

Homological stability for moduli spaces of disconnected submanifolds, I

Martin Palmer // 10th May 2018

Abstract

A well-known property of unordered configuration spaces of points (in an open, connected manifold) is that their homology *stabilises* as the number of points increases. We generalise this result to moduli spaces of submanifolds of higher dimension, where stability is with respect to the number of components having a fixed diffeomorphism type and isotopy class. As well as for unparametrised submanifolds, we prove this also for partially-parametrised submanifolds – where a *partial parametrisation* may be thought of as a superposition of parametrisations related by a fixed subgroup of the mapping class group.

In part II (in preparation), this will be further generalised to submanifolds equipped with labels in a bundle over the embedding space, from which we will deduce corollaries for the stability of diffeomorphism groups of manifolds with respect to parametrised connected sum and addition of singularities.

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1. Introduction

Let M be an open connected manifold of dimension at least 2. The configuration space of n points in M is defined to be $C_n(M) = (M^n \setminus \Delta) / \Sigma_n$, where Δ is the “collision set” of M^n

$$\Delta = \{(p_1, \dots, p_n) \in M^n \mid p_i = p_j \text{ for some } i \neq j\},$$

and Σ_n denotes the symmetric group on n letters. Alternatively, it can be written as $C_n(M) = \text{Emb}(n, M) / \Sigma_n$, where $\text{Emb}(n, M)$ denotes the space of embeddings of the zero-dimensional manifold n into M . More generally, one can define a labelled configuration space, for a given label space X , by $C_n(M, X) = \text{Emb}(n, M) \times_{\Sigma_n} X^n$. An important property of these spaces is that they satisfy homological stability as n varies:

Theorem 1.1 ([Seg73; McD75; Seg79; Ran13]) *There is a natural map $C_n(M, X) \rightarrow C_{n+1}(M, X)$ which is split-injective on homology in all degrees, and if X is path-connected it induces isomorphisms on homology up to degree $\frac{n}{2}$.*

A natural question to consider is what happens for higher-dimensional embedded submanifolds. Certain special cases have been considered before, up to dimension 2 (embedded circles and surfaces) – see §(v.) for a brief overview. The main theorem of this paper is a general stability result for moduli spaces of disconnected submanifolds of a fixed diffeomorphism type and isotopy class, where stabilisation occurs by adding new connected components to the submanifold.

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(i.) Unparametrised submanifolds. Let P be a closed manifold. A first guess for the natural analogue of $C_n(M)$ in the case of embedded copies of P may be

$$\mathbf{C}_{nP}(M) = \text{Emb}(nP, M)/(\text{Diff}(P) \wr \Sigma_n).$$

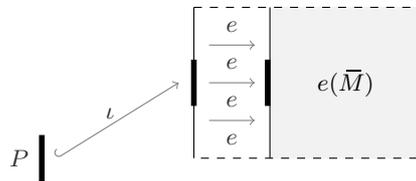
The wreath product $\text{Diff}(P) \wr \Sigma_n$ is naturally a subgroup of $\text{Diff}(nP)$, where nP is shorthand for $\{1, \dots, n\} \times P$, and they are equal if P is connected. However, in general (consider for example $M = \mathbb{R}^3$ and $P = S^1$) this has a diverging number of path-components as $n \rightarrow \infty$, so it will not satisfy homological stability even in degree zero. Instead, we study the path-components of this space separately. Assume that M is the interior of a manifold with boundary \bar{M} , and choose:

- a self-embedding $e: \bar{M} \hookrightarrow \bar{M}$ that is isotopic to the identity,
- an embedding $\iota: P \hookrightarrow \partial\bar{M}$ such that $\iota(P) \cap e(\bar{M}) = \emptyset$ and $e(\iota(P)) \subseteq M$.

Then we may define a map

$$\mathbf{C}_{nP}(M) \longrightarrow \mathbf{C}_{(n+1)P}(M) \tag{1.1}$$

by pushing a given collection of submanifolds inwards along e and adjoining a new copy of P near the boundary using $e \circ \iota$, in the region “vacated” by e .



There is a natural basepoint $[e \circ \iota]$ of $\mathbf{C}_P(M) = \text{Emb}(P, M)/\text{Diff}(P)$. Via the maps (1.1) this determines basepoints of each of the spaces $\mathbf{C}_{nP}(M)$. We now define $C_{nP}(M)$ to be the path-component of $\mathbf{C}_{nP}(M)$ containing this basepoint. The maps (1.1) restrict to *stabilisation maps*

$$C_{nP}(M) \longrightarrow C_{(n+1)P}(M). \tag{1.2}$$

We can now state a special case of our main theorem.

Theorem 1.2 (Special case of Theorem A) *If $\dim(P) \leq \frac{1}{2}(\dim(M) - 3)$, the stabilisation maps (1.2) induce split-injections on homology in all degrees and isomorphisms up to degree $\frac{n}{2}$.*

(ii.) Superpositions of parametrised submanifolds. Instead of taking the orbit space by the action of $\text{Diff}(P) \wr \Sigma_n$, we also consider the orbit space

$$\mathbf{C}_{nP}(M; G) = \text{Emb}(nP, M)/(G \wr \Sigma_n)$$

for an open subgroup $G \leq \text{Diff}(P)$. The diffeomorphism group $\text{Diff}(P)$ is locally path-connected, so its open subgroups are in one-to-one correspondence with the subgroups of the *mapping class group* $\pi_0(\text{Diff}(P))$. A point in $\text{Emb}(nP, M)/(G \wr \Sigma_n)$ is a collection of n pairwise disjoint submanifolds of M that are each diffeomorphic to P and each equipped with a parametrisation up to the action of G , in other words, a G -orbit of parametrisations, which may be more poetically described as a “*superposition*” of parametrisations.

Proceeding exactly as above (see §2 for precise constructions), we restrict to a particular sequence $C_{nP}(M; G)$ of path-components and obtain stabilisation maps

$$C_{nP}(M; G) \longrightarrow C_{(n+1)P}(M; G). \tag{1.3}$$

Our main theorem is then the following.

Theorem 1.3 (Equivalent to Theorem A) *If $\dim(P) \leq \frac{1}{2}(\dim(M) - 3)$, the stabilisation maps (1.3) induce split-injections on homology in all degrees and isomorphisms up to degree $\frac{n}{2}$.*

⟨iii.⟩ **Corollaries for mixed configurations and different kinds of stability.**

Remark 1.4 (*Mixed configurations.*) So far we have only discussed one path-component of the space $\mathbf{C}_{nP}(M; G)$, namely the one in which the embedded copies of P are isotopic (modulo G) to the standard embedding $\{[e \circ \iota], [e^2 \circ \iota], \dots, [e^n \circ \iota]\}$, in particular the different copies of P are isotopic to each other. However, once we know Theorem 1.3, we also immediately obtain homological stability for “mixed configurations” of submanifolds, in which there are n copies of P that are embedded so as to be isotopic to the standard embedding $\{[e \circ \iota], [e^2 \circ \iota], \dots, [e^n \circ \iota]\}$, as well as finitely many other embedded submanifolds (possibly with different diffeomorphism types or even dimensions), such that these two parts of the configuration may be isotoped to be “far apart” (more precisely, so that all copies of P are in a specified collar neighbourhood of $\partial\bar{M}$ and all other components of the configuration are disjoint from this collar neighbourhood).

A rough sketch of how to deduce homological stability for such moduli spaces of mixed configurations is as follows. We consider the forgetful map that forgets the copies of P and remembers only the other components of the configuration, which turns out to be a fibre bundle. The stabilisation map for the moduli spaces of mixed configurations is then a map of fibre bundles over a fixed base space, and its restriction to each fibre is a stabilisation map of the form (1.3), which is homologically stable by Theorem 1.3. Via the induced map of Serre spectral sequences this implies that the stabilisation map for the moduli spaces of mixed configurations is also homologically stable.

Remark 1.5 (*Twisted homological stability.*) Unordered configuration spaces of points are also homologically stable with respect to so-called *finite-degree – or polynomial – twisted coefficient systems*. For the symmetric groups (corresponding to configurations in \mathbb{R}^∞) this is due to [Bet02], and the result was extended to configuration spaces (in any connected, open manifold) in [Pal13a]. The method of proof in [Pal13a] is to relate the statement of homological stability with polynomial twisted coefficients, via a decomposition of the coefficients, a version of Shapiro’s lemma and a spectral sequence, to homological stability with constant coefficients, and then deduce the twisted version from the constant version. This method is wholly compatible with the setting of moduli spaces of disconnected submanifolds in this paper, so a generalisation of that argument, together with Theorem 1.3, implies that the stabilisation maps (1.3) are also homologically stable with respect to (appropriately-defined) polynomial twisted coefficient systems.

Remark 1.6 (*Representation stability.*) Via an argument of Søren Galatius, which uses only elementary representation theory of the symmetric groups, representation stability [CF13] for the rational cohomology of *ordered* configuration spaces (which was first proved by other means in [Chu12]) may be deduced from twisted homological stability for the unordered configuration spaces, for a certain polynomial twisted coefficient system. The same argument applied to Theorem 1.3 (and Remark 1.5 above) implies that the rational cohomology of the ordered moduli spaces of disconnected submanifolds, in which the different copies of P are equipped with a total ordering, is representation stable.

⟨iv.⟩ **Labelled submanifolds and corollaries for diffeomorphism groups.** Let Z be a first-countable right G -space and $\pi: Z \rightarrow \text{Emb}(P, \bar{M})$ a surjective G -equivariant fibre bundle. Let Z_n be the preimage of $\text{Emb}(nP, M) \subseteq \text{Emb}(P, \bar{M})^n$ under the map π^n . This is a right $(G \wr \Sigma_n)$ -space and the map $\pi_n: Z_n \rightarrow \text{Emb}(nP, M)$ is $(G \wr \Sigma_n)$ -equivariant. We define

$$\mathbf{C}_{nP}(M, Z; G) = Z_n / (G \wr \Sigma_n).$$

The map π_n induces a map $\mathbf{C}_{nP}(M, Z; G) \rightarrow \mathbf{C}_{nP}(M; G)$. Choosing a basepoint of Z in $\pi^{-1}(e \circ \iota)$ determines a path-component of $\mathbf{C}_{nP}(M, Z; G)$. We assumed that e is isotopic to the identity, so we may choose a path between e and the identity, which determines a path in $\text{End}(\text{Emb}(P, \bar{M}))$ by post-composition. Using Corollary 4.23 we may lift this to a path of endomorphisms of Z and then use this to lift the stabilisation maps from $\mathbf{C}_{nP}(M; G) \rightarrow \mathbf{C}_{(n+1)P}(M; G)$ to $\mathbf{C}_{nP}(M, Z; G) \rightarrow \mathbf{C}_{(n+1)P}(M, Z; G)$, which also determines a path-component $C_{nP}(M, Z; G)$ for each n . In part II we will prove that Theorem 1.3 lifts to this setting.

This will allow us to deduce a number of corollaries about homological stability of different kinds of diffeomorphism groups, including:

- *Symmetric diffeomorphism groups*, with respect to the operation of parametrised connected sum along a submanifold. This will extend some of the results of [Til16], which are concerned with symmetric diffeomorphism groups and the operation of connected sum (at a point).
[If we have two embeddings $e: L \hookrightarrow M$ and $f: L \hookrightarrow N$ and an isomorphism of normal bundles $\theta: \nu_e \cong \nu_f$, the parametrised connected sum is obtained by removing tubular neighbourhoods of $e(L)$ and $f(L)$ and identifying the resulting boundaries using θ .]
- Diffeomorphism groups of manifolds with Baas-Sullivan singularities [Sul67; Baa73], with respect to the number of singularities of a fixed type.

⟨v.⟩ **Related results.** There are several other homological stability results which are closely related to Theorem 1.3. We will give a brief overview in order of increasing dimension.

Configurations of finite sets on a surface. In [Tra14] it is shown that the *partitioned surface braid groups* are homologically stable. Fix a positive integer ξ . There is a short exact sequence

$$1 \rightarrow P\beta_{n\xi}^S \longrightarrow \beta_{n\xi}^S \longrightarrow \Sigma_{n\xi} \rightarrow 1,$$

where the kernel $P\beta_{n\xi}^S$ is the *pure surface braid group* on $n\xi$ strands. The wreath product $\Sigma_\xi \wr \Sigma_n = (\Sigma_\xi)^n \rtimes \Sigma_n$ is naturally a subgroup of $\Sigma_{n\xi}$, and the n th *partitioned braid group* $\beta_n^{\xi, S}$ is defined to be its preimage in $\beta_{n\xi}^S$. Geometrically, it is the subgroup of the $n\xi$ th braid group on S consisting of braids that preserve a given partition $n\xi = \xi + \xi + \cdots + \xi$ of the endpoints. This is a subgroup of index

$$\frac{(n\xi)!}{n! (\xi!)^n},$$

corresponding to a covering space of $C_{n\xi}(S)$ with this number of sheets. Alternatively, it may be thought of as the *moduli space of n pairwise disjoint submanifolds of M of diffeomorphism type P* , where $P = \{1, \dots, \xi\}$. We note that this result is not included as a special case of Theorem 1.3, since $\dim(P) = 0 \not\leq \frac{1}{2}(\dim(S) - 3) = -\frac{1}{2}$.

Circles in Euclidean space. Going up from dimension zero to dimension one, in [Kup13] it is shown that the sequence of moduli spaces

$$C_{nS^1}(M) \longrightarrow C_{(n+1)S^1}(M)$$

is homologically stable when M is a connected 3-manifold and $S^1 \hookrightarrow \partial M$ is an embedding into a coordinate chart. These are the spaces of n -component unlinks in M , for varying n . Note that Theorem 1.3 only applies once the dimension of M is at least 5, so the two results are disjoint.

The subspace $\mathcal{E}_n \subset C_{nS^1}(D^3)$ of unknotted, unlinked *Euclidean circles* was studied in [BH13] (the adjective ‘‘Euclidean’’ means that a circle is the image of $\{(x, y, z) \in \mathbb{R}^3 \mid z = 0, x^2 + y^2 = 1\}$ under rotation, translation and dilation), who showed that the inclusion is a homotopy equivalence. As a corollary, the spaces \mathcal{E}_n are also homologically stable.

String motion groups. Closely related to this is the sequence of fundamental groups of the spaces $\mathcal{E}_n \simeq C_{nS^1}(D^3)$, which are called the *circle-braid groups* or the *string motion groups*. They are isomorphic to the symmetric automorphism groups $\Sigma\text{Aut}(F_n)$ of the free groups F_n and also to certain quotients of mapping class groups of 3-manifolds. In this latter guise they were proved in [HW10, Corollary 1.2] to satisfy homological stability. More generally [HW10, Corollary 1.3] proves homological stability for $\Sigma\text{Aut}(G^{*n})$, where G^{*n} denotes the iterated free product $G * \cdots * G$, for $G = \pi_1(P)$ for certain 3-manifolds P (in particular $P = S^1 \times D^2$). By [CDG13, Théorème 1.2] these symmetric automorphism groups actually satisfy homological stability for any group G . Moreover, their integral homology may in principle be calculated using the methods of [Gri13].¹

¹ See Theorem C of [Gri13]. The statement is for $\text{Aut}(G^{*n})$ and doesn’t permit G to be \mathbb{Z} , but this restriction is removed by replacing $\text{Aut}(G^{*n})$ with $\Sigma\text{Aut}(G^{*n})$. In particular the integral homology of $\pi_1(\mathcal{E}_n) = \Sigma\text{Aut}(F_n)$ is identified with the direct sum of $H_*(\mathbb{Z}/2) \wr \Sigma_n; \mathbb{Z}$ together with $H_{*-e}(\mathbb{Z}/2) \wr \text{Aut}(f); \mathbb{Z}$ where f runs over certain directed, labelled graphs with n vertices and e is the number of edges of f . The wreath product is formed using the obvious homomorphism $\text{Aut}(f) \rightarrow \Sigma_n$ given by the action of f on its vertices.

Note that the spaces \mathcal{E}_n are not aspherical (they are finite-dimensional manifolds whose fundamental groups contain torsion), so homological stability for $\pi_1(\mathcal{E}_n)$ is independent of homological stability for the spaces \mathcal{E}_n themselves.

Rationally, homological stability for $\pi_1(\mathcal{E}_n)$ is also known via a different route. There is a homomorphism to the hyperoctahedral group $\pi_1(\mathcal{E}_n) \rightarrow W_n = (\mathbb{Z}/2) \wr \Sigma_n$ which just remembers the permutation of the n circles and their orientations; the kernel of this is called the *pure string motion group*. By [Wil12] the rational cohomology of the pure string motion groups is *uniformly representation stable* (see [CF13, Definition 2.6]) with respect to the action of W_n , from which it follows that the groups $\pi_1(\mathcal{E}_n)$ are rationally homologically stable. In fact, by Theorem 7.1 of [Wil12], the rational homology of $\pi_1(\mathcal{E}_n)$ is trivial.

Spaces of connected subsurfaces. One dimension higher again, [CR17] proves a homological stability result for spaces of *connected* subsurfaces of a manifold. Denote the connected, orientable surface of genus g with b boundary components by $\Sigma_{g,b}$ and let

$$\mathcal{E}(\Sigma_{g,b}, M) = \text{Emb}(\Sigma_{g,b}, M) / \text{Diff}^+(\Sigma_{g,b}),$$

where the embeddings are prescribed on a sufficiently small collar neighbourhood of the boundary $\partial\Sigma_{g,b}$ and the diffeomorphisms are required to be the identity on a sufficiently small collar neighbourhood of ∂M . Given a surface embedded in $\partial M \times [0, 1]$ with the correct boundary there is an induced stabilisation map $\mathcal{E}(\Sigma_{g,b}, M) \rightarrow \mathcal{E}(\Sigma_{g',b'}, M)$. Theorem 1.3 of [CR17] says that these maps are homologically stable, under the assumption that M is simply-connected and of dimension at least 6 (or dimension 5 with an extra restriction on the permissible stabilisation maps). The stable ranges for the various stabilisation maps are the same as the best-known ranges for Harer stability [Har85; Iva93], which were obtained in [Bol12] and [Ran16]; see also [Wah13]. In particular Theorem 1.3 of [CR17] recovers Harer stability when $M = \mathbb{R}^\infty$.

Moreover, [CR17] also identifies the homology in the stable range. There is a well-defined scanning map from each $\mathcal{E}(\Sigma_{g,b}, M)$ to a certain explicit limiting space (a union of path-components of the space of compactly-supported sections of a bundle over M) which induces an isomorphism on homology in the stable range, assuming that M is simply-connected and at least 5-dimensional.

(vi.) Stable homology. The next natural question after Theorem 1.3 is *what is the limiting homology?* As mentioned in the paragraph just above, this is known for moduli spaces of connected subsurfaces. For unordered configuration spaces this question was answered by McDuff in [McD75]:

$$\text{colim}_{n \rightarrow \infty} H_*(C_n(M, X)) \cong H_*(\Gamma_{c,o}(\dot{T}M \wedge_{\text{fib}} X_+ \rightarrow M)).$$

The colimit is taken along the stabilisation maps, $\dot{T}M \rightarrow M$ is the fibrewise one-point compactification of the tangent bundle of M , $\dot{T}M \wedge_{\text{fib}} X_+$ is its fibrewise smash product with X_+ and $\Gamma_{c,o}$ denotes any path-component of the space of compactly-supported sections of this bundle.

For moduli spaces of disconnected submanifolds one natural first guess is that the *scanning map* is a homology equivalence in the limit. This is the map which identifies the limiting homology for unordered configuration spaces and for moduli spaces of connected subsurfaces, and it is also well-defined for moduli spaces of disconnected submanifolds. For simplicity we will consider just *unparametrised* submanifolds, and discuss the scanning map for $C_{nP}(M)$.

For a finite-dimensional real vector space V let $Gr_p(V)$ be the Grassmannian of p -planes in V , let $\gamma_p^\perp(V)$ be the orthogonal complement of the canonical p -plane bundle over $Gr_p(V)$ and denote its total space by $A_p(V)$; this is the affine Grassmannian of p -planes in V . Since $Gr_p(V)$ is compact the Thom space $\text{Th}(\gamma_p^\perp(V))$ is the one-point compactification of $A_p(V)$, denoted $\dot{A}_p(V)$. This construction is functorial in V , so one can apply it fibrewise to real vector bundles, and in particular form the bundle $\dot{A}_p(TM) \rightarrow M$ of affine p -planes in the tangent bundle of M . The *scanning map for $C_{nP}(M)$* may be constructed exactly as for spaces of connected subsurfaces (see page 1388 of [CR17]),² and is of the form

$$C_{nP}(M) \longrightarrow \Gamma_{c,o}(\dot{A}_p(TM) \rightarrow M).$$

² Strictly speaking, one actually constructs a zig-zag of two maps where the reversed map is a weak equivalence.

In the case $M = \mathbb{R}^m$ the codomain is $\Omega_0^m \dot{A}_p(\mathbb{R}^m)$, so if we specialise to $m = 3$ and $P = S^1$ we have

$$\mathcal{E}_n \simeq C_{nS^1}(\mathbb{R}^3) \longrightarrow \Omega_0^3 \dot{A}_1(\mathbb{R}^3).$$

In [Kup13, §2] it is shown that the first rational homology of the right-hand side is one-dimensional, whereas (abelianising the computation of $\pi_1(\mathcal{E}_n)$ in [BH13]) the first integral homology of the left-hand side is $(\mathbb{Z}/2)^3$ for all $n \geq 2$. So the first guess that the scanning map identifies the stable homology of moduli spaces of disconnected submanifolds cannot be correct.

⟨vii.⟩ Open questions. Following on from the previous section, one open problem is of course to identify the stable homology of moduli spaces of disconnected submanifolds $C_{nP}(M; G)$ in the cases when it is known to stabilise. This is – to the best of the author’s knowledge – currently unknown unless P is a point.

Another open question is whether the dimension condition $p \leq \frac{1}{2}(m-3)$ on the dimensions $(m, p) = (\dim(M), \dim(P))$ can be weakened. The evidence suggests that it “should” be possible, since the dimension pairs $(2, 0)$ and $(3, 1)$ are excluded by the condition $p \leq \frac{1}{2}(m-3)$, but configuration spaces of points (or collections of ξ points) on surfaces are certainly homologically stable, as are moduli spaces of unlinks in 3-manifolds, by [Kup13]. Almost all of the cases in which homological stability is known for spaces of submanifolds are within the range in which there can be no non-trivial knotting — the condition $p \leq \frac{1}{2}(m-3)$ ensures this, as does the condition that M must have dimension at least 5 in the case of connected oriented subsurfaces. One exception is of course $C_{nS^1}(M)$ for a 3-manifold M , but in this case only the path-component of the unlink has been shown to be homologically stable; it is not known what happens if one tries to stabilise by adding new non-trivially knotted components to the configuration.

Outline. In the next section we give a more precise statement of the main result of the paper, Theorem 1.3, which is reformulated there as Theorem A. This will be proved in §5. In §3 we first isolate the spectral sequence part of the argument by giving an “axiomatic” homological stability theorem, or “homological stability criterion”, Theorem 3.8. In §4 we prove some preliminary results about fibre bundles and fibrations that we will need, notably using the notion of locally retractile group actions to show that certain maps between smooth mapping spaces are fibre bundles. Then in §5 we apply the homological stability criterion Theorem 3.8 to prove Theorem A. The appendix §6 contains a proof of a technical lemma about homotopy fibres of augmented semi-simplicial spaces, which is used in a key step of the proof.

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2. Precise formulation of the main result

Let M be a smooth, connected manifold of dimension m , with non-empty boundary. Let P be a smooth, closed manifold of dimension p and choose an embedding

$$\iota: P \hookrightarrow \partial M,$$

as well as a collar neighbourhood for the boundary of M , in other words a proper embedding

$$\lambda: \partial M \times [0, 2] \hookrightarrow M$$

such that $\lambda(z, 0) = z$ for all $z \in \partial M$. We also assume that λ has the property that it may be extended to a slightly larger proper embedding $\partial M \times [0, 2 + \epsilon] \hookrightarrow M$ for some $\epsilon > 0$, but we do not fix this data. Choose an open (therefore closed) subgroup $G \leq \text{Diff}(P)$.

Notation 2.1 For $\epsilon \in [0, 2]$ we will write $M_\epsilon = M \setminus \lambda(\partial M \times [0, \epsilon])$. In particular, M_0 is the interior of M . We will use the embedding space $\text{Emb}(P, M)$ very often, so we abbreviate it to $E = \text{Emb}(P, M)$. For a non-negative integer k , we write kP for the disjoint union of k copies of the manifold P , which is \emptyset if $k = 0$.

Let n be a non-negative integer. Consider the embedding space $\text{Emb}(nP, M_1)$, which has a left-action of the group $G \wr \Sigma_n \leq \text{Diff}(nP)$. The quotient space $\text{Emb}(nP, M_1)/(G \wr \Sigma_n)$ may be thought of as the subspace of the symmetric product $\text{Sp}^n(E/G)$ consisting of configurations $\{[\varphi_1], \dots, [\varphi_n]\}$ such that the images $\varphi_i(P)$ are contained in $M_1 \subseteq M$ and are pairwise disjoint. Analogously, we consider the quotient $\text{Emb}((n+1)P, M_0)/(G \wr \Sigma_{n+1})$ as a subspace of $\text{Sp}^{n+1}(E/G)$.

