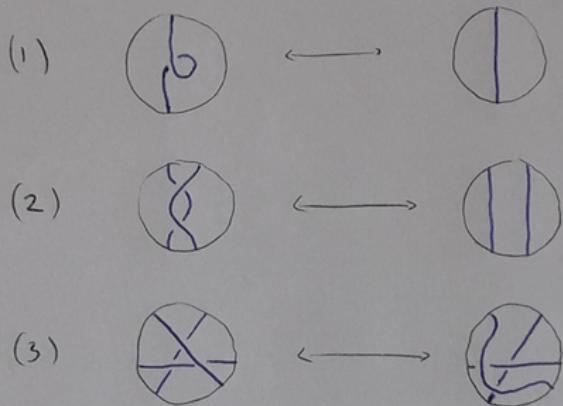
Every link has such a diagram :

- project $\mathbb{R}^3 \rightarrow \mathbb{R}^2$
- perturb  immersion
self-intersections are transverse

Theorem (Alexander-Briggs, Reidemeister 1927)

If two diagrams represent the same link, then they differ by :

- ambient isotopy in \mathbb{R}^2
- the 3 Reidemeister moves



Extremely useful:

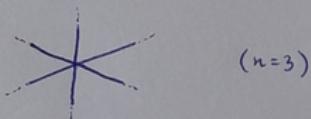
invariant of (isotopy classes of) diagrams
+ invariant under (1), (2), (3)

\Rightarrow invariant of links in \mathbb{R}^3

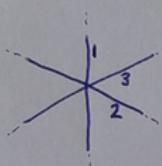
Our main theorem is an analogue of Reidemeister moves for "3-diagrams".....

n-diagrams ($n \geq 2$)

- immersed 1-manifold in \mathbb{R}^2 (closed)
- embedded except at finitely many n-tuple points, where n strands intersect transversely:

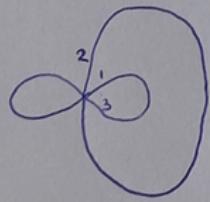


- plus "over-under" information:



Introduced by Colin Adams in 2013.

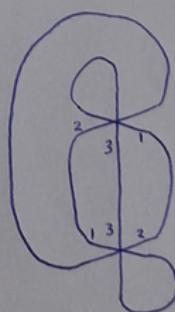
Examples



Hopf link



unlink



trefoil

Proposition (Adams 2013)

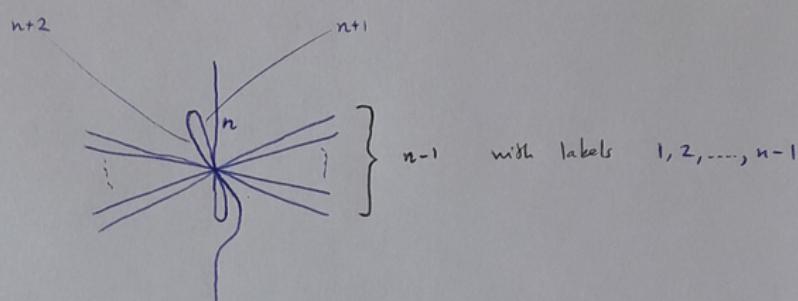
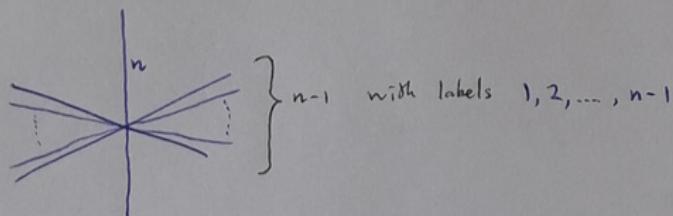
(3)

Every link in \mathbb{R}^3 has an n -crossing diagram (n-diagram) for all $n \geq 2$.

proof: (induction)