Definition 2.2 A *standard configuration* in $\text{Emb}(nP, M_1)/(G \wr \Sigma_n) \subseteq \text{Sp}^n(E/G)$ is one of the form

$$\{[\lambda(-, t_1) \circ \iota], \dots, [\lambda(-, t_n) \circ \iota]\},$$

where t_1, \dots, t_n are n distinct numbers in the interval $(1, 2)$. Note that all standard configurations are in the same path-component. A *standard configuration* in $\text{Emb}((n+1)P, M_0)/(G \wr \Sigma_{n+1})$ is one of the form

$$\{[\lambda(-, t_1) \circ \iota], \dots, [\lambda(-, t_{n+1}) \circ \iota]\},$$

where t_1, \dots, t_{n+1} are $n+1$ distinct numbers in the interval $(0, 2)$.

Definition 2.3 We now define a map $f: X \rightarrow Y$ depending on the data $(M, P, \lambda, \iota, G, n)$. First, X is the path-component of $\text{Emb}(nP, M_1)/(G \wr \Sigma_n)$ containing the standard configurations and Y is the path-component of $\text{Emb}((n+1)P, M_0)/(G \wr \Sigma_{n+1})$ containing the standard configurations. The map f is then defined as follows:

$$\{[\varphi_1], \dots, [\varphi_n]\} \longmapsto \{[\lambda(-, \frac{1}{2}) \circ \iota], [\varphi_1], \dots, [\varphi_n]\}.$$

Remark 2.4 This is an explicit version of the more intuitively-defined stabilisation maps (1.3) in the introduction.

Lemma 2.5 *The induced map $f_*: H_*(X) \rightarrow H_*(Y)$ is split-injective.*

This is not difficult to prove: see §5.2. The main result of this paper is that these maps are also *surjective* on homology in a range of degrees, if we assume that the dimension p of P is sufficiently small compared to the dimension m of M .

Theorem A *The induced map $f_*: H_*(X) \rightarrow H_*(Y)$ is an isomorphism if $* \leq \frac{n}{2}$ and $p \leq \frac{1}{2}(m-3)$.*

This is equivalent to Theorem 1.3, and will be proved in §5. Before that, in §3 we establish some sufficient axiomatic criteria for homological stability.

3. Homological stability criteria

In order to separate the geometric part of the proof from the more technical manipulation of spectral sequences, we give an axiomatic criterion for homological stability in this section, and apply it to moduli spaces of disconnected submanifolds in §5. The idea of this method of proving homological stability – finding “resolutions” of the maps one wishes to prove stability for – is due to [Ran16] and has been used many times subsequently, for example in [CR17; GR18; KM16; Per16; Ran13].³

3.1. Setup Suppose that for each integer $n \geq 0$ we have a collection $\mathcal{X}(n)$ of maps between path-connected spaces. We want to find conditions implying that each $f \in \mathcal{X}(n)$ is $\frac{n}{2}$ -homology-connected, meaning that it is an isomorphism on homology up to degree $\frac{n}{2} - 1$ and a surjection up to degree $\frac{n}{2}$, equivalently that its mapping cone Cf has trivial reduced homology up to degree $\frac{n}{2}$. As a convention we take $\mathcal{X}(n) = \{\text{all continuous maps}\}$ for $n < 0$.⁴

³ The axiomatic criterion for homological stability in this section, abstracted from the methods of [Ran16], is not stated quite as generally as it could be. For example it does not apply directly to the situations of [Ran16] and [CR17] since in those cases one has a collection of maps graded by a semi-group which is not \mathbb{N} , and it also does not apply to the situation of [KM16] since in that case the connectivity of the resolutions grows more slowly than $\frac{n}{2}$.

⁴ This is compatible with our aim that each $f \in \mathcal{X}(n)$ is $\frac{n}{2}$ -homology-connected: for $n = -1$ or -2 this says that the mapping cone Cf has trivial reduced homology in degree -1 , in other words $Cf \neq \emptyset$, but mapping cones are always non-empty (the mapping cone of $\emptyset \rightarrow X$ is X_+). For $n \leq -3$ the condition is vacuous.

We will show that this holds if each $f \in \mathcal{X}(n)$ admits a *resolution*, each level of which can be *approximated* by a map in $\mathcal{X}(k)$ for $k < n$, plus a certain factorisation condition that these data must satisfy. We begin by making this last sentence precise.

Notation 3.1 (Homology-connectivity.) For a map $f: X \rightarrow Y$, the number $h\text{conn}(f)$ is the largest integer n such that $f_*: H_*(X) \rightarrow H_*(Y)$ is an isomorphism for $* \leq n-1$ and surjective for $* = n$. Equivalently it is the largest integer n such that the reduced homology of the mapping cone of f is trivial up to degree n .

Definition 3.2 (Resolution of a space.) Recall that an augmented semi-simplicial space Y_\bullet is a diagram of the form

$$\cdots \begin{array}{c} \rightrightarrows \\ \rightrightarrows \end{array} Y_1 \begin{array}{c} \rightrightarrows \\ \rightrightarrows \end{array} Y_0 \longrightarrow Y_{-1} = Y$$

with face maps $d_i: Y_k \rightarrow Y_{k-1}$ for $1 \leq i \leq k+1$ which satisfy the simplicial identities $d_i d_j = d_{j-1} d_i$ when $i < j$. Its geometric realisation $\|Y_\bullet\|$ is the quotient of $\bigsqcup_{k \geq 0} Y_k \times \Delta^k$ by the face relations $(d_i(y), z) \sim (y, \delta_i(z))$, where δ_i is the inclusion of the i th face of the standard simplex Δ^{k+1} . This depends only on the unaugmented part $Y_{\geq 0}$ of Y_\bullet , and the augmentation map $Y_0 \rightarrow Y$ induces a well-defined map $\|Y_\bullet\| \rightarrow Y$. The augmented semi-simplicial space Y_\bullet is a *c-resolution* of Y if $h\text{conn}(\|Y_\bullet\| \rightarrow Y) \geq [c]$.

Definition 3.3 (Resolution of a map.) If we have a map of augmented semi-simplicial spaces

$$\begin{array}{ccc} \vdots & & \vdots \\ \downarrow \downarrow \downarrow & \xrightarrow{f_1} & \downarrow \downarrow \downarrow \\ X_1 & \xrightarrow{f_1} & Y_1 \\ \downarrow \downarrow & \xrightarrow{f_0} & \downarrow \downarrow \\ X_0 & \xrightarrow{f_0} & Y_0 \\ \downarrow & \xrightarrow{f} & \downarrow \\ X & \xrightarrow{f} & Y \end{array} \quad (3.1)$$

where X_\bullet is a $(c-1)$ -resolution and Y_\bullet is a c -resolution, then we say that the semi-simplicial map $f_\bullet: X_\bullet \rightarrow Y_\bullet$ is a *c-resolution* of $f: X \rightarrow Y$.

Definition 3.4 (Approximation of a resolution.) We say that a given c -resolution $f_\bullet: X_\bullet \rightarrow Y_\bullet$ is *approximated* by maps $\{f'_{i\alpha}: X'_{i\alpha} \rightarrow Y'_{i\alpha}\}$ if the following holds (the index α runs over an indexing set which depends on i). For each $i \geq 0$ there is a commutative square

$$\begin{array}{ccc} X_i & \xrightarrow{f_i} & Y_i \\ p_i \downarrow & & \downarrow q_i \\ A_i & \xrightarrow{\phi_i} & B_i \end{array} \quad (3.2)$$

in which p_i and q_i are Serre fibrations and ϕ_i is a weak equivalence. Additionally, for at least one point $a_{i\alpha}$ in each path-component $A_{i\alpha}$ of A_i , the restriction of f_i to $p_i^{-1}(a_{i\alpha}) \rightarrow q_i^{-1}(\phi_i(a_{i\alpha}))$ is equal to $f'_{i\alpha}: X'_{i\alpha} \rightarrow Y'_{i\alpha}$.

Definition 3.5 (Double resolution and approximation) A *double resolution and approximation* of a map $f: X \rightarrow Y$ is a c_1 -resolution $f_\bullet: X_\bullet \rightarrow Y_\bullet$ approximated by maps $\{f'_{i\alpha}: X'_{i\alpha} \rightarrow Y'_{i\alpha}\}$, a commutative square

$$\begin{array}{ccc} \bar{X}_\alpha & \xrightarrow{g_\alpha} & \bar{Y}_\alpha \\ \downarrow & & \downarrow \\ X'_{0\alpha} = p_0^{-1}(a_{0\alpha}) & \xrightarrow{f'_{0\alpha}} & q_0^{-1}(\phi_0(a_{0\alpha})) = Y'_{0\alpha} \end{array} \quad (3.3)$$

for each point $a_{0\alpha} \in A_0$ as above, in which the vertical maps are weak equivalences, followed by (for each α) a c_2 -resolution $g_{\alpha\bullet}: \bar{X}_{\alpha\bullet} \rightarrow \bar{Y}_{\alpha\bullet}$ approximated by maps $\{\bar{X}'_{\alpha i\beta} \rightarrow \bar{Y}'_{\alpha i\beta}\}$. This can of course be continued in the obvious way to define *iterated resolutions and approximations*, but we will only need double resolutions and approximations later.

Definition 3.6 (Three factorisation conditions.) Consider a commutative square of continuous maps

$$\begin{array}{ccc} A & \longrightarrow & B \\ \downarrow & & \downarrow h \\ C & \xrightarrow{f} & D \end{array} \quad (3.4)$$

This satisfies the *weak factorisation condition* if h factors up to homotopy through f . It satisfies the *strong factorisation condition* if it has a triangle decomposition

$$\begin{array}{ccc} A & \longrightarrow & B \\ \downarrow & \begin{array}{c} \nearrow H \\ \searrow J \end{array} & \downarrow h \\ C & \xrightarrow{f} & D \end{array} \quad (3.5)$$

(meaning that there exists a diagonal map $B \rightarrow C$ and homotopies H and J), and the composite homotopy $HJ: S^1 \times A \rightarrow D$ is homotopic to the identity homotopy. It satisfies the *moderate factorisation condition* if there is a triangle decomposition (3.5) and a map $\ell: Z \rightarrow A$ such that the composite map $HJ \circ (\text{id} \times \ell): S^1 \times Z \rightarrow D$ factors up to homotopy through f , in other words there is a dotted map making the square

$$\begin{array}{ccc} S^1 \times Z & \xrightarrow{\text{id} \times \ell} & S^1 \times A \\ \downarrow \ddots & & \downarrow HJ \\ C & \xrightarrow{f} & D \end{array} \quad (3.6)$$

commute up to homotopy.

Remark 3.7 The moderate factorisation condition implies the weak factorisation condition: if there is a triangle decomposition (3.5), then h factors (via J) up to homotopy through f . Also, the strong factorisation condition implies the moderate factorisation condition: if $HJ: S^1 \times A \rightarrow D$ is homotopic to the identity homotopy, then we may take $Z = A$, $\ell = \text{id}$ and the dotted map $S^1 \times A \rightarrow C$ to be the projection onto the second factor followed by the map $A \rightarrow C$ from (3.4).

3.2. Sufficient criteria for stability

Theorem 3.8 For each integer $n \geq 0$, let $\mathcal{X}(n)$ be a collection of maps between path-connected spaces. Then any one of the following six conditions implies that $\text{hconn}(f) \geq \lfloor \frac{n}{2} \rfloor$ for each $f \in \mathcal{X}(n)$ and each $n \geq 0$, in other words, the sequence $\mathcal{X}(n)$ is homologically stable.

For any $m \leq n$ define $\mathcal{X}_m^n = \{f \mid f \text{ is weakly equivalent to a map in } \mathcal{X}(k) \text{ for } m \leq k \leq n\}$.

The six conditions are as follows. For each $n \geq 2$, each $f: X \rightarrow Y$ of $\mathcal{X}(n)$ has

- (1) an $\frac{n}{2}$ -resolution $f_\bullet: X_\bullet \rightarrow Y_\bullet$ approximated by maps $f'_{i\alpha}$ with $f'_{0\alpha} \in \mathcal{X}_{n-2}^{n-1}$ and $f'_{i\alpha} \in \mathcal{X}_{n-2i}^{n-1}$ for $i \geq 1$. In addition, for each α , the square

$$\begin{array}{ccc} X'_{0\alpha} & \xrightarrow{f'_{0\alpha}} & Y'_{0\alpha} \\ \downarrow & & \downarrow \\ X & \xrightarrow{f} & Y \end{array} \quad (3.7)$$

- (1s) *satisfies the strong factorisation condition.*
 (1m) *satisfies the moderate factorisation condition with $\ell \in \mathcal{X}_{n-2}^{n-1}$.*
 (1w) *satisfies the weak factorisation condition, and we assume that every map in $\bigcup_{n \geq 0} \mathcal{X}(n)$ induces injections on homology in all degrees.*
 (2) *an $\frac{n}{2}$ -resolution $f_\bullet: X_\bullet \rightarrow Y_\bullet$ approximated by maps $f'_{i\alpha}$ with $f'_{0\alpha} \in \mathcal{X}_{n-2}^{n-1}$ and $f'_{i\alpha} \in \mathcal{X}_{n-2i}^{n-1}$ for $i \geq 1$. Also, for each α , the map $g_\alpha: \bar{X}_\alpha \rightarrow \bar{Y}_\alpha$ has an $\frac{n}{2}$ -resolution $g_{\alpha\bullet}: \bar{X}_{\alpha\bullet} \rightarrow \bar{Y}_{\alpha\bullet}$ approximated by maps $g'_{\alpha i\beta}$ with $g'_{\alpha 0\beta} \in \mathcal{X}_{n-2}^{n-1}$ and $g'_{\alpha i\beta} \in \mathcal{X}_{n-2i}^{n-1}$ for $i \geq 1$. In addition, for each α and β , the square*

$$\begin{array}{ccc} \bar{X}'_{\alpha 0\beta} & \xrightarrow{g'_{\alpha 0\beta}} & \bar{Y}'_{\alpha 0\beta} \\ \downarrow & & \downarrow \\ X & \xrightarrow{f} & Y \end{array} \quad (3.8)$$

- (2s) *satisfies the strong factorisation condition.*
 (2m) *satisfies the moderate factorisation condition with $\ell \in \mathcal{X}_{n-2}^{n-1}$.*
 (2w) *satisfies the weak factorisation condition, and we assume that every map in $\bigcup_{n \geq 0} \mathcal{X}(n)$ induces injections on homology in all degrees.*

Remark 3.9 Our convention from the beginning of this section implies that the condition $f \in \mathcal{X}(n)$ is vacuous when $n < 0$, so there is no condition on $f'_{i\alpha}$ or $g'_{\alpha i\beta}$ for $i > \frac{n}{2}$.

Remark 3.10 There is an obvious generalisation of this theorem, in which one takes arbitrarily many resolutions and approximations of a given $f \in \mathcal{X}(n)$, before verifying the strong/moderate/weak factorisation condition. The number of iterated resolutions and approximations is permitted to depend on f . The proof of this generalisation is an immediate extension of the proof of Theorem 3.8 given below.

Proof of Theorem 3.8. The proof is by induction on n . First note that when $n = 0, 1$ the claim is just that each $f \in \mathcal{X}(n)$ induces a surjection on path-components, which is true since we have taken all spaces to be path-connected. So let $n \geq 2$ and assume by induction that the conclusion holds for smaller values of n . Let $f \in \mathcal{X}(n)$.

Spectral sequences. We have a resolution and approximation of f , so we may consider the square (3.2) for each $i \geq 0$. First replace it by an objectwise weakly-equivalent one in which all spaces have path-components that are open. (This is possible because, for any space Z with path-components Z_j , the natural map $\bigsqcup_j Z_j \rightarrow Z$ is a weak equivalence.) It now splits as the topological disjoint union of the squares

$$\begin{array}{ccc} X_{i\alpha} & \xrightarrow{f_{i\alpha}} & Y_{i\alpha} \\ p_{i\alpha} \downarrow & & \downarrow q_{i\alpha} \\ A_{i\alpha} & \xrightarrow{\phi_{i\alpha}} & B_{i\alpha} \end{array} \quad (3.9)$$

where $X_{i\alpha} = p_i^{-1}(A_{i\alpha})$, $B_{i\alpha} = \phi_i(A_{i\alpha})$, $Y_{i\alpha} = q_i^{-1}(B_{i\alpha})$ and the maps $-_{i\alpha}$ are the corresponding restrictions of the maps $-_i$. For each α , this square can be replaced by an objectwise homotopy-equivalent one in which $A_{i\alpha} = B_{i\alpha}$ and $\phi_{i\alpha}$ is the identity, and $p_{i\alpha}$, $q_{i\alpha}$ are still Serre fibrations. There is then, for each $i \geq 0$ and α , a relative Serre spectral sequence (cf. Remark 2 on page 351 of [Swi75] and Exercise 5.6 on page 178 of [McC01]) converging to the reduced homology of $Cf_{i\alpha}$, the mapping cone of $f_{i\alpha}$, and whose E^2 page can be identified as

$$E_{s,t}^2 \cong H_s(A_{i\alpha}; \tilde{H}_t(Cf'_{i\alpha})). \quad (3.10)$$

This is first quadrant and its r th differential has bidegree $(-r, r-1)$. Moreover, the edge homomorphism

$$\tilde{H}_t(Cf'_{i\alpha}) \cong E_{0,t}^2 \rightarrow E_{0,t}^\infty \hookrightarrow \tilde{H}_t(Cf_{i\alpha}) \quad (3.11)$$

is the map on reduced homology induced the two inclusions $X'_{i\alpha} = p_i^{-1}(a_{i\alpha}) \hookrightarrow p_i^{-1}(A_{i\alpha}) = X_{i\alpha}$ and $Y'_{i\alpha} = q_i^{-1}(\phi_i(a_{i\alpha})) \hookrightarrow q_i^{-1}(B_{i\alpha}) = Y_{i\alpha}$.

Secondly, the map of augmented semi-simplicial spaces $f_\bullet: X_\bullet \rightarrow Y_\bullet$ induces a spectral sequence converging to the shifted reduced homology \tilde{H}_{*+1} of the total homotopy cofibre (twice iterated mapping cone) of

$$\begin{array}{ccc} \|X_\bullet\| & \xrightarrow{\|f_\bullet\|} & \|Y_\bullet\| \\ \downarrow & & \downarrow \\ X & \xrightarrow{f} & Y \end{array} \quad (3.12)$$

and whose E^1 page can be identified as

$$E_{s,t}^1 \cong \tilde{H}_t(Cf_s). \quad (3.13)$$

This is slightly larger than first quadrant – it lives in $\{t \geq 0, s \geq -1\}$ – and its r th differential has bidegree $(-r, r-1)$. The first differential $E_{0,t}^1 \rightarrow E_{-1,t}^1$ can be identified with the map $\tilde{H}_t(Cf_0) \rightarrow \tilde{H}_t(Cf)$ on homology induced by the augmentation maps. See [Ran16, §2.3] (a construction is also given in [Pal13b, Appendix B]).

Strategy. Since each $X_{0\alpha} \subseteq X_0$ is a union of path-components (and similarly for $Y_{0\alpha} \subseteq Y_0$), the mapping cone Cf_0 decomposes as the wedge $\bigvee_\alpha Cf_{0\alpha}$. For each α we have a map $Cf'_{0\alpha} \rightarrow Cf_{0\alpha}$. Assuming one of the variants of condition (1), the strategy is to prove that the composite map $\bigvee_\alpha Cf'_{0\alpha} \rightarrow \bigvee_\alpha Cf_{0\alpha} = Cf_0 \rightarrow Cf$ is both surjective on homology up to degree $\lfloor \frac{n}{2} \rfloor$ and the zero map on reduced homology in this range. If instead we assume one of the variants of condition (2), then we also have a homology equivalence $Cg_\alpha \rightarrow Cf'_{0\alpha}$ for each α , as well as a decomposition $Cg_{\alpha 0} = \bigvee_\beta Cg_{\alpha 0\beta}$ and maps $Cg'_{\alpha 0\beta} \rightarrow Cg_{\alpha 0\beta}$. The strategy in this case is to prove that the composite map

$$\bigvee_{\alpha\beta} Cg'_{\alpha 0\beta} \rightarrow \bigvee_{\alpha\beta} Cg_{\alpha 0\beta} = \bigvee_\alpha Cg_{\alpha 0} \rightarrow \bigvee_\alpha Cg_\alpha \rightarrow \bigvee_\alpha Cf'_{0\alpha} \rightarrow \bigvee_\alpha Cf_{0\alpha} = Cf_0 \rightarrow Cf$$

is both surjective and zero on reduced homology up to degree $\lfloor \frac{n}{2} \rfloor$.

Surjectivity on homology. We first prove that each map $Cf'_{0\alpha} \rightarrow Cf_{0\alpha}$ is surjective on homology in the required range. By condition (1) and the inductive hypothesis we have that $h\text{conn}(f'_{0\alpha}) \geq \lfloor \frac{n}{2} \rfloor - 1$, in other words $\tilde{H}_t(Cf'_{0\alpha}) = 0$ for $t \leq \lfloor \frac{n}{2} \rfloor - 1$. Hence the E^2 page of the relative Serre spectral sequence (3.10) (for $i = 0$) vanishes for $t \leq \lfloor \frac{n}{2} \rfloor - 1$ and any $s \geq 0$. So in the slightly larger range $t \leq \lfloor \frac{n}{2} \rfloor$ the second map of (3.11) is the identity (there are no extension problems for this total degree) and therefore $\tilde{H}_t(Cf'_{0\alpha}) \rightarrow \tilde{H}_t(Cf_{0\alpha})$ is surjective.

Secondly, we show that $Cf_0 \rightarrow Cf$ is also surjective on homology in this range. By condition (1) and the inductive hypothesis we have that $h\text{conn}(f'_{i\alpha}) \geq \lfloor \frac{n}{2} \rfloor - i$ for $i \geq 1$, in other words $\tilde{H}_t(Cf'_{i\alpha}) = 0$ for $t \leq \lfloor \frac{n}{2} \rfloor - i$ and $i \geq 1$. Hence the E^2 page of the relative Serre spectral sequence (3.10) (for $i \geq 1$) vanishes for $t \leq \lfloor \frac{n}{2} \rfloor - i$ and any $s \geq 0$. Therefore in the limit we have

$$\tilde{H}_*(Cf_{i\alpha}) = 0 \quad \text{for } * \leq \lfloor \frac{n}{2} \rfloor - i \quad (\text{when } i \geq 1) \quad \text{and for } * \leq \lfloor \frac{n}{2} \rfloor - 1 \quad (\text{when } i = 0).$$

The E^1 page of the spectral sequence (3.13) is the direct sum over α of $\tilde{H}_t(Cf_{s\alpha})$, and so it has a trapezium of zeros as shown in Figure 3.1. Note that since $f_\bullet: X_\bullet \rightarrow Y_\bullet$ is an $\frac{n}{2}$ -resolution we have that \tilde{H}_{*+1} of the total homotopy cofibre of (3.12) is trivial for $*+1 \leq \lfloor \frac{n}{2} \rfloor$, so the spectral sequence (3.13) converges to zero in total degree $* \leq \lfloor \frac{n}{2} \rfloor - 1$. In particular for $t \leq \lfloor \frac{n}{2} \rfloor$ we have that $E_{-1,t}^\infty = 0$. Moreover, the second, third and later differentials that hit $E_{-1,t}^r$ all have trivial domain and so cannot kill it. Hence $E_{-1,t}^1$ must already be killed by the first differential – in other words, the first differential $\tilde{H}_t(Cf_0) \cong E_{0,t}^1 \rightarrow E_{-1,t}^1 \cong \tilde{H}_t(Cf)$ must be surjective.

If instead we assume condition (2), then all of the arguments above remain valid, and in addition we repeat these arguments, using the spectral sequences associated to the resolutions $g_{\alpha\bullet}: \bar{X}_{\alpha\bullet} \rightarrow \bar{Y}_{\alpha\bullet}$.

and the relative Serre spectral sequences associated to the corresponding approximations to prove that the maps $Cg'_{\alpha 0\beta} \rightarrow Cg_{\alpha 0\beta}$ and $Cg_{\alpha 0} \rightarrow Cg_{\alpha}$ are all surjective on homology up to degree $\lfloor \frac{n}{2} \rfloor$.

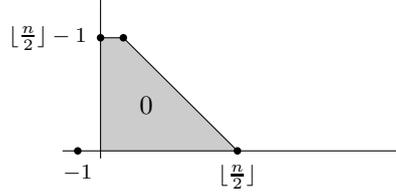


Figure 3.1 Zeros in the E^1 page of the spectral sequence (3.13).

Zero on homology. If we assume one of the variants of condition (1), we now want to show that, for each α , the composite map $Cf'_{0\alpha} \rightarrow Cf_{0\alpha} \hookrightarrow Cf_0 \rightarrow Cf$ is zero on homology up to degree $\lfloor \frac{n}{2} \rfloor$. This is the map on mapping cones induced by the square (3.7). If we assume one of the variants of condition (2), we instead want to show that, for each α and β , the composite map

$$Cg'_{\alpha 0\beta} \rightarrow Cg_{\alpha 0\beta} \hookrightarrow Cg_{\alpha 0} \rightarrow Cg_{\alpha} \rightarrow Cf'_{0\alpha} \rightarrow Cf_{0\alpha} \hookrightarrow Cf_0 \rightarrow Cf$$

is zero on homology up to degree $\lfloor \frac{n}{2} \rfloor$. This is the map on mapping cones induced by the square (3.8). So we just have to show that either (3.7) or (3.8) induces the zero map on the homology of the mapping cones (of the horizontal maps) in a range of degrees. In fact, this is what we will do under the moderate and strong factorisation conditions, but under the weak factorisation condition we will do something slightly different. We start with this case.

The weak factorisation condition. We first assume condition (1w), the weak factorisation condition and injectivity on homology of all maps in $\bigcup_{n \geq 0} \mathcal{X}(n)$. The square (3.7) induces a map of long exact sequences on homology:

$$\begin{array}{ccccccc} \cdots & \longrightarrow & \tilde{H}_t(Y'_{0\alpha}) & \xrightarrow{(**)} & \tilde{H}_t(Cf'_{0\alpha}) & \longrightarrow & \tilde{H}_{t-1}(X'_{0\alpha}) \xrightarrow{(f'_{0\alpha})_*} \tilde{H}_{t-1}(Y'_{0\alpha}) \longrightarrow \cdots \\ & & \downarrow & & \downarrow (*) & & \\ \cdots & \longrightarrow & \tilde{H}_t(X) & \xrightarrow{f_*} & \tilde{H}_t(Y) & \longrightarrow & \tilde{H}_t(Cf) \longrightarrow \cdots \end{array}$$

The triangle on the left-hand side comes from the factorisation assumed in the weak factorisation condition. It implies that the composition $(*) \circ (**)$ is zero. Since we have assumed that maps in $\bigcup_{n \geq 0} \mathcal{X}(n)$ all induce injective maps on homology in all degrees, the map $(f'_{0\alpha})_*$ in the diagram is injective for any t , and so by exactness the map $(**)$ is surjective for any t .⁵ In the range $t \leq \lfloor \frac{n}{2} \rfloor$, and after taking the direct sum of the top line over α , the map $(*)$ is surjective by what we proved above. So we have a map $(*) \circ (**)$ with target $\tilde{H}_t(Cf)$ which is both surjective and zero in the required range, which finishes the inductive step of the proof.

If we assume condition (2w), then we apply exactly the same argument to the map of long exact sequences induced by the square (3.8) instead.

The moderate and strong factorisation conditions. We first assume either (1m) or (1s) and show that the map $Cf'_{0\alpha} \rightarrow Cf$ is zero on reduced homology up to degree $\lfloor \frac{n}{2} \rfloor$. The triangle decomposition (3.5) of (3.7) induces a decomposition of this map on homology as follows:

⁵ It would not be enough to invoke the inductive hypothesis here, since it only tells us that the map $(f'_{0\alpha})_*$ in the diagram is injective for $t \leq \lfloor \frac{n}{2} \rfloor - 1$, and we need the range $t \leq \lfloor \frac{n}{2} \rfloor$.

$$\begin{array}{ccccccc}
 & & \cdots & \longrightarrow & \tilde{H}_t(Cf'_{0\alpha}) & \longrightarrow & \tilde{H}_{t-1}(X'_{0\alpha}) & \longrightarrow & \cdots \\
 & & & & \downarrow & & \swarrow & & \\
 \cdots & \longrightarrow & \tilde{H}_t(Y) & \longrightarrow & \tilde{H}_t(Cf) & \longrightarrow & \cdots & &
 \end{array}$$

where the diagonal map is

$$\tilde{H}_{t-1}(X'_{0\alpha}) \xleftarrow{\text{K\"unneth}} \tilde{H}_t(S^1 \times X'_{0\alpha}) \xrightarrow{(HJ)_*} \tilde{H}_t(Y).$$

This is proved in [Pal13b, Appendix A], and it also follows from [CR17, Lemma 7.5], which in fact gives a space-level decomposition. Putting this together with (3.6) we have a commutative diagram

$$\begin{array}{ccccc}
 \tilde{H}_{t-1}(Z) & \xrightarrow{\ell_*} & \tilde{H}_{t-1}(X'_{0\alpha}) & \longleftarrow & \tilde{H}_t(Cf'_{0\alpha}) \\
 \downarrow & & \downarrow & & \downarrow (\dagger) \\
 \tilde{H}_t(S^1 \times Z) & \longrightarrow & \tilde{H}_t(S^1 \times X'_{0\alpha}) & & \\
 \downarrow & & \downarrow (HJ)_* & & \downarrow \\
 \tilde{H}_t(X) & \xrightarrow{f_*} & \tilde{H}_t(Y) & \longrightarrow & \tilde{H}_t(Cf) \\
 \lrcorner & & \lrcorner & & \lrcorner \\
 & & 0 & &
 \end{array}$$

with either $\ell \in \mathcal{X}_{n-2}^{n-1}$ (if we assume (1m)) or $\ell = \text{id}$ (if we assume (1s), see Remark 3.7). In either case we know that the induced map ℓ_* in the diagram is surjective for $t \leq \lfloor \frac{n}{2} \rfloor$ (by the inductive hypothesis if we assume (1m)). The bottom two horizontal maps are consecutive maps in a long exact sequence, so their composition is zero. A diagram chase therefore shows that the map (\dagger) is zero for $t \leq \lfloor \frac{n}{2} \rfloor$, as required.

If we assume (2m) or (2s), then we use exactly the same argument, applied instead to the triangle decomposition (3.5) of (3.8). \square

4. Fibre bundle and fibration lemmas

4.1. Smooth mapping spaces. In this section we prove some technical lemmas that certain maps between smooth mapping spaces are fibre bundles. First we discuss briefly the topology that we use for our smooth mapping spaces, and collect some basic facts that will be useful later.

For smooth⁶ manifolds L and N , we will always use the *strong C^∞ topology* on the space $C^\infty(L, N)$ of smooth maps $L \rightarrow N$, unless explicitly stated otherwise. This topology is also sometimes known as the *Whitney C^∞ topology*.

Whenever L is compact, this coincides with the *weak C^∞ topology*, also known as the *compact-open C^∞ topology*, but when L is non-compact it is strictly finer than the weak C^∞ topology.⁷ In fact, the weak C^∞ topology is metrisable and therefore paracompact, whereas the strong C^∞ topology is not even first-countable when L is non-compact and $\dim(N) > 0$. On the other hand, the strong C^∞ topology will be useful for us since various properties of smooth maps, notably the property of being an embedding, are open conditions in this topology, and moreover the strong C^∞ topology makes the mapping space into a Baire space, so the Thom transversality theorem applies. We refer

⁶ By “smooth” we always mean C^∞ -smooth. Also, manifolds in this section have empty boundary unless explicitly stated otherwise.

⁷ On the other hand, even when L is non-compact, the strong and weak C^∞ topologies do coincide on the subset $C_{\text{pr}}^\infty(L, N)$ of all proper maps $L \rightarrow N$. In particular this means that they coincide on the diffeomorphism group $\text{Diff}(N)$ for any manifold N . In practice, we will almost exclusively work with smooth mapping spaces with compact domain and diffeomorphism groups, so the distinction between strong and weak C^∞ topologies does not arise.

to [Mat69, §2], [GG73, §II.3] and [Hir76, §2.1] for the definitions and further discussion of these topologies.

In addition to the facts mentioned above, we record three facts more formally, for future reference.

Fact 4.1 *For compact L , the space $C^\infty(L, N)$ is locally contractible. Its open subspace $\text{Emb}(L, N)$ of smooth embeddings is therefore also locally contractible, and in particular $\text{Diff}(L) = \text{Emb}(L, L)$ is locally contractible.*

For non-compact manifolds N , the diffeomorphism group $\text{Diff}(N)$ is not even locally path-connected, but its subgroup $\text{Diff}_c(N)$ of compactly-supported diffeomorphisms is locally contractible.

Proof. For the first statement, see for example [Cer61, Corollary of Proposition 4', page 281]. For the non-local-path-connectedness of $\text{Diff}(N)$ when N is non-compact (but σ -compact), see [GZ84] or Theorem 4 of [Ban+11], which states that for such N the full diffeomorphism group $\text{Diff}(N)$ is locally homeomorphic to the infinite box power $\square^\omega l_2$, which is not locally path-connected. Theorem 4 of [Ban+11] also states that the subgroup $\text{Diff}_c(N)$ is locally homeomorphic to $l_2 \times \mathbb{R}^\infty \cong \square^\omega l_2$, which is locally contractible. \square

Fact 4.2 *The function*

$$C^\infty(L, M) \times C^\infty(M, N) \longrightarrow C^\infty(L, N)$$

given by composition of smooth maps is in general discontinuous — in fact it always fails to be continuous if L is non-compact — but it becomes continuous when it is restricted to the subset $C_{\text{pr}}^\infty(L, M) \times C^\infty(M, N)$ of the domain, where C_{pr}^∞ denotes the subspace of proper smooth maps.

This is originally due to [Mat69, Proposition 1 and Remark 2 on page 259]. See also Proposition II.3.9 and the remark following it in [GG73]. As a consequence, the right action of $\text{Diff}(L)$ on the embedding space $\text{Emb}(L, N)$ is always continuous, whereas we have to assume that L is compact in order for the left action of $\text{Diff}(N)$ on this space to be continuous.

Fact 4.3 *If M is a submanifold of N , then the continuous injection*

$$C_{\text{pr}}^\infty(L, M) \longrightarrow C^\infty(L, N)$$

given by post-composition with the inclusion is a topological embedding, i.e. a homeomorphism onto its image. Thus, if $e: L \hookrightarrow N$ is a smooth embedding, the map

$$e \circ -: \text{Diff}(L) \longrightarrow \text{Emb}(L, N)$$

is a topological embedding.

The first statement follows from Remark 1 on page 259 of [Mat69]. To deduce the second statement, set $M = e(L)$ and restrict the domain and codomain to embedding spaces, to obtain a topological embedding $\text{Emb}_{\text{pr}}(L, e(L)) \hookrightarrow \text{Emb}(L, N)$. Now note that a proper embedding between manifolds of the same dimension is a diffeomorphism, so $\text{Diff}(L, e(L)) = \text{Emb}_{\text{pr}}(L, e(L))$, and pre-compose with the homeomorphism $e \circ -: \text{Diff}(L) \rightarrow \text{Diff}(L, e(L))$.

Assumption 4.4 For the rest of this section, unless otherwise specified, G and H denote topological groups, L and N denote manifolds without boundary, with L assumed to be compact, such that $\dim(L) < \dim(N)$.

4.2. A fibre bundle criterion. Let G be a topological group with a left-action on a space X , i.e. a group homomorphism $G \rightarrow \text{Homeo}(X)$ such that the adjoint $a: G \times X \rightarrow X$ is continuous.⁸

Definition 4.5 We say that X is *G -locally retractile* with respect to this action (equivalently, that the action $G \curvearrowright X$ admits local sections) if every $x \in X$ has an open neighbourhood $V_x \subseteq X$ and

⁸ Note that we do not need to specify a topology on the group of self-homeomorphisms of X , since the continuity condition is on the action map $G \times X \rightarrow X$ and not on the group homomorphism $G \rightarrow \text{Homeo}(X)$.

a continuous map $\gamma_x : V_x \rightarrow G$ sending x to the identity such that $\gamma_x(y) \cdot x = y$ for all $y \in V_x$, in other words the composition

$$V_x \xrightarrow{\gamma_x} G \xrightarrow{- \cdot x} X$$

is the inclusion. Equivalently, each orbit map $G \times \{x\} \hookrightarrow G \times X \xrightarrow{a} X$ admits a (pointed) section on some open neighbourhood of $x \in X$.

The notion of G -locally retractile spaces is also used in [CR17]. In the terminology of [Pal60], one says that X admits local cross-sections (with respect to the action of G).

Immediately from the definitions, we note:

Lemma 4.6 *Let $H \leq G \leq K$ be topological groups and let X be a locally retractile G -space.*

- (i) *If H is open in G , then the action of H on X is locally retractile.*
- (ii) *If the G -action on X extends to a K -action, then this action is also locally retractile.*
- (iii) *If $A \subseteq X$ is an open, G -invariant subspace, then the action of G on A is locally retractile.*

In particular, if G is locally path-connected, then the action of G_0 on X is locally retractile, where G_0 is the path-component of G containing the identity.

The following lemma is very useful for checking that a given map is a fibre bundle.

Proposition 4.7 ([Pal60, Theorem A]) *Let $f : X \rightarrow Y$ be a G -equivariant continuous map and assume that the space Y is G -locally retractile. Then f is a fibre bundle.*

Proof. Let $y \in Y$ and take $\gamma_y : V_y \rightarrow G$ as in Definition 4.5. Then the map

$$(x, v) \mapsto \gamma_y(v) \cdot x : f^{-1}(y) \times V_y \longrightarrow f^{-1}(V_y)$$

is a local trivialisation of f over V_y , with inverse given by

$$x \mapsto (\gamma_y(f(x))^{-1} \cdot x, f(x)) : f^{-1}(V_y) \longrightarrow f^{-1}(y) \times V_y. \quad \square$$

In the special case where f is of the form $X \rightarrow X/H$ for a right action of another group H on X , we have a stronger conclusion, as remarked in [Pal60] on page 307.

Proposition 4.8 *Let X be a space with a left G -action and a right H -action, which commute. Assume that the H -action is free, and moreover that for each $x \in X$ the map $x \cdot - : H \rightarrow X$ is a topological embedding. Assume that the induced left G -action on the quotient space X/H is locally retractile. Then the quotient map $q : X \rightarrow X/H$ is a principal H -bundle.*

Proof. For a point $y = xH \in X/H$, the local trivialisation constructed in the proof above is

$$(x \cdot h, v) \mapsto \gamma_y(v) \cdot x \cdot h : xH \times V_y \longrightarrow q^{-1}(V_y)$$

and it is clearly H -equivariant, where we let H act on xH and on $q^{-1}(V_y)$ by the restriction of its action on X , and act trivially on V_y . By hypothesis, the map $h \mapsto x \cdot h : H \rightarrow xH \subseteq X$ is a homeomorphism, so we may compose the trivialisation above with the homeomorphism $(h, v) \mapsto (x \cdot h, v) : H \times V_y \rightarrow xH \times V_y$ to obtain an H -equivariant local trivialisation

$$(h, v) \mapsto \gamma_y(v) \cdot x \cdot h : H \times V_y \longrightarrow q^{-1}(V_y).$$

This is now a local trivialisation of q over V_y as a principal H -bundle. □

For example, we note that for any subgroup H of a topological group G , we may take $X = G$ with H acting by right-multiplication. In this case the map $H \rightarrow G$ given by $h \mapsto gh$ for fixed $g \in G$ is always a topological embedding (its inverse is given by $k \mapsto g^{-1}k$), so the proposition above says in this case that if G/H is G -locally retractile, then $G \rightarrow G/H$ is a principal H -bundle. Subgroups H having the property that $G \rightarrow G/H$ is a principal H -bundle are sometimes called *admissible*, so one may rephrase this as saying that H is admissible if G/H is G -locally retractile.

4.3. Manifolds without boundary. A very useful setting where this criterion applies is for embedding spaces between smooth manifolds. Let $\text{Diff}_c(N)$ denote the topological group of compactly-supported self-diffeomorphisms of N , i.e. diffeomorphisms $\theta: N \rightarrow N$ such that $\{x \in N \mid \theta(x) \neq x\}$ is relatively compact in N .

By Fact 4.2, the action of $\text{Diff}_c(N)$ on $\text{Emb}(L, N)$ is continuous.

Proposition 4.9 ([Pal60, Theorem B]⁹) *The space $\text{Emb}(L, N)$ is $\text{Diff}_c(N)$ -locally retractile.*

There is also a 14-line proof in [Lim64]. It is also proved in [Cer61], in a much more general setting for manifolds with corners, which we will discuss in §4.4 below. We will also give a self-contained proof in §4.5 below, in the course of proving Proposition 4.15, which is a variant of this result for quotients of embedding spaces. (Our proof of Proposition 4.15 will use the ideas of [Lim64].)

We note that a direct corollary of Proposition 4.9 is the isotopy extension theorem.

Theorem 4.10 *Suppose we are given a smooth isotopy of embeddings from L into N , i.e. a path $e: [0, 1] \rightarrow \text{Emb}(L, N)$. Then there is a path $\phi: [0, 1] \rightarrow \text{Diff}_c(N)$ of compactly-supported diffeomorphisms such that $\phi(0)$ is the identity and $e(t) = \phi(t) \circ e(0)$ for all $t \in [0, 1]$.*

Proof. The map $- \circ e(0): \text{Diff}_c(N) \rightarrow \text{Emb}(L, N)$ is $\text{Diff}_c(N)$ -equivariant, and by Proposition 4.9 the embedding space $\text{Emb}(L, N)$ is $\text{Diff}_c(N)$ -locally retractile, so Proposition 4.7 implies that the map is a fibre bundle and hence a Serre fibration. \square

Remark 4.11 The fact that the map $- \circ e(0): \text{Diff}_c(N) \rightarrow \text{Emb}(L, N)$ is a Serre fibration also implies parametrised versions of the isotopy extension theorem, for smooth isotopies of embeddings parametrised by CW complexes. In fact, since L is compact, the space $\text{Emb}(L, N)$ is paracompact, as noted at the beginning of §4.1, so this implies that $- \circ e(0)$ is in fact a Hurewicz fibration. Thus we also obtain versions of the isotopy extension theorem parametrised by an arbitrary space.

In the proof of Theorem A in §5 below we will not use Proposition 4.9 itself, but rather two different extensions of it, one for manifolds with non-empty boundary (which is contained in the work of Cerf) and one for quotients of embedding spaces by open subgroups of $\text{Diff}(L)$ (which we prove directly). These are discussed in the next two subsections.

4.4. Manifolds with boundary. For the proof of Theorem A in §5 we will need a version of Proposition 4.9 for manifolds with boundary. In fact, this result extends to a very general setting for manifolds with corners, as shown in the work of Cerf [Cer61]. We first state the special case that we will actually use, and then discuss how to deduce it from [Cer61].

Let L and N be manifolds with boundary decomposed as

$$\partial L = \partial_1 L \sqcup \partial_2 L \quad \partial N = \partial_1 N \sqcup \partial_2 N$$

and assume that L is compact. Let $\text{Emb}_{12}(L, N)$ be the space, equipped with the (weak = strong) C^∞ topology, of all smooth embeddings $L \hookrightarrow N$ taking $\partial_1 L$ to $\partial_1 N$, $\partial_2 L$ to $\partial_2 N$ and $\text{int}(L)$ to $\text{int}(N)$. Any diffeomorphism of N that is isotopic to the identity must preserve the decomposition of ∂N into $\partial_1 N$ and $\partial_2 N$, so there is a well-defined action of $\text{Diff}_c(N)_0$ on $\text{Emb}_{12}(L, N)$. We will see in the discussion of Cerf's results below that this action is continuous.

Proposition 4.12 *With respect to this action, $\text{Emb}_{12}(L, N)$ is $\text{Diff}_c(N)_0$ -locally retractile.*

Now let L and N be two smooth manifolds with corners, where L is assumed to be compact, and define $\text{Emb}(L, N)$ to be the space of smooth embeddings of L into N with fixed ‘‘incidence relations’’ (see the next paragraph or [Cer61, II.1.1.1]). Everything will be given the strong C^∞ topology. Choose an embedding $f \in \text{Emb}(L, N)$ and an open neighbourhood U of $f(L)$ in N . Let $\text{Diff}_U(N)$ be the group of diffeomorphisms of N which restrict to the identity on $N \setminus U$ and let

$$\text{Iso}_U(N) \subseteq C^\infty(N \times [0, 1], N)$$

⁹ In fact, Theorem B of [Pal60] says that the action of the path-component of the identity $\text{Diff}_c(N)_0$ on $\text{Emb}(L, N)$ is locally retractile, but this is equivalent to the statement of Proposition 4.9 by Lemma 4.6.

be the subspace of maps f such that $f(-, t) \in \text{Diff}_U(N)$ for all t and $f(-, 0) = \text{id}$. It turns out that this is a topological group under pointwise composition and acts continuously on $\text{Emb}(L, N)$ by taking the diffeomorphism at the endpoint of the path and composing with the embedding.

Before stating Cerf's analogue of Proposition 4.9, we justify and explain the claim at the end of the last paragraph. First, the space $\text{Iso}_U(N)$ is a topological group with respect to pointwise composition by [Cer61, II.1.5.2]. Second, we need to know that composing an embedding $L \hookrightarrow N$ with a diffeomorphism in $\text{Diff}_U(N)$ does not change its incidence relations. To explain this we briefly recall some notions from [Cer61, II.1.1.1]. Each point in N has an *index*, which is the unique integer k such that N is locally homeomorphic to $\mathbb{R}^k \times [0, \infty)^{n-k}$ at that point. Writing N^k for the subspace of points of index at most k , a *face* of N of index k is the closure in N of a path-component of $N^k \setminus N^{k-1}$. An *incidence relation* is then a choice of a face of N for each point in L . A diffeomorphism of N induces a permutation of the set of faces of N , and it preserves the incidence relations of any embedding into N if and only if this permutation is the identity. It is easy to see that the induced permutation is a locally-constant invariant of diffeomorphisms of N , and so any diffeomorphism in the path-component of the identity sends every face to itself. Now, an element of the group $\text{Iso}_U(N)$ is a path in $\text{Diff}(N)$ starting at the identity, so the diffeomorphism at its endpoint sends every face of N to itself, and therefore preserves the incidence relations of any embedding into N . Thus the group action map $\text{Iso}_U(N) \times \text{Emb}(L, N) \rightarrow \text{Emb}(L, N)$ is well-defined. Finally, we need to know that this map is continuous. It is given by $(a, b) \mapsto a \circ i \circ b$, where $i: N \hookrightarrow N \times [0, 1]$ takes x to $(x, 1)$. This is continuous by [Cer61, Proposition 5, page 281] since i is proper and L is compact.

Theorem 4.13 ([Cer61, Théorème 5, page 293]) *The action of $\text{Iso}_U(N)$ on $\text{Emb}(L, N)$ admits a local section at $f \in \text{Emb}(L, N)$.*

This implies the analogue of Proposition 4.9 for manifolds with corners.

Corollary 4.14 *The action of $\text{Diff}_c(N)_0$ on $\text{Emb}(L, N)$ is locally retractile.*

Proof of the corollary. To see this, given a point $f \in \text{Emb}(L, N)$, choose a relatively compact open neighbourhood U of $f(L)$ in N . The action of $\text{Iso}_U(N)$ on $\text{Emb}(L, N)$ factors through the endpoint map $\text{Iso}_U(N) \rightarrow \text{Diff}_c(N)_0$ so a local section at f for the action of $\text{Iso}_U(N)$ induces a local section at f for the action of $\text{Diff}_c(N)_0$.¹⁰ \square

Proof of Proposition 4.12 from the corollary. The setting of Proposition 4.12 is a special case of the setting of Cerf. Note that the faces of a manifold with boundary (but no higher-codimension corners) are precisely its boundary-components, together with its interior. The condition imposed in the definition of $\text{Emb}_{12}(L, N)$ is therefore a union of incidence relations in the sense of Cerf, and so $\text{Emb}_{12}(L, N)$ splits as a topological disjoint union of $\text{Emb}_{\mathcal{I}}(L, N)$ for various different incidence relations \mathcal{I} .¹¹ The action of $\text{Diff}_c(N)_0$ on $\text{Emb}_{12}(L, N)$ preserves this decomposition, and its action on each piece is locally retractile by Corollary 4.14, so its action on the whole space $\text{Emb}_{12}(L, N)$ is also locally retractile. \square

4.5. Quotients of embedding spaces. Another version of Proposition 4.9 that we will need is for quotients of embedding spaces by groups of diffeomorphisms, in the following sense. We now return to the setting of Assumption 4.4, in particular all manifolds have empty boundary and L is compact with $\dim(L) < \dim(N)$. Let G be any open subgroup of $\text{Diff}(L)$.

Proposition 4.15 *The orbit space $\text{Emb}(L, N)/G$ is $\text{Diff}_c(N)$ -locally retractile.*

Corollary 4.16 *The quotient map $\text{Emb}(L, N) \rightarrow \text{Emb}(L, N)/G$ is a principal G -bundle.*

¹⁰ An important point is that although the adjoint $[0, 1] \rightarrow C^\infty(N, N)$ of a smooth map $g: N \times [0, 1] \rightarrow N$ need not be continuous in general for non-compact N , it is continuous if g is a compactly-supported diffeotopy (cf. [Hal95, Lemma 1.12]). This is needed to see that the endpoint map $\text{Iso}_U(N) \rightarrow \text{Diff}_c(N)$ lands in $\text{Diff}_c(N)_0$.

¹¹ If $\partial_1 N$ and $\partial_2 N$ are both connected, then there is just one incidence relation in the disjoint union. In general, the number of incidence relations in the disjoint union is $\leq n_1^{\ell_1} n_2^{\ell_2}$, where n_i is the number of components of $\partial_i N$ and ℓ_i is the number of components of $\partial_i L$.

Proof of the corollary. This follows directly from Fact 4.3 and Propositions 4.8 and 4.15. \square

Remark 4.17 In the special case when $G = \text{Diff}(L)$, Corollary 4.16 was first proved in [BF81], and then generalised, by removing the assumption that L is compact, in [Mic80a, Theorem 10.14]. See also [Mic80b, Theorem 13.14] and [KM97, Theorem 44.1] for proofs of this result in the non-compact case. It seems likely that Proposition 4.15, and therefore also Corollary 4.16 (for arbitrary open subgroups $G \leq \text{Diff}(L)$), is also true for non-compact L , but we have not pursued this greater generality since we will only need the result in the case when L is compact.