$n=2 : \checkmark$

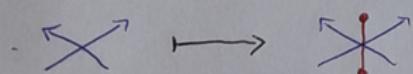
$n \mapsto n+2 :$



$n=3 :$ Fact : Every 2-diagram admits a ccc (crossing circle cover)

proof

choose orientation of the 2-diagram



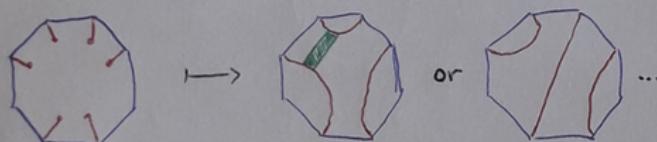
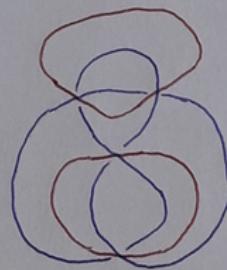
note that each complementary region contains an even number of

connect these in pairs by disjoint arcs (non-unique)

Def. ↗ disjoint union of embedded circles $\subseteq \mathbb{R}^2$
intersect the diagram only at crossing points

each crossing point of the diagram intersects the CCC

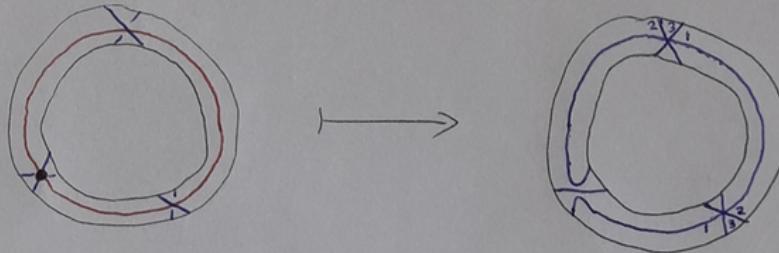
Examples



To turn a 2-diagram into a 3-diagram:

- choose a CCC + basepoint of each CC

- modify the 2-diagram as follows:



□.

Side note on n-crossing numbers

$$c_n(L) := \min \left\{ \# \text{ of crossings of } D \mid D \text{ is an } n\text{-diagram of } L \right\}$$

The proof above implies:

$$c_3(L) < c_2(L) \quad [L \text{ not an unlink}]$$

$$c_{n+2}(L) \leq c_n(L)$$

Other known facts:

$$\begin{aligned} c_4(L) &< c_2(L) & [L \text{ not an unlink}] \\ c_{kn}(L) &\leq c_n(L) & (k \text{ integer } \geq 2) \\ c_5(L) &< c_3(L) & [L \text{ non-split,} \\ && L \neq \text{unknot,} \\ && L \neq \text{Hopf}] \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \quad \begin{array}{l} [\text{Adams et al.}] \\ \\ [\text{Adams - Hoste - P.}] \end{array}$$

Open question:

$$c_{n+1}(L) \leq c_n(L) \quad \text{for all } n?$$

Relations to other invariants :

[5]

- Hyperbolic volume of hyperbolic links L :

$$\text{hypvol}(L) \leq 4 \cdot \underbrace{v_{\text{tetra}}}_{1.0149\dots} + (2c_3(L) - 4) \cdot \underbrace{v_{\text{octa}}}_{3.6638\dots}$$

[Adams, 2013]

Often better than the upper bound in terms of $c_2(L)$

$$\text{hypvol}(L) \leq 4 \cdot v_{\text{tetra}} + (c_2(L) - 5) \cdot v_{\text{octa}} \quad (\text{if } c_2(L) \geq 5)$$

- Span of the Kauffman bracket polynomial $\langle L \rangle$:

$$\text{span} \langle L \rangle \leq \left(\left\lfloor \frac{n^2}{2} \right\rfloor + 4n - 8 \right) \cdot c_n(L)$$

for $n \geq 3$

[Adams,
Capovilla-Searle,
Freeman,
Irvine,
Petti,
Vitek,
Weber,
Zhang 2014]

Classically we have:

$$\text{span} \langle L \rangle \leq 4 \cdot c_2(L) \quad [\text{Kauffman; Murasugi; Thistlethwaite 1987}]$$

- Genus :

$$g(L) \leq \frac{1}{2} (c_3(L) - \# \text{ components of } L + 1)$$

[Jabłonowski 2020]

$$\text{Classically : } g(L) \leq \frac{1}{2} (c_2(L) - \# \text{ components of } L + 1)$$

More generally : for $n \geq 3$ odd,

$$g(L) \leq \frac{1}{2} \left(\frac{(n-1)^2}{4} c_n(L) - \# \text{ components of } L + 1 \right)$$

Coming back to Reidemeister moves....