Proof of Propositions 4.9 and 4.15. Denote the projection map by

$$q: \text{Emb}(L, N) \longrightarrow \text{Emb}(L, N)/G.$$

Fix $e \in \text{Emb}(L, N)$. We will construct a local section for the action of $\text{Diff}_c(N)$ on $\text{Emb}(L, N)/G$ at the point $q(e)$ in two steps, as a composition of two maps b and θ .¹²

Step 1. First choose a tubular neighbourhood for e , namely an embedding $t_e: \nu_e \hookrightarrow N$ such that $t_e \circ o_e = e$, where $\pi_e: \nu_e \rightarrow L$ denotes the normal bundle of e and $o_e: L \rightarrow \nu_e$ denotes its zero section. Note that $V = t_e(\nu_e)$ is an open neighbourhood of $e(L)$ in N , so $\text{Emb}(L, V)$ is an open neighbourhood of e in $\text{Emb}(L, N)$ (cf. Fact 4.3). The map

$$\Phi_e = \pi_e \circ t_e^{-1} \circ -: \text{Emb}(L, V) \longrightarrow C^\infty(L, L)$$

is continuous by Fact 4.2. Define $\mathcal{W}_e = \Phi_e^{-1}(\text{id})$ and $\mathcal{U}_e = \Phi_e^{-1}(G)$. Note that $e \in \mathcal{W}_e \subseteq \mathcal{U}_e$ and that \mathcal{U}_e is open in $\text{Emb}(L, N)$ since we assumed that G is open in $\text{Diff}(L)$. Alternative descriptions of these two subsets are:

$$\begin{aligned} \mathcal{W}_e &= \{t_e \circ s \mid s \text{ is a smooth section of } \pi_e\} \\ \mathcal{U}_e &= \{t_e \circ s \circ g \mid s \text{ is a smooth section of } \pi_e \text{ and } g \in G\}. \end{aligned}$$

Note that $q^{-1}(q(\mathcal{W}_e))$ is the G -orbit of \mathcal{W}_e , which is \mathcal{U}_e . Hence $q(\mathcal{W}_e)$ is an open neighbourhood of $q(e)$ in the quotient space $\text{Emb}(L, N)/G$. Also note that $q|_{\mathcal{W}_e}$ is *injective*, since sections are equal if and only if they have the same image.

Sublemma 4.18 *The continuous injection $q|_{\mathcal{W}_e}$ is a homeomorphism onto its image.*

Proof of the sublemma. Let U be an open subset of $\text{Emb}(L, N)$. We need to show that $q(U \cap \mathcal{W}_e)$ is open in $q(\mathcal{W}_e)$. Since $q(\mathcal{W}_e)$ is open in $\text{Emb}(L, N)/G$, this is equivalent to showing that $q(U \cap \mathcal{W}_e)$ is open in $\text{Emb}(L, N)/G$, i.e. that $q^{-1}(q(U \cap \mathcal{W}_e))$ is open in $\text{Emb}(L, N)$. Define

$$\Psi_e: \mathcal{U}_e \longrightarrow \mathcal{W}_e$$

by $f \mapsto f \circ \Phi_e(f)^{-1}$. This is continuous by Fact 4.2 and the fact that inversion is continuous for diffeomorphism groups. Thus $\Psi_e^{-1}(U \cap \mathcal{W}_e)$ is open in \mathcal{U}_e , and hence in $\text{Emb}(L, N)$. Now we note that $\Psi_e^{-1}(U \cap \mathcal{W}_e)$ is precisely the G -orbit of $U \cap \mathcal{W}_e$, which is $q^{-1}(q(U \cap \mathcal{W}_e))$. (sublemma) \square

Denote the inverse of $q|_{\mathcal{W}_e}$ by

$$b: q(\mathcal{W}_e) \longrightarrow \mathcal{W}_e.$$

By the sublemma, it is continuous. Also, note that $b(q(e)) = e$.

Step 2. Now (by [Whi36]) we may choose a proper embedding

$$\iota: N \hookrightarrow \mathbb{R}^k$$

for some k . We also choose a tubular neighbourhood for ι , namely an embedding $t: \nu_\iota \hookrightarrow \mathbb{R}^k$ such that $t \circ o_\iota = \iota$, where $\pi_\iota: \nu_\iota \rightarrow N$ is the normal bundle of ι and $o_\iota: N \rightarrow \nu_\iota$ is its zero section.

We will choose a tubular neighbourhood for the composition $\iota \circ e = \iota e: L \hookrightarrow \mathbb{R}^k$ more carefully. There is an embedding of bundles

¹² At the end we mention how to modify this to obtain instead a local section for the action of $\text{Diff}_c(N)$ on $\text{Emb}(L, N)$ at the point e . Essentially, one discards the first step and uses θ directly.

$$\begin{array}{ccc}
 \nu_{\iota e} & \xhookrightarrow{u} & T\mathbb{R}^k \\
 \pi_{\nu_{\iota e}} \downarrow & & \downarrow \\
 L & \xhookrightarrow{\iota e} & \mathbb{R}^k
 \end{array}$$

so that $u(\nu_{\iota e})$ is the orthogonal complement of $T(\iota e(L))$ in $T\mathbb{R}^k|_{\iota e(L)}$ with respect to the standard Riemannian metric on \mathbb{R}^k . Write $D_r = D_r(\nu_{\iota e})$ for the subbundle of $\nu_{\iota e}$ consisting of vectors of norm $\leq r$, using the norm inherited via this embedding. Since L is compact, we may choose $r > 0$ sufficiently small so that the exponential map for $T\mathbb{R}^k$ restricts to an embedding

$$v: D_r \hookrightarrow \mathbb{R}^k$$

such that $vo_{\iota e} = \iota e$, where $o_{\iota e}: L \rightarrow D_r$ is the zero section of

$$\hat{\pi} = \pi_{\nu_{\iota e}}|_{D_r}: D_r \rightarrow L.$$

We note that:

- (i) The restriction of v to each fibre of $\hat{\pi}: D_r \rightarrow L$ is an isometry.
- (ii) Moreover, we have $v(D_r) = \{x \in \mathbb{R}^k \mid \exists y \in L \text{ such that } |\iota e(y) - x| \leq r\}$.

Now we decrease $r > 0$ if necessary so that we also have

- (iii) $v(D_r) \subseteq t(\nu_{\iota})$.

(Again, this is possible since L is compact.) Define

$$\mathcal{V}_e = \{f \in \text{Emb}(L, N) \mid \forall x \in L \text{ we have } |\iota f(x) - \iota e(x)| < \frac{r}{2}\}$$

and note that this is a $\text{Diff}(L)$ -equivariant open subset of $\text{Emb}(L, N)$. Also choose a smooth map $\lambda: [0, \infty) \rightarrow [0, 1]$ such that $\lambda(t) = 1$ for $t \leq \frac{r}{8}$ and $\lambda(t) = 0$ for $t \geq \frac{r}{4}$.

For any $f \in \mathcal{V}_e$ we now attempt to define a map $\theta(f): N \rightarrow N$ as follows.

- (1) If $x \in N \setminus \iota^{-1}v(D_{r/4})$, we set $\theta(f)(x) = x$.
- (2) If $x \in \iota^{-1}v(D_{r/2})$, we set $\theta(f)(x) = \pi_{\iota} t^{-1} \iota_f(x)$, where

$$\iota_f(x) = \iota(x) + \lambda(|\bar{x}|)(\iota f \hat{\pi}(\bar{x}) - \iota e \hat{\pi}(\bar{x})),$$

$$\text{and } \bar{x} = v^{-1} \iota(x) \in D_{r/2}.$$

To check that this is well-defined and smooth, it is enough to check that

- (a) $\iota_f(x)$ is in the image of t in case (2),
- (b) the two cases agree for $x \in \iota^{-1}v(D_{r/2}) \setminus D_{r/4}$.

The verification of (b) follows from the fact that $\lambda(t) = 0$ for $t \geq \frac{r}{4}$. For condition (a), suppose that $x \in \iota^{-1}v(D_{r/2})$ and let $\bar{x} = v^{-1} \iota(x) \in D_{r/2}$. Then

$$|\iota_f(x) - \iota e \hat{\pi}(\bar{x})| = |\iota_f(x) - \iota(x)| + |\iota(x) - \iota e \hat{\pi}(\bar{x})|.$$

For the first summand, we have

$$|\iota_f(x) - \iota(x)| \leq |\iota f \hat{\pi}(\bar{x}) - \iota e \hat{\pi}(\bar{x})| < \frac{r}{2}$$

since $f \in \mathcal{V}_e$. For the second summand, we have

$$\begin{aligned}
 |\iota(x) - \iota e \hat{\pi}(\bar{x})| &= |v(\bar{x}) - v o_{\nu_{\iota e}} \hat{\pi}(\bar{x})| \\
 &= |\bar{x} - o_{\nu_{\iota e}} \hat{\pi}(\bar{x})| \\
 &\leq \frac{r}{2}
 \end{aligned}$$

by property (i) and since $\bar{x} \in D_{r/2}$. Hence $\iota_f(x) \in v(D_r) \subseteq t(\nu_{\iota})$ by properties (ii) and (iii). This completes the verification of (a), so $\theta(f): N \rightarrow N$ is a well-defined, smooth map. Note also that it

is supported in $\iota^{-1}v(D_{r/2}) \subseteq N$, which is compact since L (and therefore $D_{r/2}$) is compact and ι is a *proper* embedding. So we have a function

$$\theta: \mathcal{V}_e \longrightarrow C_c^\infty(N, N),$$

and it is not hard to see from Fact 4.2, plus the fact that pointwise addition and multiplication of smooth maps into \mathbb{R}^k are continuous, that θ is continuous.

Step 3. (Putting together b and θ .) Recall that \mathcal{V}_e is a G -equivariant open subset of $\text{Emb}(L, N)$, so $q(\mathcal{V}_e)$ is an open subset of $\text{Emb}(L, N)/G$. Therefore, the intersection $q(\mathcal{V}_e) \cap q(\mathcal{W}_e)$ is an open neighbourhood of $q(e)$ in $\text{Emb}(L, N)/G$. Recall the continuous inverse $b: q(\mathcal{W}_e) \rightarrow \mathcal{W}_e$ of $q|_{\mathcal{W}_e}$ from Step 1. Note that

$$b(q(\mathcal{V}_e) \cap q(\mathcal{W}_e)) \subseteq \mathcal{W}_e \cap q^{-1}(q(\mathcal{V}_e)) = \mathcal{W}_e \cap \mathcal{V}_e \subseteq \mathcal{V}_e.$$

We may therefore define

$$\bar{\theta} = \theta \circ b: q(\mathcal{V}_e) \cap q(\mathcal{W}_e) \longrightarrow C_c^\infty(N, N)$$

and observe that $\bar{\theta}(q(e)) = \theta(e) = \text{id}$. Since $\text{Diff}_c(N)$ is an open neighbourhood of the identity in $C_c^\infty(N, N)$, its preimage

$$\mathcal{Y}_e = \bar{\theta}^{-1}(\text{Diff}_c(N))$$

is an open neighbourhood of $q(e)$ in $\text{Emb}(L, N)/G$ and we have a continuous map

$$\bar{\theta}: \mathcal{Y}_e \longrightarrow \text{Diff}_c(N).$$

It now remains to check that $q(\bar{\theta}(q(f)) \circ e) = q(f)$ for all $q(f) \in \mathcal{Y}_e$. We may as well assume that the representative $f \in \text{Emb}(L, N)$ of $q(f)$ has been chosen so that $b(q(f)) = f$, since this is always possible, so this is equivalent to checking that $q(\theta(f) \circ e) = q(f)$. We will show that $\theta(f) \circ e = f$ as embeddings $L \hookrightarrow N$.

Let $z \in L$. Then $\iota e(z) = v \circ \iota_e(z)$, so $e(z) \in \iota^{-1}v(D_{r/2})$ and hence

$$\begin{aligned} \theta(f)(e(z)) &= \pi_\iota t^{-1}(\iota e(z) + \lambda(0)(\iota f(z) - \iota e(z))) \\ &= \pi_\iota t^{-1}(\iota f(z)) \\ &= \pi_\iota t^{-1} t \circ \iota_e f(z) \\ &= f(z). \end{aligned}$$

Hence $(\mathcal{Y}_e, \bar{\theta})$ is a local section at $q(e)$ for the action of $\text{Diff}_c(N)$ on $\text{Emb}(L, N)/G$.

Note. The proof also shows that $\text{Emb}(L, N)$ – without taking a quotient – is $\text{Diff}_c(N)$ -locally retractile. To see this, discard Step 1, which constructs the map b , and use the map θ directly, restricted to $\theta^{-1}(\text{Diff}_c(N))$. \square

4.6. Fibration lemmas. Directly from the definition, one may see that products, compositions and pullbacks of Serre/Hurewicz fibrations are again Serre/Hurewicz fibrations. In the case of Serre fibrations there is a semi-converse to the statement about pullbacks, which we were not able to find in the literature, so we state and prove it briefly here.¹³

Lemma 4.19 *Suppose we have a pullback diagram in topological spaces*

$$\begin{array}{ccc} A & \longleftarrow & C \\ \downarrow l & & \downarrow r \\ B & \longleftarrow & D \\ & b & \end{array}$$

¹³ This will not in fact be needed for the proof in §5 (although it was used in an earlier incarnation of the proof), but we retain it here since it seems interesting, and we were not able to find it explicitly elsewhere in the literature.

in which r and b are Serre fibrations and b is surjective. Then l is also a Serre fibration.

Proof. Consider a lifting problem

$$\begin{array}{ccccc}
 [0, 1]^{k-1} & \xrightarrow{f} & A & \longleftarrow & C \\
 \downarrow i & & \downarrow l & & \downarrow r \\
 [0, 1]^k & \xrightarrow{g} & B & \longleftarrow & D
 \end{array}$$

for $k \geq 0$. Since b is surjective we may lift one corner of the map g to D . Then, using the lifting property for b (k times) we may lift the whole map g to a map $\bar{g}: [0, 1]^k \rightarrow D$. The maps $\bar{g} \circ i$ and f induce a map $\bar{f}: [0, 1]^{k-1} \rightarrow C$ by the universal property of the pullback. We may now find a map $\bar{h}: [0, 1]^k \rightarrow C$ solving the lifting problem (\bar{f}, \bar{g}) and compose with the map $C \rightarrow A$ to solve the original lifting problem (f, g) . \square

Corollary 4.20 *Let $f: X \rightarrow Y$ be an equivariant map between G -spaces, and assume that it is additionally a Serre fibration. Suppose that $X \rightarrow X/G$ and $Y \rightarrow Y/G$ are both principal G -bundles. Then the map of orbit spaces $\bar{f}: X/G \rightarrow Y/G$ is also a Serre fibration.*

Proof. Since any morphism of principal G -bundles is a pullback, the square

$$\begin{array}{ccc}
 X/G & \longleftarrow & X \\
 \bar{f} \downarrow & & \downarrow f \\
 Y/G & \longleftarrow & Y
 \end{array}$$

satisfies the hypotheses of Lemma 4.19. \square

We finish this section with a lemma about Hurewicz fibrations. Mapping spaces (except when we are talking about smooth maps between manifolds) will be equipped with the k -ification of the compact-open topology. Given a continuous map $f: X \rightarrow Y$, let $\text{End}(Y) = \text{Map}(Y, Y)$ denote the space of continuous endomorphisms of Y , and let $\text{End}_f(X)$ be the set of endomorphisms of the map f , where an endomorphism of f means a pair of endomorphisms of X and of Y that commute with f . This is topologised by taking the pullback in diagram (4.1) below and then k -ifying its topology. The notation reflects the fact that, when f is surjective, $\text{End}_f(X)$ may be thought of as the set of endomorphisms of X that preserve the fibres of f .¹⁴ There is a well-defined continuous map

$$f_{\sharp}: \text{End}_f(X) \longrightarrow \text{End}(Y).$$

Lemma 4.21 *If f is a Hurewicz fibration and X is first-countable, then f_{\sharp} is a Serre fibration.*

Proof. Any lifting problem on the left-hand side of the diagram below gives rise to the corresponding lifting problem on the right-hand side. Since f is a Hurewicz fibration, the dotted lift exists on the right-hand side, and its adjoint is a lift for the left-hand side. Hence $f \circ -$ is a Serre fibration.

$$\begin{array}{ccc}
 [0, 1]^k & \longrightarrow & \text{End}(X) \\
 \downarrow & \nearrow & \downarrow f \circ - \\
 [0, 1]^k \times [0, 1] & \longrightarrow & \text{Map}(X, Y)
 \end{array}
 \qquad
 \begin{array}{ccc}
 [0, 1]^k \times X & \longrightarrow & X \\
 \downarrow & \nearrow & \downarrow f \\
 [0, 1]^k \times X \times [0, 1] & \longrightarrow & Y
 \end{array}$$

¹⁴ Note that this is only a statement about sets, not topologies. When f is surjective, the top horizontal map in (4.1) is a continuous injection, but not necessarily a topological embedding.

The pullback of $f \circ -$ along $- \circ f$ is the map f_{\sharp} , which is therefore also a Serre fibration:

$$\begin{array}{ccc} \text{End}_f(X) & \longrightarrow & \text{End}(X) \\ f_{\sharp} \downarrow & \lrcorner & \downarrow f \circ - \\ \text{End}(Y) & \xrightarrow{- \circ f} & \text{Map}(X, Y) \end{array} \quad (4.1)$$

In the first step of the argument we used the following fact. Let A and B be first-countable and C an arbitrary space. Then a function $g: A \times B \rightarrow C$ is continuous if and only if $g(a, -): B \rightarrow C$ is continuous for each $a \in A$ and the function $A \rightarrow \text{Map}(B, C)$ given by $a \mapsto g(a, -)$ is continuous when its codomain is given the k -ification of the compact-open topology.¹⁵ \square

Remark 4.22 Note that the proof cannot show that f_{\sharp} is a Serre fibration if f is only assumed to be a Serre fibration, unless we additionally assume that X is homeomorphic to a cell complex. It also cannot show that f_{\sharp} is a Hurewicz fibration, even when we assume that f is a Hurewicz fibration: we can show that it has the homotopy lifting property with respect to all first-countable spaces, but not arbitrary spaces.¹⁶

Corollary 4.23 *If L and N are smooth manifolds, where L is compact, Z is a first-countable space and $f: Z \rightarrow \text{Emb}(L, N)$ is a fibre bundle, then $f_{\sharp}: \text{End}_f(Z) \rightarrow \text{End}(\text{Emb}(L, N))$ is a Serre fibration.*

Proof. Since L is compact, the embedding space $\text{Emb}(L, N)$ is paracompact, as mentioned at the beginning of §4.1. It is also obviously Hausdorff, because N is Hausdorff. Since f is a fibre bundle over a paracompact Hausdorff base space, it is a Hurewicz fibration (see e.g. [Spa66, Corollary 2.7.14, page 96]), and then Lemma 4.21 implies that f_{\sharp} is a Serre fibration. \square

5. Proof of stability

In this section we apply Theorem 3.8 to prove our main theorem. Fix integers m and p satisfying $0 \leq p \leq \frac{1}{2}(m-3)$ and let n be a non-negative integer. Let $\mathcal{X}(n)$ be the collection of all maps $f: X \rightarrow Y$ as constructed in Definition 2.3, for all choices of $(M, P, \lambda, \iota, G)$, where M is a smooth, connected m -manifold, P is a smooth, closed p -manifold, ι is an embedding $P \hookrightarrow \partial M$, λ is a proper embedding $\partial M \times [0, 2] \hookrightarrow M$ with $\lambda(-, 0) = \text{inclusion}$ and G is an open subgroup of $\text{Diff}(P)$.

To prove Lemma 2.5 and Theorem A we will show that every map in $\bigcup_{n \geq 0} \mathcal{X}(n)$ is split-injective on homology and the sequence $\mathcal{X}(n)$ satisfies condition (2w) of Theorem 3.8. In the next section we spell this out precisely, as a guide to the proof.

5.1. Overview of the proof. We first show in §5.2 that every map $f \in \bigcup_{n \geq 0} \mathcal{X}(n)$ induces split injections on homology in all degrees.

Now fix $n \geq 2$ and $f: X \rightarrow Y$ in $\mathcal{X}(n)$. We construct in §5.3 a map $f_{\bullet}: X_{\bullet} \rightarrow Y_{\bullet}$ of augmented semi-simplicial spaces whose (-1) st level is $f: X \rightarrow Y$, and show that $\text{hconn}(\|X_{\bullet}\| \rightarrow X) \geq n-1$ and $\text{hconn}(\|Y_{\bullet}\| \rightarrow Y) \geq n$.

Fix $i \geq 0$. In §5.4 we construct a commutative square

$$\begin{array}{ccc} X_i & \xrightarrow{f_i} & Y_i \\ p_i \downarrow & & \downarrow q_i \\ A_i & \hookrightarrow & B_i \end{array} \quad (5.1)$$

¹⁵ This fact is more usually stated with no first-countability condition, and with the k -ification of the product topology on $A \times B$. To deduce the version that we used, note that products of first-countable spaces are again first-countable, so $A \times B$ is first-countable, and therefore a k -space, so k -ification does not change its topology.

¹⁶ On the other hand, if we were willing to move entirely into the cgwh category by modifying the product topology, we could conclude that f_{\sharp} is a Hurewicz fibration—in the cgwh category, i.e. it has the homotopy lifting property with respect to all cgwh spaces.

where A_i is path-connected, p_i and q_i are Serre fibrations and the inclusion $A_i \hookrightarrow B_i$ is a homotopy equivalence, and we show, for a certain point $a_i \in A_i$, that the restriction of f_i to $p_i^{-1}(a_i) \rightarrow q_i^{-1}(a_i)$ is in $\mathcal{X}(n - i - 1)$. In the case $i = 0$ we also construct a commutative square

$$\begin{array}{ccc} \bar{X} & \xrightarrow{g} & \bar{Y} \\ \downarrow & & \downarrow \\ p_0^{-1}(a_0) & \xrightarrow{\text{restriction of } f_0} & q_0^{-1}(a_0) \end{array} \quad (5.2)$$

in which the vertical maps are homeomorphisms. (This last step is of course not very significant: the map g is just slightly more convenient to work with than the restriction of f_0 for the next constructions.)

In §5.5 we construct a map $g_\bullet: \bar{X}_\bullet \rightarrow \bar{Y}_\bullet$ of augmented semi-simplicial spaces whose (-1) st level is $g: \bar{X} \rightarrow \bar{Y}$, and we show that $\|\bar{X}_\bullet\| \rightarrow \bar{X}$ and $\|\bar{Y}_\bullet\| \rightarrow \bar{Y}$ are weak equivalences.

Fix $j \geq 0$. In §5.6 we construct another commutative square

$$\begin{array}{ccc} \bar{X}_j & \xrightarrow{g_j} & \bar{Y}_j \\ \bar{p}_j \downarrow & & \downarrow \bar{q}_j \\ \bar{A}_j & \hookrightarrow & \bar{B}_j \end{array} \quad (5.3)$$

where \bar{p}_j and \bar{q}_j are Serre fibrations and the inclusion $\bar{A}_j \hookrightarrow \bar{B}_j$ is a homotopy equivalence. We also show that, for every point $\bar{a} \in \bar{A}_j$, the restriction of g_j to $\bar{p}_j^{-1}(\bar{a}) \rightarrow \bar{q}_j^{-1}(\bar{a})$ is in $\mathcal{X}(n - 1)$.

Finally, fix $a_0 \in A_0$ as above and any point $\bar{a} \in \bar{A}_0$. In §5.7 we show that the composite map

$$\bar{q}_0^{-1}(\bar{a}) \hookrightarrow \bar{Y}_0 \longrightarrow \bar{Y} \xrightarrow{\cong} q_0^{-1}(a_0) \hookrightarrow Y_0 \longrightarrow Y$$

factors up to homotopy through $f: X \rightarrow Y$. (See Figure 5.1 for a picture.)

Combining all of these constructions from §§5.3–5.7 with split-injectivity from §5.2 verifies condition (2w) for the sequence $\mathcal{X}(n)$, and therefore Theorem 3.8 implies Theorem A.

5.2. Split-injectivity. Fix the input data M, P, λ, ι, G and temporarily write the map $f: X \rightarrow Y$ of Definition 2.3 as $f_n: X_n \rightarrow Y_n$ to make the dependence on n explicit (but we continue to hide the dependence on the other choices from the notation). By construction, X_{n+1} is a subspace of Y_n . The only difference is that, in Y_n , the submanifolds are required to have image contained in M_0 , whereas in X_{n+1} they are required to have image contained in the slightly smaller manifold $M_1 \subset M_0$. Using the collar neighbourhood λ , it is easy to construct a deformation retraction for the inclusion $M_1 \hookrightarrow M_0$, which induces a deformation retraction for the inclusion $X_{n+1} \hookrightarrow Y_n$.

Now choosing a homotopy inverse for each of these inclusions, the maps f_n give us a sequence

$$\cdots \longrightarrow X_{n-1} \longrightarrow X_n \longrightarrow X_{n+1} \longrightarrow \cdots,$$

and taking reduced homology in any fixed degree $*$ we get a sequence

$$0 = \tilde{H}_*(X_0) \longrightarrow \tilde{H}_*(X_1) \longrightarrow \tilde{H}_*(X_2) \longrightarrow \tilde{H}_*(X_3) \longrightarrow \cdots$$

of abelian groups and homomorphisms. (Note that X_0 is the one-point space.)

Lemma 5.1 (Lemma 2 of [Dol62]) *Suppose we have a sequence of abelian group homomorphisms $s_n: A_n \rightarrow A_{n+1}$ for $n \geq 0$ with $A_0 = 0$, together with homomorphisms $\tau_{k,n}: A_n \rightarrow A_k$ for $1 \leq k \leq n$ such that $\tau_{n,n} = \text{id}$ and $\tau_{k,n} = \tau_{k,n+1} \circ s_n \pmod{\text{im}(s_{k-1})}$, i.e. $\text{im}(\tau_{k,n} - \tau_{k,n+1} \circ s_n) \subseteq \text{im}(s_{k-1})$. Then every s_n is split-injective.*

To prove Lemma 2.5 it would therefore suffice to define maps $X_n \rightarrow X_k$ for each $1 \leq k \leq n$ such that the induced maps on reduced homology satisfy the hypotheses of this lemma. In fact we will

define maps $X_n \rightarrow \mathrm{Sp}^b(X_k)$ where $b = \binom{n}{k}$. These induce homomorphisms $\tilde{H}_*(X_n) \rightarrow \tilde{H}_*(X_k)$ by sending a cycle in X_n first to a cycle in $\mathrm{Sp}^b(X_k)$ and then viewing it as a formal sum of cycles in X_k . Alternatively, we may apply the Dold-Thom theorem [DT58] that $H_* = \pi_* \circ \mathrm{Sp}^\infty$ for $* \geq 1$ and note that $\mathrm{Sp}^\infty \circ \mathrm{Sp}^b = \mathrm{Sp}^\infty$.

Definition 5.2 Let $\tau_{k,n}: X_n \rightarrow \mathrm{Sp}^{\binom{n}{k}}(X_k)$ be the map taking $\{[\varphi_1], \dots, [\varphi_n]\}$ to the formal sum of $\{[\varphi_i] \mid i \in S\}$ over all subsets $S \subseteq \{1, \dots, n\}$ with $|S| = k$.

Clearly $\tau_{n,n} = \mathrm{id}$, and there are homotopies

$$\tau_{k,n+1} \circ f_n \simeq \tau_{k,n} + f_{k-1} \circ \tau_{k-1,n}$$

of maps $X_n \rightarrow \mathrm{Sp}^{\binom{n+1}{k}}(X_k)$. The hypotheses of Lemma 5.1 are therefore satisfied after taking reduced homology, so Lemma 5.1 implies Lemma 2.5.

5.3. Resolution by subconfigurations. Let $n \geq 2$ and fix the input data $(M, P, \lambda, \iota, G)$ determining a map $f: X \rightarrow Y$ in $\mathcal{X}(n)$. Recall that we denote $\mathrm{Emb}(P, M)$ by E and that G is an open subgroup of $\mathrm{Diff}(P)$.

Definition 5.3 For $i \geq -1$ let X_i be the subspace of $X \times (E/G)^{i+1}$ consisting of tuples

$$(\{[\varphi_1], \dots, [\varphi_n]\}, ([\psi_0], \dots, [\psi_i]))$$

such that the $[\psi_0], \dots, [\psi_i]$ are pairwise distinct and $\{[\psi_0], \dots, [\psi_i]\} \subseteq \{[\varphi_1], \dots, [\varphi_n]\}$. There are obvious face maps $d_j: X_i \rightarrow X_{i-1}$, given by forgetting $[\psi_j]$, that turn this into an augmented semi-simplicial space X_\bullet with $X_{-1} = X$. We define an augmented semi-simplicial space Y_\bullet with $Y_{-1} = Y$ in exactly the same way, and there is a semi-simplicial map $f_\bullet: X_\bullet \rightarrow Y_\bullet$, defined by adjoining $[\lambda(-, \frac{1}{2}) \circ \iota]$ to a configuration, such that $f_{-1} = f$.

As an aside, we now show that the given embedding $\iota: P \hookrightarrow \partial M$ may be extended to an embedding

$$\hat{\iota}: P \times (-1, 1) \times [0, 2] \hookrightarrow M.$$

This will be used many times for the constructions in the following sections.

First, choose a tubular neighbourhood for ι . If we write $\nu_\iota: N \rightarrow P$ for the normal bundle of ι and $o_\iota: P \rightarrow N$ for its zero section, this means an embedding $\bar{\iota}: N \hookrightarrow \partial M$ such that $\bar{\iota} \circ o_\iota = \iota$. The unit sphere subbundle $S(\nu_\iota): S(N) \rightarrow P$ of ν_ι has fibres homeomorphic to S^{m-p-2} . The obstructions to the existence of a section of $S(\nu_\iota)$ therefore live in cohomology groups of the form $H^i(P; \pi_{i-1}(S^{m-p-2}))$. Since P has dimension $p \leq m - p - 3$, these groups all vanish, and so there exists a section of $S(\nu_\iota)$. This is a non-vanishing section of ν_ι , and therefore determines a trivial one-dimensional subbundle $P \times \mathbb{R} \rightarrow P$ of ν_ι , in particular an embedding $P \times \mathbb{R} \hookrightarrow N$. Composing this with $\bar{\iota}$ and restricting to $P \times (-1, 1)$, we obtain an embedding $P \times (-1, 1) \hookrightarrow \partial M$, which we also denote by $\bar{\iota}$ by an abuse of notation. Note that $\bar{\iota}(-, 0) = \iota$. Now we may define the desired embedding $\hat{\iota}$ by $\hat{\iota}(z, s, t) = \lambda(\bar{\iota}(z, s), t)$. Intuitively, the coordinate $s \in (-1, 1)$ specifies a ‘‘shift’’ of the standard embedding $\iota: P \hookrightarrow \partial M$ parallel to the boundary, and the coordinate $t \in [0, 2]$ specifies a shift orthogonal to the boundary, into the interior of M if $t > 0$.

For a space Z , denote the configuration space of n unordered, distinct points in Z by $C_n(Z)$. There is then a map

$$st_n: C_n((-1, 1) \times (1, 2)) \rightarrow X$$

given by $st_n(\{(s_1, t_1), \dots, (s_n, t_n)\}) = \{[\hat{\iota}(-, s_1, t_1)], \dots, [\hat{\iota}(-, s_n, t_n)]\}$. Note that the image of st_n contains the *standard configurations* of Definition 2.2, corresponding to the configurations with $s_1 = s_2 = \dots = s_n = 0$. Similarly, there is a map

$$st'_{n+1}: C_{n+1}((-1, 1) \times (0, 2)) \rightarrow Y$$

whose image contains the standard configurations in Y .

Now we show that $\text{hconn}(\|X_\bullet\| \rightarrow X) \geq n - 1$ and $\text{hconn}(\|Y_\bullet\| \rightarrow Y) \geq n$. We will do this just in the first case, since the second case is almost identical. We first note that all face maps (and compositions of face maps) of X_\bullet are covering maps. In particular, the augmentation $X_0 \rightarrow X$ is a covering map. Now, X is path-connected by definition, and it is not hard to see that X_0 is also path-connected: we just need to show that two points in the same fibre of $X_0 \rightarrow X$ over $x \in X$ can be connected by a path in X_0 , which we can do by first moving x into the image of st_n and then using the image of a braid in $C_n((-1, 1) \times (1, 2))$ to permute the components of the configuration of submanifolds x . Since the space of vertices X_0 is path-connected, so is the geometric realisation $\|X_\bullet\|$. The relative Hurewicz theorem therefore tells us that $\text{hconn}(\|X_\bullet\| \rightarrow X) \geq n - 1$ as long as the map $\|X_\bullet\| \rightarrow X$ is $(n - 1)$ -connected, in other words its homotopy fibre is $(n - 2)$ -connected.

We will use the following lemma, which appeared in an earlier, preprint version of [Ran16] (but not in the final, published version), and which is also very similar to Lemma 2.14 of [ER17]. We also give a self-contained proof in the appendix §6.

Lemma 5.4 *For any augmented semi-simplicial space X_\bullet and point $x \in X = X_{-1}$, the canonical map $\|\text{hofib}_x(k_\bullet)\| \rightarrow \text{hofib}_x(\|X_\bullet\| \rightarrow X)$ is a weak equivalence, where $k_n: X_n \rightarrow X$ denotes the unique composition of face maps $X_n \rightarrow X_{n-1} \rightarrow \dots \rightarrow X_0 \rightarrow X$.*

We note that we are implicitly using a specific point-set model for the homotopy fibre of a map, so that $\text{hofib}_x(k_\bullet)$ is a semi-simplicial *space*, and not just a semi-simplicial object in the homotopy category. This is explained in more detail in §6.2.

In our case, the maps $k_n: X_n \rightarrow X$ are covering maps, therefore Serre fibrations, so there is a levelwise weak equivalence $k_\bullet^{-1}(x) \rightarrow \text{hofib}_x(k_\bullet)$, which then induces a weak equivalence on geometric realisations (cf. Theorem 2.2 of [ER17]). Thus the homotopy fibre of $\|X_\bullet\| \rightarrow X$ is weakly equivalent to $\|k_\bullet^{-1}(x)\|$.

The semi-simplicial set $k_\bullet^{-1}(x)$ has as its set of i -simplices all ordered $(i + 1)$ -tuples of pairwise distinct elements of the set $k_0^{-1}(x) = x = \{[\varphi_1], \dots, [\varphi_n]\} \in X$. This is often called the *complex of injective words* on n letters, and its geometric realisation is known to be homotopy equivalent to a wedge of $(n - 1)$ -spheres, see for example [Ran13, Proposition 3.3]. In particular, this means that $\|k_\bullet^{-1}(x)\|$, and therefore the homotopy fibre of $\|X_\bullet\| \rightarrow X$, is $(n - 2)$ -connected, as claimed.

From the above discussion (and an identical argument in the case of Y_\bullet) we conclude:

Lemma 5.5 *The map $f_\bullet: X_\bullet \rightarrow Y_\bullet$ of augmented semi-simplicial spaces is an n -resolution of $f: X \rightarrow Y$, in other words $\text{hconn}(\|X_\bullet\| \rightarrow X) \geq n - 1$ and $\text{hconn}(\|Y_\bullet\| \rightarrow Y) \geq n$.*

5.4. The first approximation. Fix $i \geq 0$. For a space Z , write $\tilde{C}_k(Z)$ for the configuration space of k ordered points in Z and define a map

$$\tilde{st}_k: \tilde{C}_k((-1, 1) \times (1, 2)) \longrightarrow (E/G)^k$$

by $\tilde{st}_k((s_1, t_1), \dots, (s_k, t_k)) = ([\hat{l}(-, s_1, t_1)], \dots, [\hat{l}(-, s_k, t_k)])$. The domain of \tilde{st}_k (the k th ordered configuration space of the plane) is path-connected, and therefore so is its image in $(E/G)^k$.

Definition 5.6 Let A_i be the path-component of $\text{Emb}((i + 1)P, M_1)/G^{i+1} \subseteq (E/G)^{i+1}$ containing the standard configurations, i.e. the image of \tilde{st}_{i+1} . Equivalently, A_i is the subspace of $(E/G)^{i+1}$ consisting of tuples $([\psi_0], \dots, [\psi_i])$ such that the images $\psi_\alpha(P)$ are pairwise disjoint and contained in M_1 , and there exists a path of such configurations starting at $([\psi_0], \dots, [\psi_i])$ and ending at a standard configuration.

We define B_i in exactly the same way, except that we replace M_1 with M_0 .

Lemma 5.7 *The inclusion $A_i \hookrightarrow B_i$ is a homotopy equivalence.*

Proof. Using the collar neighbourhood λ , we may construct a deformation retraction for the inclusion $M_1 \hookrightarrow M_0$, which induces a deformation retraction for the inclusion $A_i \hookrightarrow B_i$. \square

Definition 5.8 Define $p_i: X_i \rightarrow A_i$ by sending $(\{[\varphi_1], \dots, [\varphi_n]\}, ([\psi_0], \dots, [\psi_i]))$ to $([\psi_0], \dots, [\psi_i])$. In words, p_i takes a configuration of submanifolds in which $i + 1$ components have been marked

(and ordered), and forgets all of the non-marked components. The map $q_i: Y_i \rightarrow B_i$ is defined in exactly the same way.

These are clearly well-defined, and fit into a commutative square (5.1).

Lemma 5.9 *The maps $p_i: X_i \rightarrow A_i$ and $q_i: Y_i \rightarrow B_i$ are Serre fibrations.*

Proof. By Proposition 4.15, the action of $\text{Diff}_c(M_1)$ on the quotient space $\text{Emb}((i+1)P, M_1)/G^{i+1}$ is locally retractile. Since $\text{Diff}_c(M_1)$ is locally path-connected by Fact 4.1, Lemma 4.6 implies that the restriction of this action to the identity path-component $\text{Diff}_c(M_1)_0$ is also locally retractile. Embedding spaces are locally contractible as long as the domain manifold is compact (by Fact 4.1 again), so in particular they are locally path-connected, and so their path-components are open. The property of having open path-components passes to quotient spaces, so A_i is an open subspace of $\text{Emb}((i+1)P, M_1)/G^{i+1}$. It is also $\text{Diff}_c(M_1)_0$ -invariant, since it is a path-component and the group $\text{Diff}_c(M_1)_0$ is path-connected. Therefore Lemma 4.6 tells us that the action of $\text{Diff}_c(M_1)_0$ on A_i is locally retractile.

There is also a well-defined action of $\text{Diff}_c(M_1)_0$ on X_i given by post-composition, and $p_i: X_i \rightarrow A_i$ is equivariant with respect to these actions. Thus Proposition 4.7 implies that it is a fibre bundle, in particular a Serre fibration.

An almost identical argument, replacing M_1 by M_0 everywhere, shows that $q_i: Y_i \rightarrow B_i$ is also a fibre bundle, and therefore a Serre fibration. \square

Now choose a point $a_i = ([\psi_0], \dots, [\psi_i]) \in A_i$ such that each $\psi_\alpha(P)$ is contained in M_2 and define

$$\text{im}(a_i) = \psi_0(P) \cup \psi_1(P) \cup \dots \cup \psi_i(P).$$

Proposition 5.10 *The following two conditions are equivalent for a configuration*

$$\{[\varphi_1], \dots, [\varphi_{n-i-1}]\} \in \text{Emb}((n-i-1)P, M_1 \setminus \text{im}(a_i))/(G \wr \Sigma_{n-i-1}).$$

- (1) *There is a path in this space from $\{[\varphi_1], \dots, [\varphi_{n-i-1}]\}$ to the image of st_{n-i-1} .*
- (2) *There is a path in the space $\text{Emb}(nP, M_1)/(G \wr \Sigma_n)$ from $\{[\varphi_1], \dots, [\varphi_{n-i-1}], [\psi_0], \dots, [\psi_i]\}$ to the image of st_n .*

We defer the proof for a few paragraphs. This immediately implies:

Corollary 5.11 *There is a canonical homeomorphism $p_i^{-1}(a_i) \cong X_{n-i-1}(M \setminus \text{im}(a_i))$ given by*

$$(\{[\varphi_1], \dots, [\varphi_n]\}, ([\psi_0], \dots, [\psi_i])) \mapsto \{[\varphi_1], \dots, [\varphi_{n-i-1}]\},$$

where we assume that the indexing of the $[\varphi_1], \dots, [\varphi_n]$ is chosen so that $[\psi_\alpha] = [\varphi_{n-\alpha}]$.

Remark 5.12 The notation $X_{n-i-1}(M \setminus \text{im}(a_i))$ means the space X from Definition 2.3, with the same P, λ, ι, G as before, but with n replaced by $n-i-1$ and with M replaced by its open submanifold $M \setminus \text{im}(a_i)$.

By exactly the same argument, replacing M_1 with M_0 everywhere, we also have a canonical homeomorphism $q_i^{-1}(a_i) \cong Y_{n-i-1}(M \setminus \text{im}(a_i))$, and these fit into a commutative diagram

$$\begin{array}{ccc} X_{n-i-1}(M \setminus \text{im}(a_i)) & \xrightarrow{f_{n-i-1}(M \setminus \text{im}(a_i))} & Y_{n-i-1}(M \setminus \text{im}(a_i)) \\ \parallel & & \parallel \\ p_i^{-1}(a_i) & \xrightarrow{\text{restriction of } f_i} & q_i^{-1}(a_i) \end{array} \quad (5.4)$$

Thus we have shown that the restriction of f_i to $p_i^{-1}(a_i) \rightarrow q_i^{-1}(a_i)$ is in $\mathcal{X}(n-i-1)$.

Proof of Proposition 5.10. First assume that we have a path of configurations $\{[\varphi_1^t], \dots, [\varphi_{n-i-1}^t]\}$ in $M_1 \setminus \text{im}(a_i)$ indexed by $t \in [0, 1]$ such that $[\varphi_\alpha^0] = [\varphi_\alpha]$ and $\{[\varphi_1^1], \dots, [\varphi_{n-i-1}^1]\}$ is in the image of st_{n-i-1} . By the definition of A_i , there exists a path $([\psi_0^t], \dots, [\psi_i^t])$ in $\text{Emb}((i+1)P, M_1)/G^{i+1}$ with $[\psi_0^0] = [\psi_0]$ and $([\psi_0^1], \dots, [\psi_i^1])$ in the image of \tilde{st}_{i+1} . By compactness, there is some $\epsilon > 0$ such that $\psi_\alpha^t(P) \subseteq M_{1+\epsilon}$ for all α and all t . We now construct a path in $\text{Emb}(nP, M_1)/(G \wr \Sigma_n)$ from $\{[\varphi_1], \dots, [\varphi_{n-i-1}], [\psi_0], \dots, [\psi_i]\}$ to the image of st_n in three steps.

- (i) The path $\{[\varphi_1^t], \dots, [\varphi_{n-i-1}^t], [\psi_0], \dots, [\psi_i]\}$ ends at the configuration

$$\{[\hat{\iota}(-, s_1, t_1)], \dots, [\hat{\iota}(-, s_{n-i-1}, t_{n-i-1})], [\psi_0], \dots, [\psi_i]\}$$

for some $s_\alpha \in (-1, 1)$ and $t_\alpha \in (1, 2)$.

- (ii) Next, keep the $[\psi_0], \dots, [\psi_i]$ fixed and move the other part of the configuration, staying within the image of st_{n-i-1} , so that $t_\alpha \in (1, 1 + \epsilon)$ for all $\alpha \in \{1, \dots, n-i-1\}$. Note that this will not intersect any of $\psi_0(P), \dots, \psi_i(P)$ since the latter are contained in M_2 by our assumption on a_i .

- (iii) Now the path $\{[\hat{\iota}(-, s_1, t_1)], \dots, [\hat{\iota}(-, s_{n-i-1}, t_{n-i-1})], [\psi_0^t], \dots, [\psi_i^t]\}$ ends in the image of st_n .

Conversely, assume that we are given a path of configurations

$$\gamma: [0, 1] \longrightarrow \text{Emb}(nP, M_1)/(G \wr \Sigma_n)$$

with $\gamma(0) = \{[\varphi_1], \dots, [\varphi_{n-i-1}], [\psi_0], \dots, [\psi_i]\}$ and $\gamma(1) \in st_n$. We will write

$$\gamma(t) = \{[\varphi_1^t], \dots, [\varphi_{n-i-1}^t], [\psi_0^t], \dots, [\psi_i^t]\}$$

and note that it make sense to talk about the various components $[\varphi_\alpha^t]$ and $[\psi_\alpha^t]$ individually as well as together, since they may be distinguished using unique path-lifting for the covering space $\text{Emb}(nP, M_1)/G^n \rightarrow \text{Emb}(nP, M_1)/(G \wr \Sigma_n)$. Without loss of generality, we may arrange that

- (a) $\psi_\alpha^t(P) \subseteq M_{1.5}$ for all α and t .
 (b) $\varphi_\alpha^1(P) \subseteq M_1 \setminus M_{1.5} = \lambda(\partial M \times (1, 1.5])$ for all α .

Condition (a) is possible to arrange, using the collar neighbourhood λ , since we have assumed that $\psi_\alpha^0(P) \subseteq M_2$. For condition (b): once we have arrived in the image of st_n , we may choose an appropriate path in the configuration space $C_n((-1, 1) \times (1, 2))$ whose image under st_n fixes the $[\psi_\alpha^1]$ and moves the $[\varphi_\alpha^1]$ into $M_1 \setminus M_{1.5}$.

Define a path $\gamma': [0, 1] \rightarrow \text{Emb}((i+1)P, M_{1.5})/(G \wr \Sigma_{i+1})$ by $t \mapsto \{[\psi_0^t], \dots, [\psi_i^t]\}$ and define

$$\text{Diff}_c(M_{1.5}) \longrightarrow \text{Emb}((i+1)P, M_{1.5})/(G \wr \Sigma_{i+1}) \quad (5.5)$$

by $\Phi \mapsto \{[\Phi \circ \psi_0], \dots, [\Phi \circ \psi_i]\}$. By Propositions 4.15 and 4.7 this is a fibre bundle, thus a Serre fibration, so we may find a lift $\gamma'': [0, 1] \rightarrow \text{Diff}_c(M_{1.5})$ of γ' such that $\gamma''(0)$ is the identity. We now define a path

$$\gamma''': [0, 1] \longrightarrow \text{Emb}((n-i-1)P, M_1 \setminus \text{im}(a_i))/(G \wr \Sigma_{n-i-1})$$

by $\gamma'''(t) = \{[\gamma''(t)^{-1} \circ \varphi_1^t], \dots, [\gamma''(t)^{-1} \circ \varphi_{n-i-1}^t]\}$, where we are implicitly extending compactly-supported diffeomorphisms of $M_{1.5}$ to M_1 by the identity on $M_1 \setminus M_{1.5}$. This is now a path from $\{[\varphi_1], \dots, [\varphi_{n-i-1}]\}$ to the image of st_{n-i-1} . \square

We finish this subsection by defining a slightly more convenient (and homeomorphic) model for the restriction of f_0 to $p_0^{-1}(a_0) \rightarrow q_0^{-1}(a_0)$.

Definition 5.13 Recall from §5.3 that we have chosen a tubular neighbourhood for the embedding $\iota: P \hookrightarrow \partial M$. In other words, writing $\nu_\iota: N \rightarrow P$ for the normal bundle of ι and $o_\iota: P \rightarrow N$ for its zero section, we chose an embedding $\bar{\iota}: N \hookrightarrow \partial M$ such that $\bar{\iota} \circ o_\iota = \iota$. Now let $D(\nu_\iota): D(N) \rightarrow P$ be the closed unit disc subbundle of ν_ι and define

$$T = \bar{\iota}(D(N)).$$

This is a compact codimension-zero submanifold of ∂M with boundary $\bar{\iota}(S(N))$, where $S(\nu_\iota): S(N) \rightarrow P$ is the unit sphere subbundle of ν_ι .

Definition 5.14 Let \bar{X} be the path-component of $\text{Emb}((n-1)P, M_1 \setminus \lambda(T \times \{2\})) / (G \wr \Sigma_{n-1})$ containing the image of st_{n-1} . Let \bar{Y} be the path-component of $\text{Emb}(nP, M_0 \setminus \lambda(T \times \{2\})) / (G \wr \Sigma_n)$ containing the image of st_n . There is a continuous map

$$g: \bar{X} \longrightarrow \bar{Y}$$

defined by $\{[\varphi_1], \dots, [\varphi_{n-1}]\} \mapsto \{[\hat{i}(-, 0, \frac{1}{2})], [\varphi_1], \dots, [\varphi_{n-1}]\}$.

Recall that we have fixed a point $a_0 = [\psi_0] \in A_0$ with $\psi_0(P) \subseteq M_2$. Choose a diffeomorphism

$$\Psi: M \setminus \psi_0(P) \longrightarrow M \setminus \lambda(T \times \{2\})$$

that restricts to the identity on $M \setminus M_{1.5} = \lambda(\partial M \times [0, 1.5])$. This exists because, firstly, $[\psi_0]$ has a path in E/G to $[\hat{i}(-, 0, 2)]$, by definition of A_0 . Since the map (5.5) (with $i = 0$) is a Serre fibration, we may lift this to a path of diffeomorphisms, evaluate at 1, extend by the identity on $M \setminus M_{1.5}$ and then restrict to obtain a diffeomorphism

$$M \setminus \psi_0(P) \longrightarrow M \setminus \hat{i}(P \times \{0\} \times \{2\})$$

that restricts to the identity on $M \setminus M_{1.5}$. Now, since $\lambda(T \times \{2\})$ is a tubular neighbourhood of $\hat{i}(P \times \{0\} \times \{2\}) \subset \lambda(\partial M \times \{2\})$, it is easy to construct a diffeomorphism

$$M \setminus \hat{i}(P \times \{0\} \times \{2\}) \longrightarrow M \setminus \lambda(T \times \{2\})$$

that restricts to the identity on $M \setminus M_{1.5}$. (We note that, to construct this, we use the fact (assumed at the beginning of §2) that the collar neighbourhood $\lambda: \partial M \times [0, 2] \hookrightarrow M$ extends to a slightly larger collar neighbourhood $\partial M \times [0, 2 + \epsilon] \hookrightarrow M$.) Composing these two diffeomorphisms gives the desired diffeomorphism Ψ .

Remark 5.15 If we are careful in how we define the second diffeomorphism above, we may ensure the following useful property of Ψ . Let $s: P \rightarrow N$ be any section of the normal bundle ν . Consider the half-open path $[0, 2) \rightarrow \text{Emb}(P, M_1 \setminus \lambda(T \times \{2\}))$ given by $t \mapsto \lambda(-, t) \circ \bar{i} \circ s$. Postcomposing at each time t with the diffeomorphism Ψ^{-1} defines a half-open path $\gamma: [0, 2) \rightarrow \text{Emb}(P, M_1 \setminus \psi_0(P))$. Then this path may be extended continuously to a path $[0, 2] \rightarrow \text{Emb}(P, M_1)$ by setting $\gamma(2) = \psi_0$. A second useful property of Ψ is that if we consider Ψ^{-1} as an embedding $M \setminus \lambda(T \times \{2\}) \hookrightarrow M$, then it is isotopic to the inclusion through embeddings that restrict to the identity on $M \setminus M_{1.5}$.

Lemma 5.16 *Postcomposition with Ψ^{-1} defines homeomorphisms $\bar{X} \rightarrow p_0^{-1}(a_0)$ and $\bar{Y} \rightarrow q_0^{-1}(a_0)$ such that*

$$\begin{array}{ccc} \bar{X} & \xrightarrow{g} & \bar{Y} \\ \downarrow & & \downarrow \\ p_0^{-1}(a_0) & \xrightarrow{\text{restriction of } f_0} & q_0^{-1}(a_0) \end{array} \quad (5.6)$$

commutes.