16

By the proposition above, we know that ($\forall n \geq 2$)

$$\{n\text{-diagrams}\} /_{\text{isotopy}} \longrightarrow \{\text{links}\} /_{\text{isotopy}}$$

is surjective.

Q: What is its "kernel"?

Can it be described by finitely many local moves?

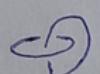
($n=2$) Reidemeister moves

($n=3$) ... in 5 minutes — first, a subtlety about orientations.

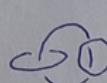
Relative orientations of links

any link $L \longrightarrow$ partition into maximal non-split sublinks

Ex.: K knot $\longrightarrow \{K\}$

 $\longrightarrow \{\text{---}\}$

$0\ 0 \longrightarrow \{0, 0\}$

 $\longrightarrow \{\text{---}, \text{---}\}$

Def.: A relative orientation of L is an orientation of each component of L , modulo orientation reversal of each maximal non-split sublink (independently).

of rel. orientations

Ex.: K knot 1

 2

 2

$0\ 0\ 0$ 1

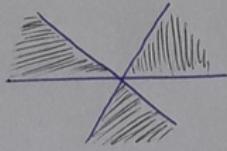
Lemma: For n odd, each n -crossing diagram D of L

determines an orientation of L

(& hence a relative orientation)

proof: Choose a chessboard colouring of D

→ locally:

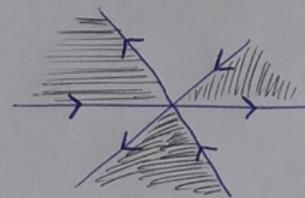


($n=3$)

To resolve ambiguity, say that the unbounded region should be white.

Orient each strand of D so that it points anticlockwise around each black region.

This is compatible since n is odd:



□.

Lemma: For n odd,

$$\{n\text{-diagrams}\}_{\text{iso}} \xrightarrow{\quad} \{\text{oriented links}\}_{\text{iso}}$$

is surjective.

proof ————— slight refinement of
the proof earlier.

$$\downarrow \quad \{ \text{rel. oriented links} \}_{\text{iso}}$$

Theorem (Adams - Hoste - P. 2019)

∃ five moves on 3-diagrams such that:

$$\begin{array}{ccc} \{3\text{-diagrams}\}_{\text{iso}} & \xrightarrow{\quad} & \{ \text{rel. oriented links} \}_{\text{iso}} \\ \downarrow & & \nearrow \text{bijection} \\ \{3\text{-diagrams}\}_{\text{iso}} & & \end{array}$$

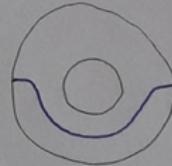
& five moves

- i.e.
- (A) each of the moves preserves the represented (link + rel. or.)
 - (B) if two 3-diagrams represent the same (link + rel. or.), then they differ by isotopy + a finite sequence of these moves.

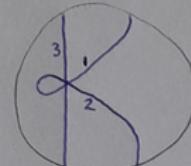
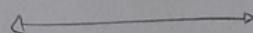
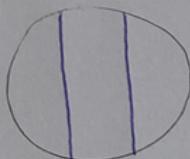
The moves :

L8

(0)



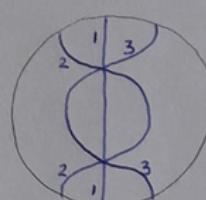
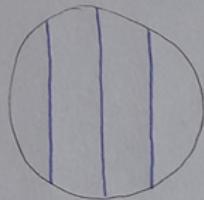
(1)



or

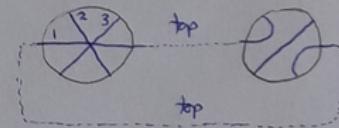
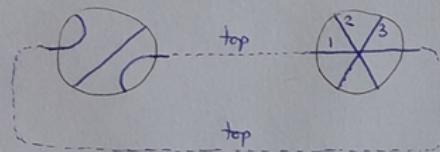


(2)

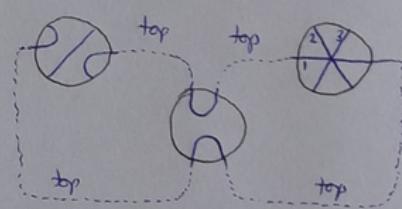
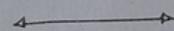
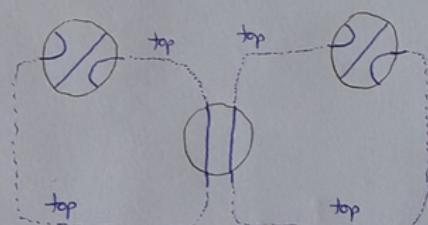


(Bp)

"basepoint"



(Band)



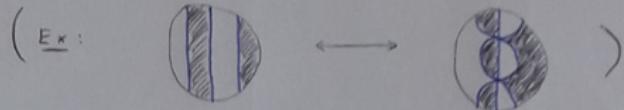
(g)

Note:

- Each move preserves the isotopy type of the induced link.