Proof. This is immediate from the constructions. One easy but important observation is that if a configuration $\{[\varphi_1], \dots, [\varphi_{n-1}]\}$ has a path to the image of st_{n-1} , then so does the configuration $\{[\Psi^{-1} \circ \varphi_1], \dots, [\Psi^{-1} \circ \varphi_{n-1}]\}$, since Ψ^{-1} is the identity on $\lambda(\partial M \times [0, 1.5])$. \square

5.5. Resolution by tubes to the boundary.

Definition 5.17 (The second resolution) Let \bar{X}_0 be the subspace of $\bar{X} \times \text{Emb}(P \times [0, 2], M)$ consisting of all elements $(\{[\varphi_1], \dots, [\varphi_{n-1}]\}, \tau)$ with the following properties.

- (a) There exist $h \in (\frac{1}{2}, 1)$ and $\epsilon \in (0, 1)$ so that $\tau(-, t) = \hat{i}(-, h, t)$ for all $t \in [0, 1 + \epsilon] \cup [2 - \epsilon, 2]$.
- (b) The image $\tau(P \times (1, 2))$ is contained in $M_1 \setminus (\varphi_1(P) \cup \varphi_2(P) \cup \dots \cup \varphi_{n-1}(P) \cup \lambda(T \times \{2\}))$.

There is an obvious map $\bar{X}_0 \rightarrow \bar{X}$ given by forgetting τ . More generally, for $i \geq 0$, let \bar{X}_i be the subspace of $\bar{X} \times \text{Emb}(P \times [0, 2], M)^{i+1}$ consisting of all elements $(\{[\varphi_1], \dots, [\varphi_{n-1}]\}, (\tau_0, \dots, \tau_i))$ with the following properties.

- (ab) Each τ_α satisfies the properties (a) and (b) above.
- (c) For $\alpha \neq \beta$, the images $\tau_\alpha(P \times [0, 2])$ and $\tau_\beta(P \times [0, 2])$ are disjoint.
- (d) Write $h_\alpha \in (\frac{1}{2}, 1)$ for the number associated to τ_α by condition (a). Then $h_0 < h_1 < \dots < h_i$.

There are maps $d_j: \bar{X}_i \rightarrow \bar{X}_{i-1}$ defined by forgetting τ_j . These obviously satisfy the simplicial identities, so they give $\bar{X}_\bullet = \{\bar{X}_i\}_{i \geq 0} \cup \{\bar{X}\}$ the structure of an augmented semi-simplicial space.

The augmented semi-simplicial space \bar{Y}_\bullet is defined similarly — the space \bar{Y}_i is the subspace of $\bar{Y} \times \text{Emb}(P \times [0, 2], M)$ consisting of all elements $(\{[\varphi_1], \dots, [\varphi_{n-1}]\}, (\tau_0, \dots, \tau_i))$ with the properties (c) and (d) above, as well as the following variants of (a) and (b).

- (ā) There exist $h \in (\frac{1}{2}, 1)$ and $\epsilon \in (0, 1)$ so that $\tau(-, t) = \hat{\iota}(-, h, t)$ for all $t \in [0, \epsilon] \cup [2 - \epsilon, 2]$.
- (b) The image $\tau(P \times (0, 2))$ is contained in $M_0 \setminus (\varphi_1(P) \cup \varphi_2(P) \cup \dots \cup \varphi_{n-1}(P) \cup \lambda(T \times \{2\}))$.

There are again maps forgetting τ_j that give $\bar{Y}_\bullet = \{\bar{Y}_i\}_{i \geq 0} \cup \{\bar{Y}\}$ the structure of an augmented semi-simplicial space. There is a map of augmented semi-simplicial spaces

$$g_\bullet: \bar{X}_\bullet \longrightarrow \bar{Y}_\bullet$$

given by $(\{[\varphi_1], \dots, [\varphi_{n-1}]\}, (\tau_0, \dots, \tau_i)) \mapsto (\{\hat{\iota}(-, 0, \frac{1}{2}), [\varphi_1], \dots, [\varphi_{n-1}]\}, (\tau_0, \dots, \tau_i))$ on spaces of i -simplices. Clearly $g_{-1} = g$, i.e. this extends $g: \bar{X} \rightarrow \bar{Y}$ to augmented semi-simplicial spaces.

Remark 5.18 A vertex of \bar{X}_\bullet is intuitively a “tube” with cross-section P going from the boundary ∂M to $\lambda(T \times \{2\})$, which is a thickened copy of P in the interior of M . This tube must be “straight” in a certain sense near each end, and it must be disjoint from the configuration (and the interior of the tube must also be disjoint from $\lambda(T \times \{2\})$). An ordered collection of such tubes forms a simplex if and only if they are pairwise disjoint and the ordering coincides with the intrinsic ordering that they inherit from the boundary condition near ∂M .

Our task in this subsection is to show that the induced maps

$$\|\bar{X}_\bullet\| \longrightarrow \bar{X} \quad \text{and} \quad \|\bar{Y}_\bullet\| \longrightarrow \bar{Y}$$

are weak equivalences. We will do this explicitly just for $\|\bar{X}_\bullet\| \rightarrow \bar{X}$, since the other case is almost identical. We will use the following theorem due to Galatius and Randal-Williams.

Theorem 5.19 (Theorem 6.2 of [GR14]) *If $Z_\bullet \rightarrow Z$ is an augmented semi-simplicial space, the following conditions imply that the map $\|Z_\bullet\| \rightarrow Z$ is a weak equivalence.*

- (i) *The map $Z_i \rightarrow Z_0 \times_Z \dots \times_Z Z_0$ taking an i -simplex to the ordered set of its $i + 1$ vertices is a homeomorphism onto an open subspace.*
- (ii) *Under this identification, an $(i + 1)$ -tuple of vertices (v_0, v_1, \dots, v_i) lies in Z_i if and only if (v_α, v_β) lies in Z_1 for all $\alpha < \beta$.*
- (iii) *Denote the augmentation map $Z_0 \rightarrow Z$ by a . For every point $v \in Z_0$ there is an open neighbourhood U of $a(v) \in Z$ and a section $s: U \rightarrow Z_0$ of a such that $s(a(v)) = v$.*
- (iv) *For any finite set $\{v_1, \dots, v_k\}$ in a fibre of a , there is another vertex v in the same fibre such that $(v_\alpha, v) \in Z_1$ for all $\alpha \in \{1, \dots, k\}$.*

Remark 5.20 We note that, in [GR14], condition (iii) is slightly weaker and more complicated to state, and incorporates the $k = 0$ part of condition (iv), i.e. surjectivity of $a: Z_0 \rightarrow Z$.

First note that conditions (i)–(iii) are clearly true for $Z_\bullet = \bar{X}_\bullet$. For (i) and (ii) this is because we defined an i -simplex to be an $(i + 1)$ -tuple of vertices satisfying conditions (c) and (d), which are open conditions that may be determined by looking at ordered sub-tuples of length 2. For condition (iii), let $v = (\{[\varphi_1], \dots, [\varphi_{n-1}]\}, \tau) \in \bar{X}_0$. Define U to be the open subspace of \bar{X} consisting of all configurations $\{[\varphi'_1], \dots, [\varphi'_{n-1}]\}$ such that $\bigcup_{\alpha=1}^{n-1} \varphi'_\alpha(P)$ is disjoint from $\tau(P \times [0, 2])$. This is an open neighbourhood of $a(v) = \{[\varphi_1], \dots, [\varphi_{n-1}]\}$ and we may define a section of $a: \bar{X}_0 \rightarrow \bar{X}$ on U by

$$s: U \longrightarrow \bar{X}_0 \quad \{[\varphi'_1], \dots, [\varphi'_{n-1}]\} \mapsto (\{[\varphi'_1], \dots, [\varphi'_{n-1}]\}, \tau),$$

which sends $a(v)$ to v .

In order to verify condition (iv) for $Z_\bullet = \overline{X}_\bullet$ we will first take a detour to discuss transversality. One corollary of Thom's transversality theorem is the following.

Theorem 5.21 (Corollary II.4.12(b), page 56, [GG73]) *Let L and N be smooth manifolds without boundary and $f: L \rightarrow N$ a smooth map. Let $W \subseteq N$ be a smooth submanifold and $A \subseteq B \subseteq L$ open subsets such that $\overline{A} \subseteq B$. Let \mathcal{U} be an open neighbourhood of $f \in C^\infty(L, N)$ in the Whitney C^∞ -topology. Then there exists $g \in \mathcal{U}$ such that*

- (1) $g|_A = f|_A$,
- (2) g is transverse to W on $L \setminus B$.

A useful corollary of this is the following.

Corollary 5.22 *Let L and N be smooth manifolds without boundary and let $W \subseteq N$ be a smooth submanifold that is closed as a subset such that $\dim(W) + \dim(L) < \dim(N)$. Also, let $f: L \rightarrow N$ be a smooth map and $B \subseteq L$ an open subset such that $f(\overline{B}) \subseteq N \setminus W$. Let \mathcal{U} be an open neighbourhood of $f \in C^\infty(L, N)$ in the Whitney C^∞ -topology. Then, for any open subset $A \subseteq B$ with $\overline{A} \subseteq B$, there exists $g \in \mathcal{U}$ such that*

- (1) $g|_A = f|_A$,
- (2) $g(L) \subseteq N \setminus W$.

This says, roughly, that if we have a smooth map f whose image is disjoint from W on a closed subset \overline{B} , then we may find a smooth map g that is arbitrarily close to f (in the sense that $g \in \mathcal{U}$), agrees with f on a slightly smaller subset (namely A), and whose entire image is disjoint from W .

Proof. Let $\mathcal{V} = \{g \in C^\infty(L, N) \mid g(\overline{B}) \subseteq N \setminus W\}$. This condition is equivalent to requiring that $\Gamma_g \subseteq (L \times N) \setminus (\overline{B} \times W)$, where Γ_g is the graph of g . Therefore \mathcal{V} is open in the graph topology (which is the Whitney C^0 -topology) on $C^\infty(L, N)$, and therefore it is also open in the Whitney C^∞ -topology on $C^\infty(L, N)$. Applying Theorem 5.21 to the open neighbourhood $\mathcal{U} \cap \mathcal{V}$ of f we obtain $g \in \mathcal{U}$ such that $g|_A = f|_A$, $g(L \setminus B) \subseteq N \setminus W$ and $g(\overline{B}) \subseteq N \setminus W$. The last two properties combined imply that $g(L) \subseteq N \setminus W$. \square

We will use this to prove:

Proposition 5.23 *The augmented semi-simplicial space $Z_\bullet = \overline{X}_\bullet$ satisfies condition (iv) of Theorem 5.19.*

Corollary 5.24 *The maps $\|\overline{X}_\bullet\| \rightarrow \overline{X}$ and $\|\overline{Y}_\bullet\| \rightarrow \overline{Y}$ are weak equivalences.*

Proof. By the discussion above, $Z_\bullet = \overline{X}_\bullet$ satisfies conditions (i)–(iii) and by Proposition 5.23 it also satisfies condition (iv). Theorem 5.19 therefore implies that $\|\overline{X}_\bullet\| \rightarrow \overline{X}$ is a weak equivalence. The argument for $\|\overline{Y}_\bullet\| \rightarrow \overline{Y}$ is almost identical, replacing n by $n + 1$ and M_1 by M_0 everywhere. \square

Proof of Proposition 5.23. Fix a point $\varphi = \{[\varphi_1], \dots, [\varphi_{n-1}]\} \in \overline{X}$ and a collection of embeddings $\tau_1, \dots, \tau_k: P \times [0, 2] \hookrightarrow M$ such that $(\varphi, \tau_\alpha) \in \overline{X}_0$ for each α . Let $h_\alpha \in (\frac{1}{2}, 1)$ be the number associated to τ_α by condition (a) of Definition 5.17. We need to construct a new embedding

$$\tau: P \times [0, 2] \hookrightarrow M \tag{5.7}$$

such that $(\varphi, \tau) \in \overline{X}_0$ and $(\varphi, (\tau_\alpha, \tau)) \in \overline{X}_1$ for all $\alpha \in \{1, \dots, k\}$. As a first step, choose $h \in (\frac{1}{2}, 1)$ such that $h > \max_{\alpha=1}^k h_\alpha$ and define an embedding $\sigma: P \times [0, 2] \hookrightarrow M$ by $\sigma = \hat{i}(-, h, -)$.

It now suffices to find an embedding

$$\sigma': P \times (1, 2) \hookrightarrow M_1 \setminus \lambda(T \times \{2\})$$

such that

- $\sigma = \sigma'$ on $P \times ((1, 1 + \epsilon) \cup (2 - \epsilon, 2))$ for some $\epsilon > 0$,

- the image of σ' is disjoint from $\varphi_1(P) \cup \dots \cup \varphi_{n-1}(P)$ and $\tau_1(P \times (1, 2)) \cup \dots \cup \tau_k(P \times (1, 2))$.

This is because we could then define (5.7) to agree with σ on $P \times ([0, 1] \cup \{2\})$ and to agree with σ' on $P \times (1, 2)$, and it would satisfy all of the required conditions.

Let $\sigma_0 = \sigma|_{P \times (1, 2)}$. We will construct σ' from σ_0 by using Corollary 5.22 to modify it to be disjoint from the manifolds $\tau_\alpha(P \times (1, 2))$ and $\varphi_\alpha(P)$ one at a time.

Set $L = P \times (1, 2)$, $N = M_1 \setminus \lambda(T \times \{2\})$, $f = \sigma_0$ and $W = \tau_1(P \times (1, 2))$. By a compactness argument, and using the fact that $h \neq h_1$ and property (a) of τ_1 , we may find $\delta > 0$ such that

$$\sigma_0(P \times ((1, 1 + 2\delta] \cup [2 - 2\delta, 2))) \subseteq N \setminus W.$$

We may therefore set $B = P \times ((1, 1 + 2\delta) \cup (2 - 2\delta, 2))$. Since being an embedding is an open condition in the Whitney C^∞ -topology, we may take \mathcal{U} to be an open neighbourhood of $f = \sigma_0$ in $C^\infty(L, N)$ consisting of embeddings. Corollary 5.22 therefore gives us an embedding

$$\sigma_1: P \times (1, 2) \hookrightarrow M_1 \setminus (\lambda(T \times \{2\}) \cup \tau_1(P \times (1, 2)))$$

such that $\sigma_1 = \sigma_0$ on $P \times ((1, 1 + \delta) \cup (2 - \delta, 2))$. Note that here we crucially used the fact that $\dim(P) \leq \frac{1}{2}(\dim(M) - 3)$ in order to satisfy the dimension condition of Corollary 5.22.

Iterating this, we next set $L = P \times (1, 2)$, $N = M_1 \setminus (\lambda(T \times \{2\}) \cup \tau_1(P \times (1, 2)))$, $f = \sigma_1$ and $W = \tau_2(P \times (1, 2))$ and apply Corollary 5.22 to obtain an embedding

$$\sigma_2: P \times (1, 2) \hookrightarrow M_1 \setminus (\lambda(T \times \{2\}) \cup \tau_1(P \times (1, 2)) \cup \tau_2(P \times (1, 2)))$$

such that $\sigma_2 = \sigma_1$ on $P \times ((1, 1 + \delta') \cup (2 - \delta', 2))$ for some $\delta' > 0$. After a finite number of further applications of Corollary 5.22 we obtain an embedding σ' with the required properties. \square

5.6. The second approximation.

Definition 5.25 For $j \geq 0$ define \bar{A}_j to be the subspace of $\text{Emb}(P \times [0, 2], M)^{i+1}$ consisting of tuples of embeddings (τ_0, \dots, τ_j) such that each τ_α satisfies condition (a) of Definition 5.17, the tuple satisfies conditions (c) and (d) of Definition 5.17 and each τ_α also satisfies:

- (b) $\tau_\alpha(P \times (1, 2)) \subseteq M_1 \setminus \lambda(T \times \{2\})$.

Similarly, define \bar{B}_j to be the subspace of $\text{Emb}(P \times [0, 2], M)^{i+1}$ consisting of (τ_0, \dots, τ_j) satisfying conditions (a), (c) and (d) of Definition 5.17, as well as

- (b) $\tau_\alpha(P \times (0, 2)) \subseteq M_0 \setminus \lambda(T \times \{2\})$.

Lemma 5.26 *The inclusion $\bar{A}_j \hookrightarrow \bar{B}_j$ is a homotopy equivalence.*

Proof. We will define a deformation retraction for the inclusion, i.e. a map

$$H: \bar{B}_j \times [0, 1] \longrightarrow \bar{B}_j$$

such that $H(-, 0) = \text{id}$ and $H((\bar{A}_j \times [0, 1]) \cup (\bar{B}_j \times \{1\})) \subseteq \bar{A}_j$. For this, we choose a smooth map

$$\Upsilon: S \longrightarrow [0, 2],$$

where $S = \{(s, t) \in [0, 1] \times [0, 2] \mid s \leq t\}$, such that

- (i) $\Upsilon(0, t) = t$,
- (ii) $\Upsilon(s, t) = t - s$ for $t \leq s + \frac{1}{4}$,
- (iii) $\Upsilon(s, t) = t$ for $t \geq \frac{7}{4}$,
- (iv) for each fixed $s \in [0, 1]$ the map $\Upsilon(s, -)$ is a diffeomorphism $[s, 2] \cong [0, 2]$ with $\Upsilon(s, 1) \leq 1$.

This is not hard (although a little fiddly) to construct. Note that the function $\Upsilon(s, t) = 2(\frac{t-s}{2-s})$ satisfies conditions (i) and (iv), but not (ii) or (iii). If we were working only with C^0 embeddings, then we would not need (ii) or (iii) and this version of Υ would work, but in order to ensure that the two parts of the definition below glue together to form a C^∞ embedding we also need conditions (ii) and (iii).

We may now use this to “conjugate” each τ_α by reparametrising its domain by $\Upsilon(s, -)$ and its codomain by $\Upsilon(s, -)^{-1}$. More precisely, we define the deformation retraction by

$$H((\tau_0, \dots, \tau_j), s) = (\tau_0^s, \dots, \tau_j^s),$$

where $\tau_\alpha^s: P \times [0, 2] \hookrightarrow M$ is defined by

$$\tau_\alpha^s(z, t) = \begin{cases} \hat{\iota}(z, h_\alpha, t) & \text{for } 0 \leq t \leq s \\ \tilde{\Upsilon}_s \circ \tau_\alpha(z, \Upsilon(s, t)) & \text{for } s \leq t \leq 2, \end{cases}$$

where $\tilde{\Upsilon}_s: M \hookrightarrow M$ is the self-embedding defined by $\lambda \circ (\text{id} \times \Upsilon(s, -)^{-1}) \circ \lambda^{-1}$ on the collar neighbourhood and by the identity elsewhere.

The choice of smoothly varying reparametrisation $\Upsilon(s, -)$ ensures that the two pieces of this definition glue together to form a smooth embedding, and one may easily check that this H is indeed a deformation retraction. \square

Now define a map $\bar{p}_j: \bar{X}_j \rightarrow \bar{A}_j$ taking $(\{[\varphi_1], \dots, [\varphi_{n-1}]\}, (\tau_0, \dots, \tau_j))$ to the tuple (τ_0, \dots, τ_j) , and similarly $\bar{q}_j: \bar{Y}_j \rightarrow \bar{B}_j$ taking $(\{[\varphi_1], \dots, [\varphi_n]\}, (\tau_0, \dots, \tau_j))$ to (τ_0, \dots, τ_j) . These forgetful maps fit into a commutative square:

$$\begin{array}{ccc} \bar{X}_j & \xrightarrow{g_j} & \bar{Y}_j \\ \bar{p}_j \downarrow & & \downarrow \bar{q}_j \\ \bar{A}_j & \hookrightarrow & \bar{B}_j \end{array}$$

Proposition 5.27 *The maps $\bar{p}_j: \bar{X}_j \rightarrow \bar{A}_j$ and $\bar{q}_j: \bar{Y}_j \rightarrow \bar{B}_j$ are Serre fibrations.*

Proof. We start by constructing a manifold with boundary M_{cut} whose interior is $M_1 \setminus \lambda(T \times \{2\})$. Recall that $T \subseteq \partial M$ is a codimension-zero submanifold with boundary, and write \mathring{T} for its interior. We will attach two pieces of boundary to $M_1 \setminus \lambda(T \times \{2\})$. First, we (re-)attach $\lambda(\partial M \times \{1\})$ as one piece of boundary.¹⁷ Second, we attach $\lambda(\mathring{T} \times \{2\})$, *but only along one side*, as the second piece of boundary. More precisely, we define

$$M_{\text{cut}} = M \setminus \lambda((\partial M \times [0, 1]) \cup (T \times \{2\})) \cup_{\lambda(\mathring{T} \times (1, 2))} \lambda(\mathring{T} \times (1, 2]). \quad (5.8)$$

The name M_{cut} comes from thinking of the operation of removing $\lambda(T \times \{2\})$ and re-attaching $\lambda(\mathring{T} \times \{2\})$ along one side only as making a “cut” in the interior of M in order to get a new piece of boundary. One may see directly from the definition (5.8) that $\text{int}(M_{\text{cut}}) = M_1 \setminus \lambda(T \times \{2\})$ and $\partial M_{\text{cut}} = \lambda(\partial M \times \{1\}) \sqcup \lambda(\mathring{T} \times \{2\})$ as described more heuristically above.

Now let $L = P \times [1, 2] \times \{0, \dots, j\}$ and decompose its boundary as

$$\partial_1 L = P \times \{1\} \times \{0, \dots, j\} \quad \partial_2 L = P \times \{2\} \times \{0, \dots, j\}.$$

Similarly, decompose the boundary of M_{cut} as

$$\partial_1 M_{\text{cut}} = \lambda(\partial M \times \{1\}) \quad \partial_2 M_{\text{cut}} = \lambda(\mathring{T} \times \{2\}).$$

Define $\hat{A}_j = \text{Emb}_{12}(L, M_{\text{cut}})$, where the embedding space $\text{Emb}_{12}(-, -)$ is defined as in §4 just before Proposition 4.12. Equivalently an element of \hat{A}_j consists of a tuple (τ_0, \dots, τ_j) of embeddings $\tau_\alpha: P \times [1, 2] \hookrightarrow M$ with pairwise-disjoint images, such that

- $\tau_\alpha(P \times \{1\}) \subseteq \lambda(\partial M \times \{1\})$,
- $\tau_\alpha(P \times \{2\}) \subseteq \lambda(\mathring{T} \times \{2\})$,
- $\tau_\alpha(P \times (1, 2)) \subseteq M_1 \setminus \lambda(T \times [2, 2 + \epsilon])$ for some $\epsilon > 0$.

¹⁷ Note that we do not say one “boundary-component”, because we are not assuming that ∂M is connected.

Now define \hat{X}_j to be the subspace of $\bar{X} \times \hat{A}_j$ consisting of all $(\{[\varphi_1], \dots, [\varphi_{n-1}]\}, (\tau_0, \dots, \tau_j))$ such that

$$\bigcup_{\alpha=1}^{n-1} \varphi_\alpha(P) \quad \text{is disjoint from} \quad \bigcup_{\alpha=0}^j \tau_\alpha(P \times [1, 2]).$$

(Recall that the space \bar{X} was defined in Definition 5.14.) There is a well-defined continuous action of $\text{Diff}_c(M_{\text{cut}})_0$ on both \hat{X}_j and \hat{A}_j given by post-composition, and the projection onto the second factor $\hat{p}_j: \hat{X}_j \rightarrow \hat{A}_j$ is equivariant with respect to these actions. (Note that it is important for the well-definedness of the actions that we are considering the path-component $\text{Diff}_c(M_{\text{cut}})_0$ of the identity in the group $\text{Diff}_c(M_{\text{cut}})$, so in particular we are considering actions of a path-connected group.) Propositions 4.12 and 4.7 now imply that \hat{p}_j is a fibre bundle, in particular a Serre fibration.

Now we may define a topological embedding $\bar{A}_j \hookrightarrow \hat{A}_j$ by $(\tau_0, \dots, \tau_j) \mapsto (\tau_0|_{P \times [1, 2]}, \dots, \tau_j|_{P \times [1, 2]})$. By construction, the pullback of \hat{p}_j along this embedding is exactly the map $\bar{p}_j: \bar{X}_j \rightarrow \bar{A}_j$. Hence \bar{p}_j is a Serre fibration, as required. The argument for \bar{q}_j is essentially identical, so it is omitted. \square

Now fix $\bar{a} = (\tau_0, \dots, \tau_j) \in \bar{A}_j$. We will show that the restriction of g_j to the fibres $\bar{p}_j^{-1}(\bar{a}) \rightarrow \bar{q}_j^{-1}(\bar{a})$ lies in $\mathcal{X}(n-1)$. Define

$$\check{M} = M \setminus (\tau_0(P \times [0, 2]) \cup \dots \cup \tau_j(P \times [0, 2]) \cup \lambda(T \times \{2\}))$$

and note that $\partial\check{M} = \partial M \setminus \hat{i}(P \times \{h_0, \dots, h_j\} \times \{0\})$. Choose $\epsilon > 0$ such that:

- $\tau_\alpha(z, t) = \hat{i}(z, h_\alpha, t)$ for all $t \in [0, 1 + \epsilon]$, $z \in P$ and $\alpha \in \{0, \dots, j\}$,
- each $\tau_\alpha(P \times (1 + \epsilon, 2])$ is contained in $M_{1+\epsilon}$.

Choose a diffeomorphism $\theta: [0, 2] \rightarrow [0, 1 + \epsilon]$ such that $\theta(t) = t$ for $t \in [0, 1]$ and define

$$\mu: \partial\check{M} \times [0, 2] \hookrightarrow \check{M}$$

by $\mu(z, t) = \lambda(z, \theta(t))$. This is a collar neighbourhood for the boundary of \check{M} . Write $X_{n-1}(\check{M}, \mu)$ for the space X from Definition 2.3 with P, ι, G the same as before but with n, M, λ replaced by $n-1, \check{M}, \mu$ respectively, and similarly for $Y_{n-1}(\check{M}, \mu)$ and the map $f_{n-1}(\check{M}, \mu)$.