- Moves (1), (2), (B_p), (Band):

LHS and RHS admit chessboard colourings that are equal on the boundary



\Rightarrow These moves preserve also the induced orientation.

- Move (o):

Reverses chessboard colouring (& hence orientation) of the subdiagram surrounded by the annulus,

But this is a union of split-summands of the link,

\Rightarrow preserves the induced relative orientation.

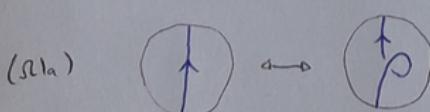
\hookrightarrow proves statement (A).

Sketch proof of statement (B) — why do these moves suffice?

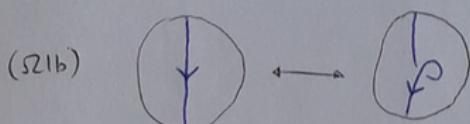
Recall:

$$\left\{ \text{2-diagrams} \right\} \xrightarrow[\text{(R1)(R2)(R3)}]{\text{iso}} \cong \left\{ \text{links} \right\} \xrightarrow{\text{iso}}$$

[Polyak 2010]: $\left\{ \text{oriented 2-diagrams} \right\} \xrightarrow[\text{(R1a), (R1b), (R2), (R3)}]{\text{iso}} \cong \left\{ \text{oriented links} \right\} \xrightarrow{\text{iso}}$



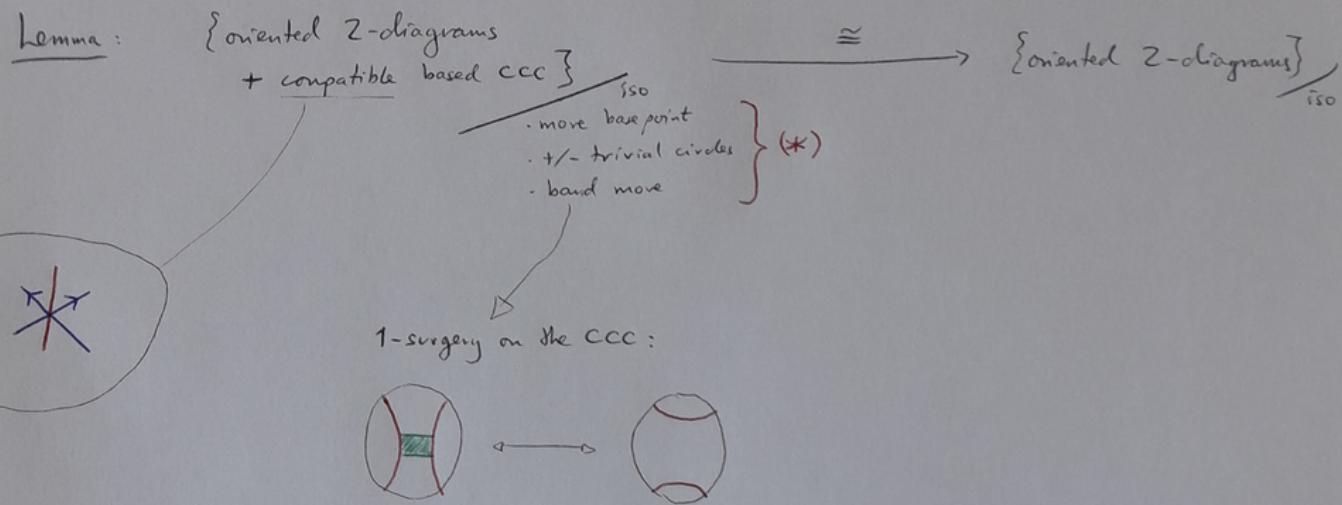
(R22)



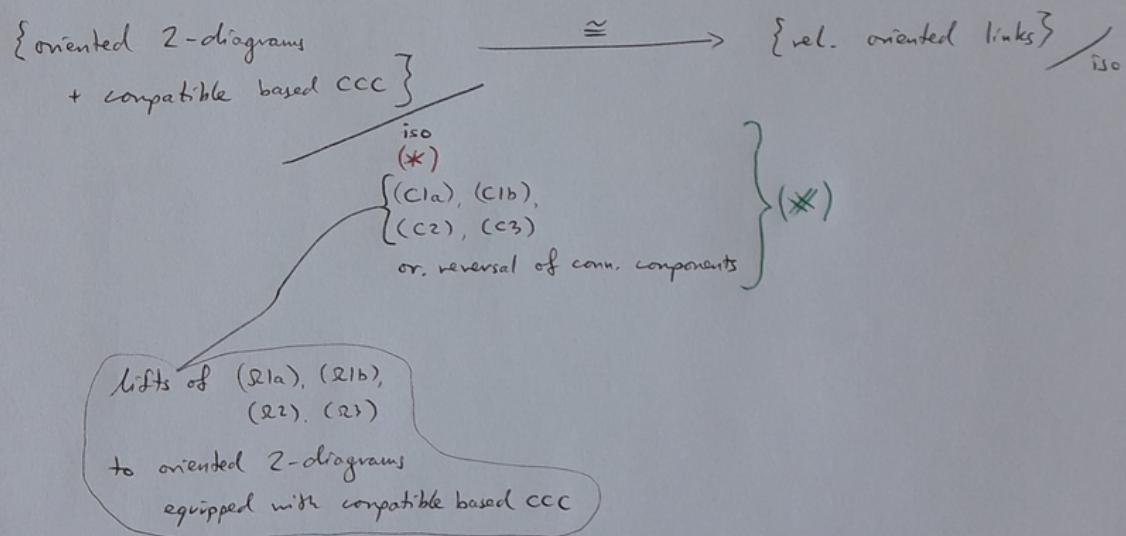
(R23)



10



Corollary (1):



Proposition (2):

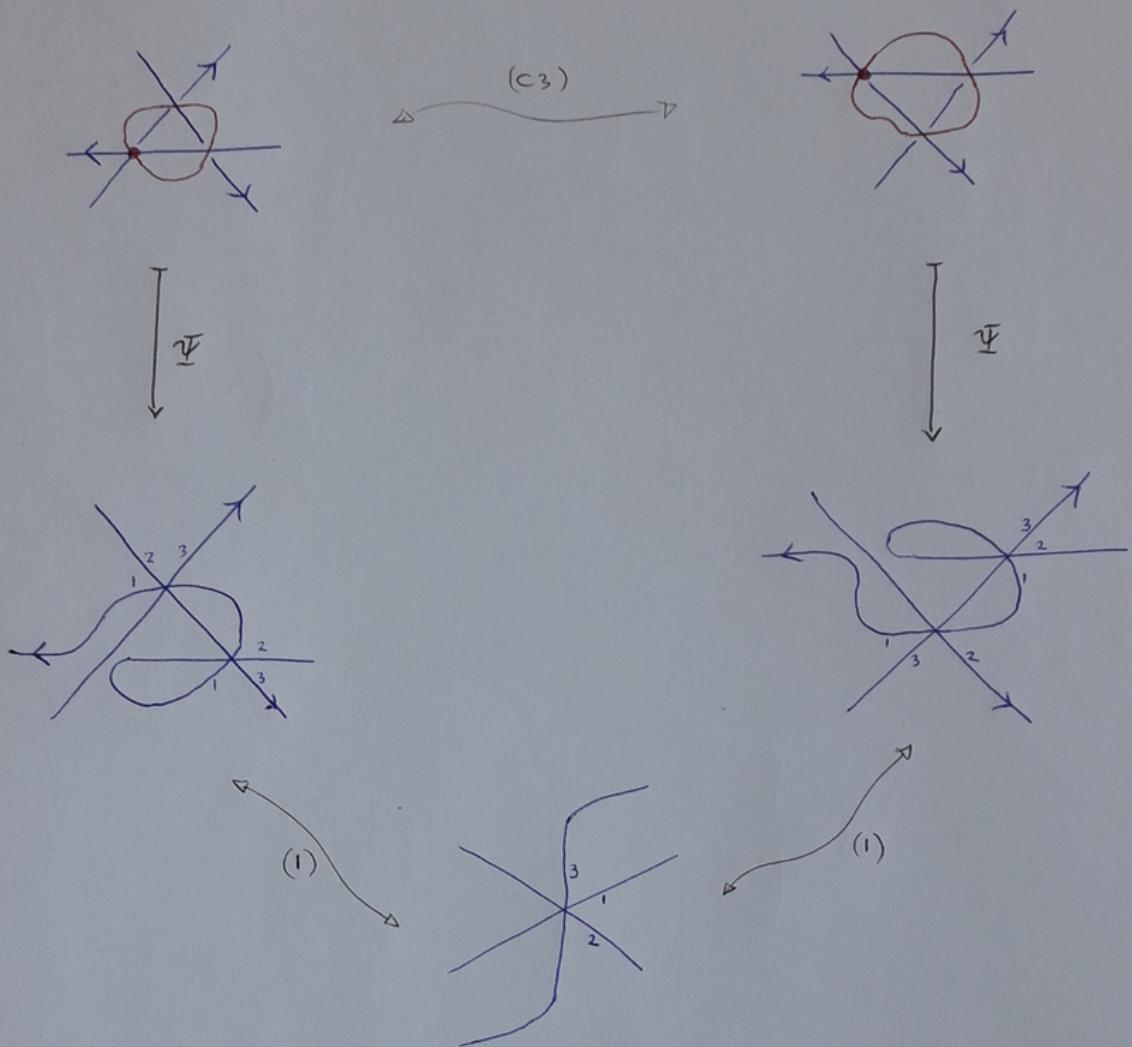
Denote by Σ the operation $\left\{ \text{oriented 2-diagrams} \atop + \text{comp.-based CCC} \right\} \rightarrow \left\{ \text{3-diagrams} \right\}$