Remark 5.28 In a moment we will show that the restriction of g_j to the fibres $\bar{p}_j^{-1}(\bar{a}) \rightarrow \bar{q}_j^{-1}(\bar{a})$ may be identified (up to homeomorphism) with $f_{n-1}(\check{M}, \mu)$, and from this we would like to deduce that it lies in $\mathcal{X}(n-1)$. We therefore have to check that \check{M} and μ (as well as P, ι, G) are valid input data for Definition 2.3. The only non-trivial issue with this is to see that \check{M} is connected. To obtain \check{M} from M we have first removed $\lambda(T \times \{2\})$ and then each $\tau_\alpha(P \times [0, 2])$. The latter all have codimension at least $m - p - 1 \geq p + 2 \geq 2$ and the former deformation retracts onto its core $\lambda(\iota(P) \times \{2\})$ (recall that $T \subseteq \partial M$ is a tubular neighbourhood for $\iota(P) \subseteq \partial M$), which has codimension at least $m - p \geq p + 3 \geq 3$, so neither of these operations change π_0 . Therefore \check{M} is connected since M is connected.

A little thought about the definitions yields the following descriptions of $\bar{p}_j^{-1}(\bar{a})$ and $X_{n-1}(\check{M}, \mu)$. First we fix some temporary notation. Write

$$U = \text{Emb}(P \times \{1, \dots, n-1\}, M_1 \setminus \lambda(T \times \{2\})) / (G \wr \Sigma_{n-1})$$

and set $W = \tau_0(P \times (1, 2)) \cup \dots \cup \tau_j(P \times (1, 2))$, which is a properly embedded submanifold of $M_1 \setminus \lambda(T \times \{2\})$. Choose a tuple (s_1, \dots, s_{n-1}) of distinct points in the interval $(1, 1 + \epsilon)$ and let φ_{st} be the embedding

$$(z, \alpha) \mapsto \hat{i}(z, 0, s_\alpha): P \times \{1, \dots, n-1\} \hookrightarrow M_1 \setminus \lambda(T \times \{2\}).$$

Note that the image of φ_{st} is disjoint from W due to how we chose ϵ above. With this notation, we have

$$X_{n-1}(\check{M}, \mu) \subseteq \bar{p}_j^{-1}(\bar{a}) \subseteq U,$$

and, given an element $[\varphi] \in U$,

- $[\varphi] \in \bar{p}_j^{-1}(\bar{a})$ if and only if $\text{im}(\varphi)$ is disjoint from W and there is a path in U from $[\varphi]$ to $[\varphi_{\text{st}}]$,
- $[\varphi] \in X_{n-1}(\check{M}, \mu)$ if and only if $\text{im}(\varphi)$ is disjoint from W and there is a path $t \mapsto [\varphi^t]$ in U from $[\varphi]$ to $[\varphi_{\text{st}}]$ such that $\text{im}(\varphi^t)$ is disjoint from W for all $t \in [0, 1]$.

Replacing M_1 with M_0 and $n - 1$ with n , we obtain a similar description of $Y_{n-1}(\check{M}, \mu) \subseteq \bar{q}_j^{-1}(\bar{a})$, and a commutative square

$$\begin{array}{ccc} \bar{p}_j^{-1}(\bar{a}) & \xrightarrow{\text{restriction of } g_j} & \bar{q}_j^{-1}(\bar{a}) \\ \cup & & \cup \\ X_{n-1}(\check{M}, \mu) & \xrightarrow{f_{n-1}(\check{M}, \mu)} & Y_{n-1}(\check{M}, \mu) \end{array}$$

(for commutativity we use the fact that the collar neighbourhoods $\lambda(z, t)$ and $\mu(z, t)$ of M and \check{M} agree for $t \leq 1$ due to how we chose θ above; in particular they agree on $\iota(P) \times \{\frac{1}{2}\}$).

It remains to show that in fact $X_{n-1}(\check{M}, \mu) = \bar{p}_j^{-1}(\bar{a})$ and $Y_{n-1}(\check{M}, \mu) = \bar{q}_j^{-1}(\bar{a})$. This will follow immediately from the descriptions above together with the following general lemma, in which we take $L = P \times \{1, \dots, n - 1\}$ and $N = M_1 \setminus \lambda(T \times \{2\})$.

Lemma 5.29 *Let L and N be manifolds without boundary such that $\dim(N) \geq 2 \dim(L) + 3$ and assume that L is compact. Let $W \subseteq N$ be a closed subset that is a finite union of properly embedded submanifolds, each of dimension at most $\dim(N) - \dim(L) - 2$. Let G be an open subgroup of $\text{Diff}(L)$. Suppose we have a path*

$$\gamma: [0, 1] \longrightarrow \text{Emb}(L, N)/G$$

such that $\gamma(0)(L)$ and $\gamma(1)(L)$ are disjoint from W . Then there exists another path

$$\gamma': [0, 1] \longrightarrow \text{Emb}(L, N)/G$$

with the same endpoints as γ , such that $\gamma'(t)(L)$ is disjoint from W for all $t \in [0, 1]$, in other words γ' has image contained in $\text{Emb}(L, N \setminus W)/G$.

We will use the following theorem of Whitney in the proof.

Theorem 5.30 ([Whi36, Theorem 5 in §11]) *Let L and N be smooth manifolds without boundary such that $\dim(N) \geq 2 \dim(L) + 1$ and let $A \subseteq L$ be a closed subset. Suppose we are given a continuous map $\phi: L \rightarrow N$ such that its restriction to A is a smooth injective immersion. Then there exists a smooth injective immersion $\psi: L \rightarrow N$ such that $\psi|_A = \phi|_A$.*

We will also use the following immediate corollary of Thom's transversality theorem.

Proposition 5.31 *Let L and N be smooth manifolds without boundary, L assumed to be compact, and $X \subseteq N$ a countable union of submanifolds of N . Then given any embedding $\phi \in \text{Emb}(L, N)$ there is a path $\gamma: [0, 1] \rightarrow \text{Emb}(L, N)$ with $\gamma(0) = \phi$ and $\gamma(1)$ transverse to X .*

Proof. By the transversality theorem of Thom (cf. [GG73, Theorem II.4.9, page 54]), the subset

$$\{\phi' \in \text{Emb}(L, N) \mid \phi' \text{ is transverse to } X\} \subseteq \text{Emb}(L, N)$$

is dense in the strong C^∞ topology. Since $\text{Emb}(L, N)$ is locally path-connected (indeed, locally contractible since L is compact, cf. Fact 4.1) we may choose a path-connected open neighbourhood $\mathcal{U} \subseteq \text{Emb}(L, N)$ of ϕ . By density, we may find $\phi' \in \mathcal{U}$ that is transverse to X , and then by path-connectedness of \mathcal{U} we may find a path from ϕ to ϕ' . \square

Proof of Lemma 5.29. We will prove this in $4 = \{0, 1, 2, 3\}$ steps.

Step 0. First, we show that we may assume without loss of generality that $\gamma(0)(L)$ and $\gamma(1)(L)$ are disjoint subsets of N . So we assume temporarily that the lemma is true under this assumption,

and let $\gamma: [0, 1] \rightarrow \text{Emb}(L, N)/G$ be a path such that $\gamma(0)(L)$ and $\gamma(1)(L)$ are disjoint from W (but not necessarily from each other).

The projection map $\text{Emb}(L, N) \rightarrow \text{Emb}(L, N)/G$ is a surjective Serre fibration (by Corollary 4.16) so we may lift γ to $\bar{\gamma}: [0, 1] \rightarrow \text{Emb}(L, N)$. Now $\bar{\gamma}(0)$ is an embedding $L \hookrightarrow N \setminus W$, and by Proposition 5.31 (replacing N by $N \setminus W$ and setting $X = \bar{\gamma}(1)(L)$), there is a path $\delta: [-1, 0] \rightarrow \text{Emb}(L, N \setminus W)$ such that $\delta(0) = \bar{\gamma}(0)$ and $\delta(-1)$ is transverse to $\bar{\gamma}(1)(L)$, which implies (since $2 \dim(L) < \dim(N)$) that $\delta(-1)(L)$ is disjoint from $\bar{\gamma}(1)(L)$.

Write $[\delta]$ for the composition of δ and the projection to $\text{Emb}(L, N)/G$. Concatenating $[\delta]$ and γ we obtain a path in $\text{Emb}(L, N)/G$ whose endpoints $[\delta(-1)]$ and $\gamma(1)$ are (orbits of) embeddings whose images are disjoint from W and from each other. Thus, by our temporary assumption, there exists a path in $\text{Emb}(L, N \setminus W)/G$ between $[\delta(-1)]$ and $\gamma(1)$. Concatenating this path with the reverse of $[\delta]$ we obtain a path in $\text{Emb}(L, N \setminus W)/G$ between $[\delta(0)] = \gamma(0)$ and $\gamma(1)$, as desired.

We may from now on assume that $\gamma(0)(L)$ and $\gamma(1)(L)$ are disjoint.

Step 1. (Extending γ via tubular neighbourhoods.)

As in step 0, since the projection $\text{Emb}(L, N) \rightarrow \text{Emb}(L, N)/G$ is a surjective Serre fibration (by Corollary 4.16), we may lift γ to $\bar{\gamma}: [0, 1] \rightarrow \text{Emb}(L, N)$ such that $\bar{\gamma}(0)(L)$ and $\bar{\gamma}(1)(L)$ are disjoint from W and each other. Denote the normal bundle of $\bar{\gamma}(0): L \hookrightarrow N$ by $V_0 = \nu(\bar{\gamma}(0)) \rightarrow L$ and its zero section by $z_0: L \rightarrow V_0$. Choose a tubular neighbourhood, i.e. an embedding $t_0: V_0 \hookrightarrow N$ such that $t_0 \circ z_0 = \bar{\gamma}(0)$.

Sublemma 5.32 *The normal bundle $V_0 \rightarrow L$ has a trivial one-dimensional subbundle.*

Proof of the sublemma. It suffices to show that the unit sphere subbundle $S(V_0) \rightarrow L$ has a section. The fibres of this bundle are k -spheres, where $k = \dim(N) - \dim(L) - 1$, and the obstruction classes to the existence of such a section live in the cohomology groups $H^i(L; \pi_{i-1}(S^k))$. If $i > \dim(L)$ this clearly vanishes. If $i \leq \dim(L)$, then

$$i - 1 \leq \dim(L) - 1 \leq \dim(N) - \dim(L) - 4 = k - 3,$$

so it also vanishes in this case. (sublemma) \square

The inclusion of a trivial one-dimensional subbundle is an embedding $L \times \mathbb{R} \hookrightarrow V_0$. Let us denote by $\hat{\gamma}_0: L \times \mathbb{R} \hookrightarrow N$ the composition of this embedding and the embedding t_0 . Note that $\hat{\gamma}_0(-, 0) = \bar{\gamma}(0)$. We may now choose disjoint open subsets U_0 and U_1 of N such that

$$\begin{aligned} U_0 &\supseteq \hat{\gamma}_0(L \times \{0\}) = \bar{\gamma}(0)(L) \\ U_1 &\supseteq W \cup \bar{\gamma}(1)(L) \end{aligned}$$

since these are disjoint subsets of N that are compact and closed respectively, and N is regular (since it is a manifold). By compactness of L we may find $\epsilon > 0$ such that $\hat{\gamma}_0(L \times [-\epsilon, \epsilon]) \subseteq U_0$, so in particular $\hat{\gamma}_0(L \times [-\epsilon, \epsilon])$ is disjoint from W and $\bar{\gamma}(1)(L)$.

We may similarly use a tubular neighbourhood of $\bar{\gamma}(1)$ to extend it to an embedding $\hat{\gamma}_1: L \times \mathbb{R} \hookrightarrow N$ with $\hat{\gamma}_1(-, 0) = \bar{\gamma}(1)$. As above, choose disjoint open subsets U'_0 and U'_1 of N such that

$$\begin{aligned} U'_0 &\supseteq \hat{\gamma}_1(L \times \{0\}) = \bar{\gamma}(1)(L) \\ U'_1 &\supseteq W \cup \hat{\gamma}_0(L \times [-\epsilon, \epsilon]). \end{aligned}$$

By compactness of L we may decrease $\epsilon > 0$ if necessary so that $\hat{\gamma}_1(L \times [-\epsilon, \epsilon]) \subseteq U'_0$. Hence:

- The subsets $\hat{\gamma}_0(L \times [-\epsilon, \epsilon])$ and $\hat{\gamma}_1(L \times [-\epsilon, \epsilon])$ of N are disjoint from W and from each other.

Now we use $\hat{\gamma}_0$ and $\hat{\gamma}_1$ to extend $\bar{\gamma}$ to a slightly larger interval. Define $\hat{\gamma}: (-3\epsilon, 1+3\epsilon) \rightarrow \text{Emb}(L, N)$ by:

$$\hat{\gamma}(t)(z) = \begin{cases} \hat{\gamma}_0(z, t + 2\epsilon) & t \in (-3\epsilon, -\epsilon] \\ \hat{\gamma}_0(z, -t) & t \in [-\epsilon, 0] \\ \bar{\gamma}(t)(z) & t \in [0, 1] \\ \hat{\gamma}_1(z, t - 1) & t \in [1, 1 + \epsilon] \\ \hat{\gamma}_1(z, 1 - t + 2\epsilon) & t \in [1 + \epsilon, 1 + 3\epsilon]. \end{cases}$$

This is a continuous path in $\text{Emb}(L, N)$ extending $\bar{\gamma}$ (i.e. $\hat{\gamma}|_{[0,1]} = \bar{\gamma}$) such that

- $\hat{\gamma}(-2\epsilon) = \bar{\gamma}(0)$,
- $\hat{\gamma}(1 + 2\epsilon) = \bar{\gamma}(1)$,
- $\hat{\gamma}(t)(L)$ is disjoint from W for $t \leq 0$ and for $t \geq 1$.

Step 2. (Making the adjoint of $\hat{\gamma}$ into an embedding.)

The adjoint of $\hat{\gamma}$ is a continuous map

$$f_1: L \times (-3\epsilon, 1 + 3\epsilon) \longrightarrow N$$

defined by $f_1(z, t) = \hat{\gamma}(t)(z)$. Let $A_0 = L \times (-3\epsilon, -\epsilon]$ and $A_1 = L \times [1 + \epsilon, 1 + 3\epsilon)$. The restriction of f_1 to A_0 is (up to an affine shift in coordinates) equal to $\hat{\gamma}_0$, so it is an embedding. Similarly, up to an affine shift in coordinates, the restriction of f_1 to A_1 is equal to $\hat{\gamma}_1$, so it is also an embedding. Moreover, the closures of the images of A_0 and A_1 under f_1 are disjoint, so the restriction of f_1 to $A = A_0 \sqcup A_1$ is an embedding. Applying Theorem 5.30 to $\phi = f_1$ (note that the L of the theorem is what we are calling $L \times (-3\epsilon, 1 + 3\epsilon)$ here) we obtain a smooth injective immersion

$$f_2: L \times (-3\epsilon, 1 + 3\epsilon) \longrightarrow N$$

such that $f_2|_A = f_1|_A$. Let

$$f_3: L \times (-2.5\epsilon, 1 + 2.5\epsilon) \longrightarrow N$$

be the restriction of f_2 to the relatively compact subset $L \times (-2.5\epsilon, 1 + 2.5\epsilon)$. Note that

- f_3 is an embedding, since it is the restriction of an injective immersion to a relatively compact subset of the domain,
- $f_3(B_1)$ is disjoint from W ,

where for $r \in (0, 2)$ we write

$$B_r = L \times ((-2.5\epsilon, -r\epsilon) \cup (1 + r\epsilon, 1 + 2.5\epsilon)).$$

Step 3. (Transversality and disjointness from W .)

We may write $W = W_1 \cup \dots \cup W_k$, where each W_i is a properly embedded submanifold of N of dimension at most $\dim(N) - \dim(L) - 2$. We will use Corollary 5.22 to modify f_3 to be disjoint from the W_i one at a time. First, since $f_3(B_1)$ is disjoint from W_1 , we may apply Corollary 5.22 to f_3 and W_1 to obtain an embedding

$$f_4: L \times (-2.5\epsilon, 1 + 2.5\epsilon) \hookrightarrow N \setminus W_1$$

such that f_4 agrees with f_3 on $B_{1.5}$. (We note that, in order to obtain an *embedding*, we chose the \mathcal{U} in Corollary 5.22 to be an open neighbourhood of f_3 consisting of embeddings.) Now, since $f_4(B_{1.5}) = f_3(B_{1.5})$ is disjoint from W_2 , we may apply Corollary 5.22 to f_4 and W_2 to obtain an embedding

$$f_5: L \times (-2.5\epsilon, 1 + 2.5\epsilon) \hookrightarrow N \setminus (W_1 \cup W_2)$$

such that f_5 agrees with f_4 (and therefore also with f_3) on $B_{1.55}$. Iterating this procedure another $k - 2$ times we eventually obtain an embedding

$$f_{k+3}: L \times (-2.5\epsilon, 1 + 2.5\epsilon) \hookrightarrow N \setminus (W_1 \cup \dots \cup W_k) = N \setminus W$$

such that f_{k+3} agrees with f_3 on $B_{1.55\dots 5}$. In particular, it agrees with f_3 , and therefore with f_1 , on $L \times \{-2\epsilon\}$ and $L \times \{1 + 2\epsilon\}$. We may now define

$$\gamma': [-2\epsilon, 1 + 2\epsilon] \longrightarrow \text{Emb}(L, N)$$

by $\gamma'(t)(z) = f_{k+3}(z, t)$ and note that

- $\gamma'(t)(L)$ is disjoint from W for all $t \in [-2\epsilon, 1 + 2\epsilon]$,
- $\gamma'(-2\epsilon) = f_{k+3}(\cdot, -2\epsilon) = f_1(\cdot, -2\epsilon) = \hat{\gamma}(-2\epsilon) = \bar{\gamma}(0)$,
- $\gamma'(1 + 2\epsilon) = f_{k+3}(\cdot, 1 + 2\epsilon) = f_1(\cdot, 1 + 2\epsilon) = \hat{\gamma}(1 + 2\epsilon) = \bar{\gamma}(1)$.

Rescaling the interval $[-2\epsilon, 1 + 2\epsilon]$ to $[0, 1]$ and post-composing with the projection $\text{Emb}(L, N) \rightarrow \text{Emb}(L, N)/G$, we obtain a path γ' as claimed in the lemma. \square

5.7. The weak factorisation condition. We first quickly recap some choices and constructions that we have made so far in the proof.

Recap 5.33 In §5.4 we chose an embedding $\psi_0: P \hookrightarrow M_2$ such that $a_0 = [\psi_0] \in A_0 \subseteq B_0$, and we constructed a diffeomorphism

$$\Psi: M \setminus \psi_0(P) \longrightarrow M \setminus \lambda(T \times \{2\}).$$

In §5.6 we chose an embedding $\tau_0: P \times [0, 2] \hookrightarrow M$ such that $\bar{a} = \tau_0 \in \bar{A}_0 \subseteq \bar{B}_0$. With respect to these choices, there is a composite map

$$Y_{n-1}(\check{M}, \mu) = \bar{q}_0^{-1}(\bar{a}) \hookrightarrow \bar{Y}_0 \longrightarrow \bar{Y} \xrightarrow{\Psi^{-1} \circ -} q_0^{-1}(a_0) \hookrightarrow Y_0 \longrightarrow Y, \quad (5.9)$$

where $Y_0 \rightarrow Y$ and $\bar{Y}_0 \rightarrow \bar{Y}$ are the augmentation maps of the semi-simplicial spaces Y_\bullet and \bar{Y}_\bullet respectively, the two inclusions are the inclusions of fibres for the Serre fibrations $q_0: Y_0 \rightarrow B_0$ and $\bar{q}_0: \bar{Y}_0 \rightarrow \bar{B}_0$ (cf. Lemma 5.9 and Proposition 5.27) and the middle map is a homeomorphism induced by post-composing all embeddings with the inverse of Ψ (cf. Lemma 5.16). Finally, $\bar{q}_0^{-1}(\bar{a})$ was identified in §5.6 with $Y_{n-1}(\check{M}, \mu)$, where $\check{M} = M \setminus (\tau_0(P \times [0, 2]) \cup \lambda(T \times \{2\}))$ and μ is a collar neighbourhood for the boundary of \check{M} , a restriction and rescaling of λ .

Last step of the proof. The last step of the proof of Theorem A is to check the *weak factorisation condition*, i.e. to show that the map (5.9) factors up to homotopy through the map $f: X \rightarrow Y$ that we started with. Let us denote the map (5.9) by

$$\eta: Y_{n-1}(\check{M}, \mu) \longrightarrow Y = Y_n(M, \lambda).$$

We will now construct a map $\zeta: Y_{n-1}(\check{M}, \mu) \rightarrow X = X_n(M, \lambda)$ and a homotopy \mathcal{H} from $f \circ \zeta$ to η . First we describe f and η explicitly. By definition, $f: X_n(M, \lambda) \rightarrow Y_n(M, \lambda)$ acts by

$$\{[\varphi_1], \dots, [\varphi_n]\} \longmapsto \{[\hat{i}(-, 0, 0.5)], [\varphi_1], \dots, [\varphi_n]\}.$$

Combining the two augmentation maps, the diffeomorphism Ψ and the identification $Y_{n-1}(\check{M}, \mu) = \bar{q}_0^{-1}(\bar{a})$, we see that $\eta: Y_{n-1}(\check{M}, \mu) \rightarrow Y_n(M, \lambda)$ acts by

$$\{[\varphi_1], \dots, [\varphi_n]\} \longmapsto \{[\psi_0], [\Psi^{-1} \circ \varphi_1], \dots, [\Psi^{-1} \circ \varphi_n]\}. \quad (5.10)$$

Two paths of embeddings. To construct ζ and \mathcal{H} we will use two paths of embeddings Γ and Δ . First, recall from Remark 5.15 that there is a path

$$\Gamma: [0, 1] \longrightarrow \text{Emb}(M \setminus \lambda(T \times \{2\}), M)$$

such that $\Gamma(0) = \Psi^{-1}$, $\Gamma(1)$ is the inclusion and the restriction of $\Gamma(s)$ to $M \setminus M_{1.5}$ is the identity for all $s \in [0, 1]$. Second, recall that in §5.6 we chose an $\epsilon > 0$ such that

- $\tau_0(z, t) = \hat{i}(z, h_0, t)$ for all $t \in [0, 1 + \epsilon]$ and $z \in P$,
- $\tau_0(P \times (1 + \epsilon, 2])$ is contained in $M_{1+\epsilon}$.

Now choose a path $\delta: [0, 1] \rightarrow \text{Emb}([0, 2], [0, 2])$ such that $\delta(0)$ is the identity, $\delta(1)$ takes $[0, 2]$ to $[1, 2]$ and $\delta(s)|_{[1+\epsilon, 2]} = \text{id}$ for all $s \in [0, 1]$. This determines a path

$$\Delta: [0, 1] \longrightarrow \text{Emb}(M, M)$$

by defining $\Delta(s)|_{M \setminus \lambda(\partial M \times [0, 2])} = \text{id}$ and $\Delta(s)(\lambda(z, t)) = \lambda(z, \delta(s)(t))$ for $(z, t) \in \partial M \times [0, 2]$. Note that $\Delta(s)(\check{M}) \subseteq \check{M}$ for all $s \in [0, 1]$, due to how we chose ϵ and δ above, so this may be regarded as a path

$$\Delta: [0, 1] \longrightarrow \text{Emb}(\check{M}, \check{M})$$

with $\Delta(0) = \text{id}$.

The map ζ . We now define $\zeta: Y_{n-1}(\check{M}, \mu) \rightarrow X_n(M, \lambda)$ to act by

$$\{[\varphi_1], \dots, [\varphi_n]\} \longmapsto \{[\Delta(1) \circ \varphi_1], \dots, [\Delta(1) \circ \varphi_n]\}.$$

This is easily seen to be well-defined and continuous. The map $f \circ \zeta: Y_{n-1}(\check{M}, \mu) \rightarrow Y_n(M, \lambda)$ therefore acts by

$$\{[\varphi_1], \dots, [\varphi_n]\} \longmapsto \{[\hat{\iota}(-, 0, 0.5)], [\Delta(1) \circ \varphi_1], \dots, [\Delta(1) \circ \varphi_n]\}. \quad (5.11)$$

The homotopy \mathcal{H} . We will now construct a homotopy

$$\mathcal{H}: Y_{n-1}(\check{M}, \mu) \times [0, 4] \longrightarrow Y_n(M, \lambda)$$

between $\mathcal{H}(-, 0) = (5.11)$ and $\mathcal{H}(-, 4) = (5.10)$. We first define it explicitly and then explain what we are doing more intuitively. Explicitly, the definition is

$$\mathcal{H}(\{[\varphi_1, \dots, \varphi_n]\}, t) = \begin{cases} \{[\hat{\iota}(-, th_0, 0.5)], [\Delta(1) \circ \varphi_1, \dots, \varphi_n]\} & t \in [0, 1] \\ \{[\tau_0(-, 0.5)], [\Delta(2-t) \circ \varphi_1, \dots, \varphi_n]\} & t \in [1, 2] \\ \{[\tau_0(-, 0.5)], [\Gamma(3-t) \circ \varphi_1, \dots, \varphi_n]\} & t \in [2, 3] \\ \{[\Psi^{-1} \circ \tau_0(-, 1.5t-4)], [\Psi^{-1} \circ \varphi_1, \dots, \varphi_n]\} & t \in [3, 4] \\ \{[\psi_0], [\Psi^{-1} \circ \varphi_1, \dots, \varphi_n]\} & t = 4, \end{cases} \quad (5.12)$$

where the notation $[(wxyz)_{1, \dots, n}]$ is an abbreviation of $[(wxyz)_1], \dots, [(wxyz)_n]$. A more explanatory description is as follows:

- (1) At time $t = 0$ the homotopy $\mathcal{H}(-, 0)$ pushes the configuration $[\varphi_1, \dots, \varphi_n]$ away from the boundary of \check{M} using the self-embedding $\Delta(1)$ (this is ζ) and then adjoins a new embedded copy of P via the embedding $[\hat{\iota}(-, 0, 0.5)]$ (this is f).
- (2) In the interval $t \in [0, 1]$ the location of the new copy of P is modified (by a straight line) from $[\hat{\iota}(-, 0, 0.5)]$ to $[\hat{\iota}(-, h_0, 0.5)] = [\tau_0(-, 0.5)]$. Since the rest of the configuration $[\Delta(1) \circ \varphi_1, \dots, \varphi_n]$ is contained in M_1 , this does not result in any collisions.
- (3) In the interval $t \in [1, 2]$ the new copy of P stays fixed at $[\tau_0(-, 0.5)]$ and the rest of the configuration moves from $[\Delta(1) \circ \varphi_1, \dots, \varphi_n]$ to $[\Delta(0) \circ \varphi_1, \dots, \varphi_n] = [\varphi_1, \dots, \varphi_n]$. This does not result in any collisions with $\tau_0(P \times \{0.5\})$ since the original configuration $[\varphi_1, \dots, \varphi_n]$ is contained in \check{M} , so in particular it is disjoint from

$$\tau_0(P \times [0, 1 + \epsilon]) = \hat{\iota}(P \times \{h_0\} \times [0, 1 + \epsilon]) = \lambda(P_{h_0} \times [0, 1 + \epsilon]), \quad (5.13)$$

where for $r \in (-1, 1)$ we write $P_r = \hat{\iota}(P \times \{r\} \times \{0\}) \subseteq \partial M$, and the self-embeddings $\Delta(s)$ act on the subset (5.13) $\subseteq M$ by ‘‘compressing’’ the second coordinate.

- (4) In the interval $t \in [2, 3]$ the new copy of P remains fixed at $[\tau_0(-, 0.5)]$ and the rest of the configuration moves from $[\varphi_1, \dots, \varphi_n]$ to $[\Psi^{-1} \circ \varphi_1, \dots, \varphi_n]$ via the isotopy of embeddings Γ .
- (5) In the half-open interval $t \in [3, 4)$ the configuration $[\Psi^{-1} \circ \varphi_1, \dots, \varphi_n]$ remains fixed. Note that, since $[\varphi_1, \dots, \varphi_n]$ is disjoint from $\tau_0(P \times [0, 2])$, the configuration $[\Psi^{-1} \circ \varphi_1, \dots, \varphi_n]$ is disjoint from $\Psi^{-1} \circ \tau_0(P \times [0, 2])$. We may therefore move the new copy of P along this embedded copy of $P \times [0, 2]$ from $[\tau_0(-, 0.5)] = [\Psi^{-1} \circ \tau_0(-, 0.5)]$ *almost* to $[\Psi^{-1} \circ \tau_0(-, 2)]$ (but not quite, since Ψ^{-1} is not defined exactly at $\tau_0(P \times \{2\}) \subseteq \lambda(T \times \{2\})$). As t approaches 4 (so $1.5t - 4$ approaches 2), the new copy of P that we have adjoined approaches $\psi_0(P)$. More precisely:
- (6) For $t \in [4 - \epsilon', 4)$, for some $\epsilon' > 0$, the path of embeddings $t \mapsto \Psi^{-1} \circ \tau_0(-, 1.5t - 4)$ is of the form considered in Remark 5.15, and it may therefore be continuously extended to $t = 4$ with the embedding ψ_0 . Hence we may define the homotopy $\mathcal{H}(-, 4)$ to send the configuration $[\varphi_1, \dots, \varphi_n]$ to the configuration $[\Psi^{-1} \circ \varphi_1, \dots, \varphi_n]$ with a new copy of P adjoined via the embedding $[\psi_0]$. This is precisely η .

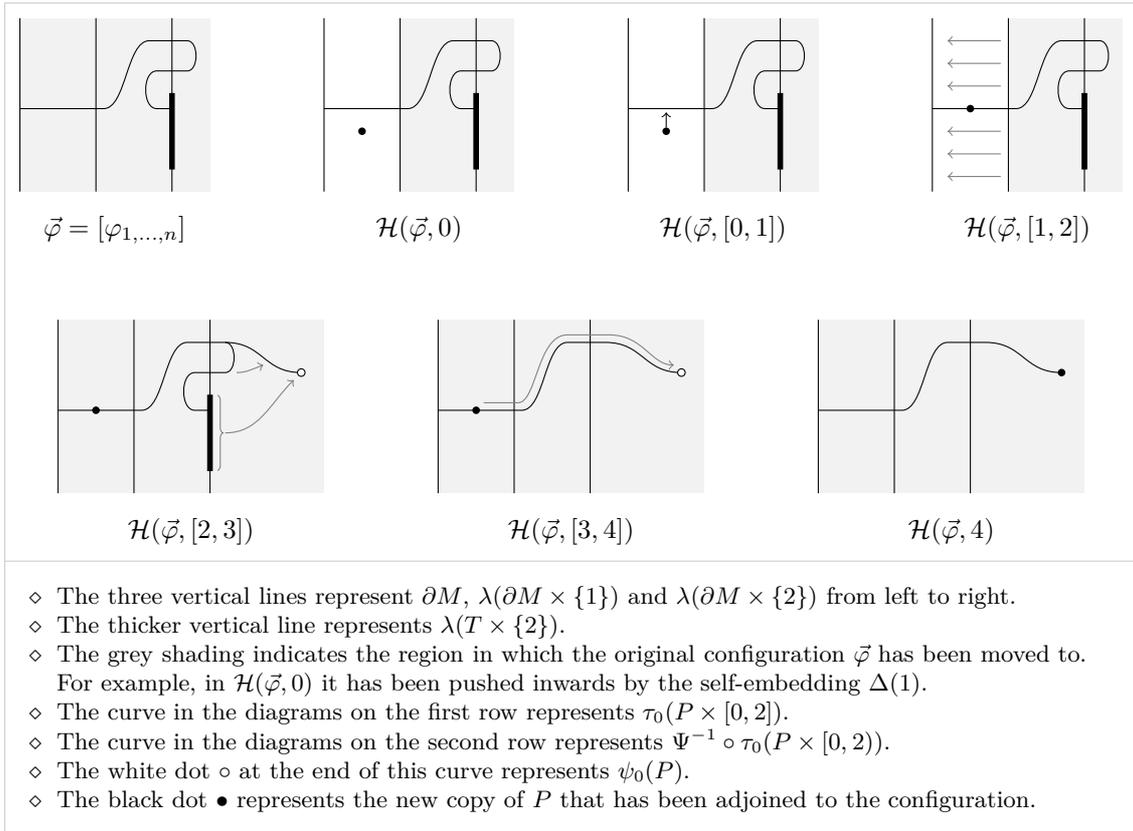
For a picture worth $\frac{10}{3}$ times as much as these approx. 300 words, see Figure 5.1. This homotopy

$$\mathcal{H}: f \circ \zeta \simeq \eta$$

verifies the weak factorisation condition, and therefore completes the proof of Theorem A.

6. Appendix. Homotopy fibres of augmented semi-simplicial spaces

In this appendix, we give a proof of Lemma 5.4, which is restated as Lemma 6.7 below.


 Figure 5.1 The homotopy \mathcal{H} verifying the weak factorisation condition.

6.1. Preliminaries We begin by mentioning an elementary lemma on colimits in topological spaces.

Lemma 6.1 *Let $F, G: I \rightarrow \mathbf{Top}$ be diagrams of topological spaces and $\alpha: F \Rightarrow G$ be a natural transformation with the property that $\alpha_i: F(i) \rightarrow G(i)$ is a closed inclusion for each $i \in I$. Suppose also that for each $i \in I$ the square*

$$\begin{array}{ccc}
 F(i) & \xrightarrow{\mu_i} & \operatorname{colim}(F) \\
 \alpha_i \downarrow & & \downarrow \alpha_* \\
 G(i) & \xrightarrow{\nu_i} & \operatorname{colim}(G)
 \end{array} \tag{6.1}$$

is Cartesian in the category of sets, meaning that the canonical function from $F(i)$ to the pullback (in sets) of the rest of the diagram is a bijection. Then the map

$$\alpha_*: \operatorname{colim}(F) \longrightarrow \operatorname{colim}(G)$$

is also a closed inclusion. The same holds with “closed inclusion” replaced by “open inclusion”.

Remark 6.2 It is sufficient to check that each square (6.1) is Cartesian in the category of sets for each i in a given *cofinal* subcategory J of I , since restricting F and G to J does not change their colimits (see [Stacks, 09WN]).

Proof. It is immediate that α_* is injective, so it remains to show that it is a closed (resp. open) map. We write the proof in the closed case; the open case is identical. Let A be a closed subset of $\operatorname{colim}(F)$. By the definition of the colimit topology, it suffices to show that $\nu_i^{-1}(\alpha_*(A))$ is closed in $G(i)$ for each i . But since the square above is Cartesian in the category of sets, we have $\nu_i^{-1}(\alpha_*(A)) = \alpha_i(\mu_i^{-1}(A))$, which is closed since α_i is a closed map. \square

Definition 6.3 Let Z_\bullet be a semi-simplicial space, and let Y_\bullet be a semi-simplicial subspace. We call Y_\bullet *full* relative to Z_\bullet if each square

$$\begin{array}{ccc} \Delta^n \times Y_n & \longrightarrow & \Delta^n \times Z_n \\ \downarrow & & \downarrow \\ \|Y_\bullet\|^{(n)} & \longrightarrow & \|Z_\bullet\|^{(n)} \end{array} \quad (6.2)$$

is *Cartesian* in the category of sets, meaning that the canonical function from $\Delta^n \times Y_n$ to the pullback (in sets) of the rest of the diagram is a bijection. Another way of stating this is that a simplex $\sigma \in Z_n$ is contained in Y_n whenever at least one of its vertices is contained in Y_0 . Another equivalent characterisation is that the subspace $\|Y_\bullet^\delta\|$ of $\|Z_\bullet^\delta\|$ is a union of path-components, where Y_n^δ denotes Y_n given the discrete topology and similarly for Z_n^δ .

Example 6.4 Let Z_\bullet be an *augmented* semi-simplicial space, choose a subset $A \subseteq Z_{-1}$ and define $Y_n = f_n^{-1}(A)$ where $f_n: Z_n \rightarrow Z_{-1}$ is the unique composition of face maps. Then Y_\bullet is a full semi-simplicial subspace of Z_\bullet , which can be seen as follows. Suppose σ is a simplex in Z_n and one of its vertices is in Y_0 , in other words $d^n(\sigma) \in Y_0$, where d^n is one of the possible compositions of face maps $Z_n \rightarrow Z_0$. Then we have $f_n(\sigma) = f_0(d^n(\sigma)) \in A$ and so $\sigma \in Y_n$.

The relevance of this definition is the following lemma.

Lemma 6.5 *Let Z_\bullet be a semi-simplicial space and Y_\bullet be a full semi-simplicial subspace. If each inclusion $Y_n \hookrightarrow Z_n$ is a closed inclusion then the map of geometric realisations*

$$\|Y_\bullet\| \longrightarrow \|Z_\bullet\| \quad (6.3)$$

is also a closed inclusion. Similarly when “closed inclusion” is replaced by “open inclusion”.

Proof. The proof is identical for the “open” statement and the “closed” statement, so we will just prove the “closed” statement. We will first prove by induction that the map of skeleta

$$\|Y_\bullet\|^{(n)} \longrightarrow \|Z_\bullet\|^{(n)} \quad (6.4)$$

is a closed inclusion for all n . The case $n = 0$ is part of the assumption, so we let $n \geq 1$ and assume the result for $n - 1$ by inductive hypothesis. The map (6.4) is the map of pushouts induced by the following diagram:

$$\begin{array}{ccccc} \Delta^n \times Y_n & \longleftarrow & \partial\Delta^n \times Y_n & \longrightarrow & \|Y_\bullet\|^{(n-1)} \\ \downarrow & & \downarrow & & \downarrow \\ \Delta^n \times Z_n & \longleftarrow & \partial\Delta^n \times Z_n & \longrightarrow & \|Z_\bullet\|^{(n-1)} \end{array} \quad (6.5)$$

in which the vertical maps are closed inclusions by assumption and inductive hypothesis. To apply Lemma 6.1 we need to check that three squares of the form (6.1) are Cartesian in the category of sets. The square corresponding to the left-hand side of (6.5) is precisely (6.2), and therefore Cartesian in the category of sets by assumption. The square corresponding to the middle of (6.5) therefore also has this property, since the left-hand square of (6.5) is Cartesian (in spaces, not just in sets, although this is not relevant here). The square corresponding to the right-hand side of (6.5) is

$$\begin{array}{ccc} \|Y_\bullet\|^{(n-1)} & \longrightarrow & \|Z_\bullet\|^{(n-1)} \\ \downarrow & & \downarrow \\ \|Y_\bullet\|^{(n)} & \longrightarrow & \|Z_\bullet\|^{(n)} \end{array} \quad (6.6)$$

which is also Cartesian in the category of sets.¹⁸ Lemma 6.1 then implies that (6.4) is a closed inclusion.

Finally, we show that (6.3) is a closed inclusion. By the same reasoning as above, the square

$$\begin{array}{ccc} \|Y_\bullet\|^{(n)} & \longrightarrow & \|Z_\bullet\|^{(n)} \\ \downarrow & & \downarrow \\ \|Y_\bullet\| & \longrightarrow & \|Z_\bullet\| \end{array} \quad (6.7)$$

is Cartesian in the category of sets for all n . We already know that (6.4) is a closed inclusion for each n , so Lemma 6.1 implies that (6.3) is a closed inclusion. \square

6.2. Computing homotopy fibres levelwise

Convention 6.6 For a map $g: Y \rightarrow Z$ and point $z \in Z$, we take the following explicit model for the homotopy fibre $\text{hofib}_z(g)$: denote the mapping space $\text{Map}([0, 1], \{0\}; Z, \{z\})$ by $P_z Z$ and let $\text{hofib}_z(g)$ be the pullback of g and the evaluation map $\text{ev}_1: P_z Z \rightarrow Z$.

Let X_\bullet be an augmented semi-simplicial space and write $f_n: X_n \rightarrow X := X_{-1}$ for the unique composition of face maps. Note that, for any point $x \in X$, the homotopy fibres $\{\text{hofib}_x(f_n)\}_{n \geq 0}$ naturally inherit face maps from X_\bullet and so form a semi-simplicial space $\text{hofib}_x(f_\bullet)$.

The following lemma appeared as Lemma 2.1 in the third arXiv version of [Ran16] (but not in the final, published version) and is also very similar to Lemma 2.14 of [ER17] (they assume that the maps f_n are all quasifibrations). We give a complete proof in this appendix, which is self-contained apart from an appeal to one theorem of Dold and Thom (Theorem 6.8 below).

Lemma 6.7 *The sequence $\|\text{hofib}_x(f_\bullet)\| \rightarrow \|X_\bullet\| \rightarrow X$ is a homotopy fibre sequence over x .*

A sequence $A \rightarrow B \rightarrow C$ is a *homotopy fibre sequence over $c \in C$* if the square

$$\begin{array}{ccc} A & \longrightarrow & B \\ \downarrow & & \downarrow \\ \{c\} & \longrightarrow & C \end{array}$$

is homotopy Cartesian, meaning that there exists a homotopy filling the square, and the canonical map (induced by this homotopy) from A to the homotopy pullback of the rest of the diagram is a weak equivalence. This property is invariant under objectwise weak equivalence of diagrams (which will be used in the proof of the lemma, cf. diagram (6.9) below). The lemma therefore equivalently states that the canonical map

$$\|\text{hofib}_x(f_\bullet)\| \longrightarrow \text{hofib}_x(\|X_\bullet\| \rightarrow X) \quad (6.8)$$

is a weak equivalence.

Before proving this, we recall that a *quasifibration*, introduced in [DT58], is a map $f: X \rightarrow Y$ with the property that for each $y \in Y$ the natural map $f^{-1}(y) \rightarrow \text{hofib}_y(f)$ is a weak equivalence. Quasifibrations are not closed under taking pullbacks,¹⁹ but they do satisfy a useful local-to-global result, proved in [DT58] (see also [Str11, Theorem 15.84]).

¹⁸ To see this, consider everything as subsets of the set $\|Z_\bullet\|$. There is a surjection

$$k: \bigsqcup_m (\Delta^m \times Z_m) \longrightarrow \|Z_\bullet\|$$

and we need to show that the intersection of the subsets $k(\Delta^n \times Y_n)$ and $k(\Delta^{n-1} \times Z_{n-1})$ is precisely $k(\Delta^{n-1} \times Y_{n-1})$. Clearly this is contained in the intersection. To show the converse, consider $(t, y) \in \Delta^n \times Y_n$ and $(s, z) \in \Delta^{n-1} \times Z_{n-1}$ such that $k(t, y) = k(s, z)$. The equivalence relation defining k glues each face of an n -simplex to exactly one $(n-1)$ -simplex, so we must have that $z = d_i(y)$ for some face map d_i . Hence $z \in Y_{n-1}$ and so $k(s, z) \in k(\Delta^{n-1} \times Y_{n-1})$.

¹⁹ See Bemerkung 2.3 of [DT58].

Theorem 6.8 ([DT58, Satz 2.2]) *Let $f: X \rightarrow Y$ be a surjective map and \mathcal{U} a basis for the topology of Y . If the restriction $f^{-1}(U) \rightarrow U$ is a quasifibration for all $U \in \mathcal{U}$, then f is a quasifibration.*

Proof of Lemma 6.7. For each $n \geq 0$ define $Y_n := X^{[0,1]} \times_X X_n$, so the map f_n factors as a weak equivalence followed by a Serre fibration $X_n \rightarrow Y_n \rightarrow X$. Denote the second map by g_n . The spaces $\{Y_n\}_{n \geq 0}$ inherit face maps from X_\bullet and form an augmented semi-simplicial space $Y_\bullet \rightarrow X$ whose composition of face maps $Y_n \rightarrow X$ is g_n . Now choose a CW-approximation $w: Z \rightarrow X$ for X , and write $Z_\bullet \rightarrow Z$ for the levelwise pullback of Y_\bullet along w . Note that, since w is a weak equivalence and each $g_n: Y_n \rightarrow X$ is a Serre fibration, the map of augmented semi-simplicial spaces $Z_\bullet \rightarrow Y_\bullet$ over w is a levelwise weak equivalence and the compositions of face maps $h_n: Z_n \rightarrow Z$ are Serre fibrations. Choose a point $z \in Z$ and a path in X from $w(z)$ to x . This path induces homotopy equivalences $\text{hofib}_{w(z)}(f_n) \simeq \text{hofib}_x(f_n)$. Summarising, we have the following commutative diagram, where \sim_ℓ denotes a levelwise weak equivalence:

$$\begin{array}{ccccccc}
 \text{hofib}_x(f_\bullet) & \xrightarrow{\sim_\ell} & \text{hofib}_{w(z)}(f_\bullet) & \xrightarrow{\sim_\ell} & \text{hofib}_{w(z)}(g_\bullet) & \xleftarrow{\sim_\ell} & \text{hofib}_z(h_\bullet) \\
 & \searrow & \downarrow & & \downarrow & & \downarrow \\
 & & X_\bullet & \xrightarrow{\sim_\ell} & Y_\bullet & \xleftarrow{\sim_\ell} & Z_\bullet \\
 & & & & \downarrow & & \downarrow \\
 & & & & X & \xleftarrow[w]{\sim} & Z
 \end{array} \tag{6.9}$$

In the induced diagram after taking (thick) geometric realisations, all horizontal maps are weak equivalences. Hence it suffices to prove that the sequence $\|\text{hofib}_z(h_\bullet)\| \rightarrow \|Z_\bullet\| \rightarrow Z$ is a homotopy fibre sequence for any $z \in Z$. In other words, we would like to show that the map t in the square

$$\begin{array}{ccc}
 \|\text{hofib}_z(h_\bullet)\| & \xrightarrow{t} & \text{hofib}_z(h) \\
 \ell \uparrow & & \uparrow r \\
 \|\text{fib}_z(h_\bullet)\| & \xrightarrow{b} & \text{fib}_z(h)
 \end{array} \tag{6.10}$$

is a weak equivalence, where h denotes the induced map $\|Z_\bullet\| \rightarrow Z$. Since each h_n is a Serre fibration, the map ℓ in (6.10) is a weak equivalence. It is easy to see that the map b is a continuous bijection (in fact the same is true for t , although we will not use this). To see that it is in fact a homeomorphism, consider the triangle

$$\begin{array}{ccccc}
 \|\text{fib}_z(h_\bullet)\| & \xrightarrow{b} & \text{fib}_z(h) & \xrightarrow{i} & \|Z_\bullet\| \\
 & & \searrow & \nearrow & \\
 & & & & \|i_\bullet\|
 \end{array} \tag{6.11}$$

where $i_n: \text{fib}_z(h_n) \hookrightarrow Z_n$ and $i: \text{fib}_z(h) \hookrightarrow \|Z_\bullet\|$ are the inclusions. The map $\|i_\bullet\|$ is injective, and b will be a homeomorphism if and only if $\|i_\bullet\|$ is an inclusion, i.e. a topological embedding. By Lemma 6.5 (and Example 6.4), the map $\|i_\bullet\|$ will be a closed inclusion as long as each i_n is a closed inclusion. So we need to show that $\text{fib}_z(h_n) = h_n^{-1}(z)$ is a closed subset of Z_n . But Z is a CW-complex, so in particular its points are closed, so $\{z\}$ is closed in Z and so $h_n^{-1}(z)$ is closed in Z_n by continuity of h_n . Hence the map b in (6.10) is a homeomorphism.

It remains to show that the map r in (6.10) is a weak equivalence for each $z \in Z$; in other words, we need to show that the map $h: \|Z_\bullet\| \rightarrow Z$ is a quasifibration. We will do this using Theorem 6.8. Since Z is a CW-complex, it is locally contractible, so we may take \mathcal{U} to be a basis for its topology consisting of contractible subsets.

To apply Theorem 6.8, we need to know that h is surjective, which will be true if and only if $h_0: Z_0 \rightarrow Z$ is surjective. But we may assume without loss of generality that $f_0: X_0 \rightarrow X$ is

π_0 -surjective.²⁰ By construction, this is equivalent to surjectivity of the map $g_0: Y_0 \rightarrow X$. Now h_0 is the pullback of g_0 along w , and is therefore also surjective.

Let $U \in \mathcal{U}$. We need to show that the restriction $h|_U: h^{-1}(U) \rightarrow U$ is a quasifibration. Let $z \in U$. Since each $h_n: Z_n \rightarrow Z$ is a Serre fibration, so is its restriction $h_n|_U: h_n^{-1}(U) \rightarrow U$. Hence we have weak equivalences

$$h_n^{-1}(z) \xrightarrow{\sim} \text{hofib}_z(h_n|_U) \xrightarrow{\sim} h_n^{-1}(U),$$

where the second weak equivalence is due to the fact that U is contractible. We therefore have a levelwise weak equivalence $h_{\bullet}^{-1}(z) \rightarrow h_{\bullet}^{-1}(U)$, and hence a weak equivalence on thick geometric realisations $\|h_{\bullet}^{-1}(z)\| \rightarrow \|h_{\bullet}^{-1}(U)\|$. But this is the inclusion $h^{-1}(z) \rightarrow h^{-1}(U)$, so the composition of the maps

$$h^{-1}(z) \longrightarrow \text{hofib}_z(h|_U) \longrightarrow h^{-1}(U)$$

is a weak equivalence. The right-hand map is a weak equivalence since U is contractible, so by 2-out-of-3, the left-hand map is also a weak equivalence. Since $z \in U$ was arbitrary, we have shown that $h|_U$ is a quasifibration.

Theorem 6.8 now tells us that h is a quasifibration, and so the map r in (6.10) is a weak equivalence. We showed above that ℓ is a weak equivalence and b is a homeomorphism, so the map t is also a weak equivalence. Thus the sequence $\|\text{hofib}_z(h_{\bullet})\| \rightarrow \|Z_{\bullet}\| \rightarrow Z$ is a homotopy fibre sequence for any $z \in Z$. By diagram (6.9) this implies that $\|\text{hofib}_x(f_{\bullet})\| \rightarrow \|X_{\bullet}\| \rightarrow X$ is a homotopy fibre sequence for any $x \in X$, as required. \square

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²⁰ Suppose that Lemma 6.7 holds with this assumption and let X_{\bullet} be any augmented semi-simplicial space with basepoint $x \in X = X_{-1}$. Define X' to be the smallest union of path-components of X containing the image of $\|X_{\bullet}\|$ (which is the same as the image of X_0) and define $X'_n = X_n$ for $n \geq 0$. If $x \notin X'$ then the lemma is vacuously true (since both $\text{hofib}_x(\|X_{\bullet}\| \rightarrow X)$ and $\|\text{hofib}_x(f_{\bullet})\|$ are empty). Otherwise, applying the lemma to X'_{\bullet} we see that $\|\text{hofib}_x(f_{\bullet})\| \rightarrow \|X_{\bullet}\| \rightarrow X'$ is a homotopy fibre sequence over x . Adding disjoint path-components to the third space in a homotopy fibre sequence does not affect the property of being a homotopy fibre sequence, so $\|\text{hofib}_x(f_{\bullet})\| \rightarrow \|X_{\bullet}\| \rightarrow X$ is also a homotopy fibre sequence over x .

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