If $d \longleftrightarrow d'$ by (**).

Then $\Sigma(d) \longleftrightarrow \Sigma(d')$ by (o), (i), (z), (S_p), (Band).

proof for move (c3) :

II



12

Lemma(3) :

\forall 3-diagram D

\exists oriented 2-diagram + compatible based CCC d

such that

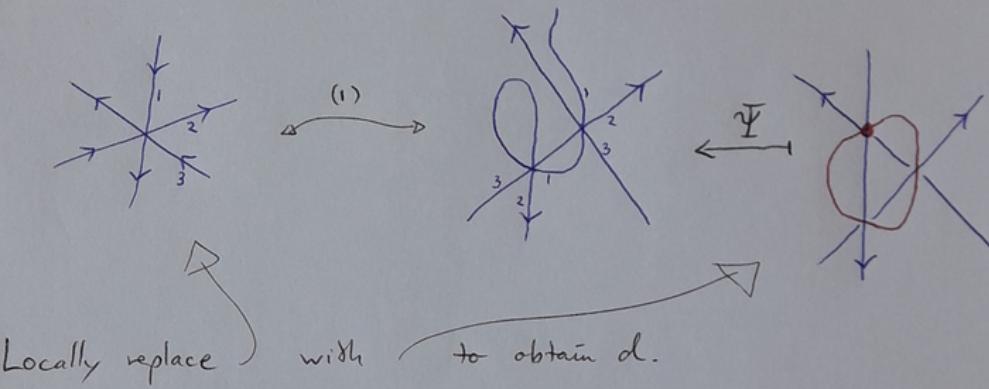
$$\Psi(d) \xrightarrow{(1)} D$$

" $\Psi : \{ \text{or. 2-diagrams} \\ + \text{comp. based ccc} \} \longrightarrow \{ \text{3-diagrams} \}$ is surjective modulo (1)-moves."

proof: Give D the canonical orientation \rightsquigarrow locally



Then:



□.

End of the proof :

D_1, D_2 3-diagrams representing the same rel. oriented link.

$$\begin{array}{ccccccc}
 D_1 & \xrightarrow{(1)} & \Psi(d_1) & \xleftarrow{\text{(2), (1'), (2'), (Bp), (Band)}} & \Psi(d_2) & \xrightarrow{(1)} & D_2 \\
 \text{Lem(3)} & & & \parallel \text{Prop(2)} & & & \text{Lem(3)} \\
 d_1 & \xrightarrow[\text{Coro(1)}]{(\times)} & d_2
 \end{array}$$

□.